
CS380: Computer Graphics

Ray Tracing

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Course URL:
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KAIST



Class Objectives

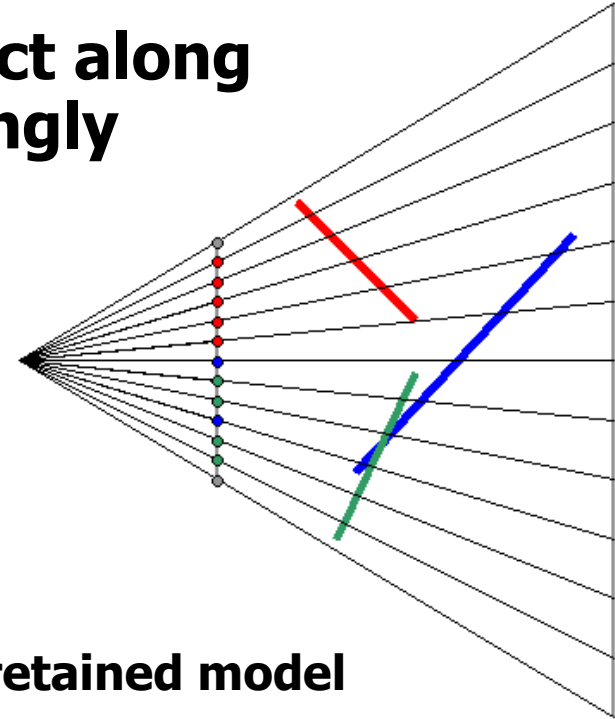
- **Understand overall algorithm of recursive ray tracing**
 - **Ray generations**
 - **Intersection tests and acceleration methods**
 - **Basic sampling methods**
- **Related chapter**
 - **Part II, Ray Tracing**

Various Visibility Algorithm

- **Scan-line algorithm; briefly touched before**
- **Z-buffer**
- **Ray casting, etc.**

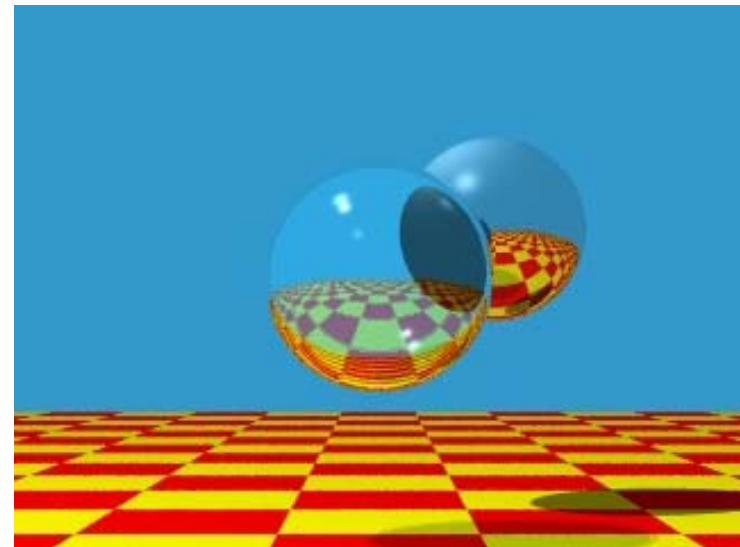
Ray Casting

- For each pixel, find closest object along the ray and shade pixel accordingly
- Advantages
 - Conceptually simple
 - Can be extended to handle global illumination effects
- Disadvantages
 - Renderer must have access to entire retained model
 - Hard to map to special-purpose hardware
 - Less efficient than rasterization in terms of utilizing spatial coherence



Recursive Ray Casting

- Ray casting generally dismissed early on because of aforementioned problems
- Gained popularity in when Turner Whitted (1980) showed this image
 - *Show recursive* ray casting could be used for global illumination effects

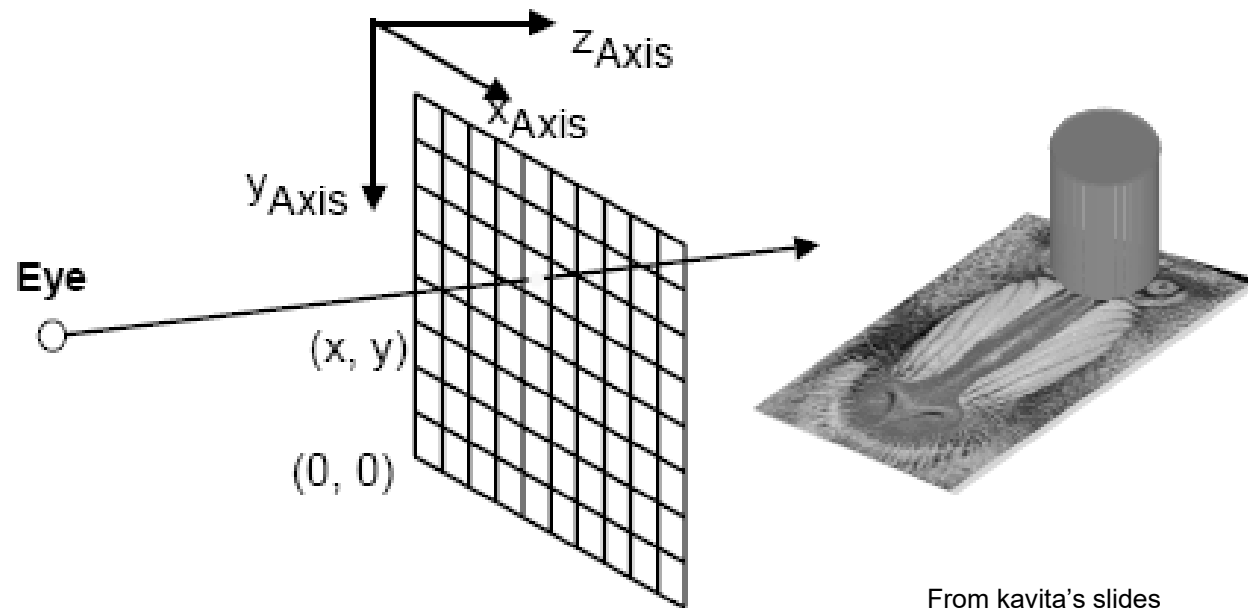


Ray Casting and Ray Tracing

- **Trace rays from eye into scene**
 - **Backward ray tracing**
- **Ray casting used to compute visibility at the eye**
- **Perform ray tracing for arbitrary rays needed for shading**
 - **Reflections**
 - **Refraction and transparency**
 - **Shadows**

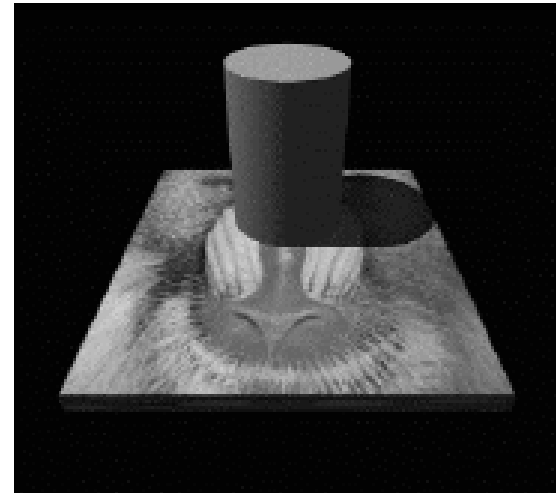
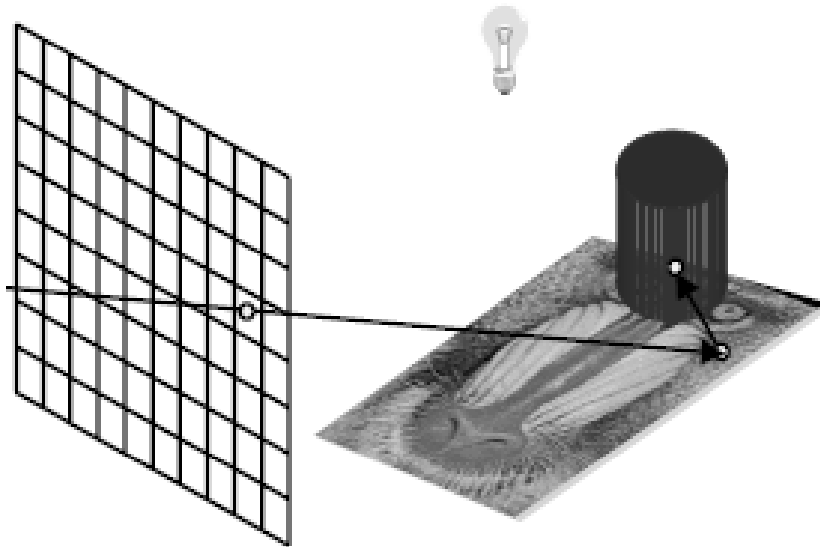
Basic Algorithms of Ray Tracing

- Rays are cast from the eye point through each pixel in the image



Shadows

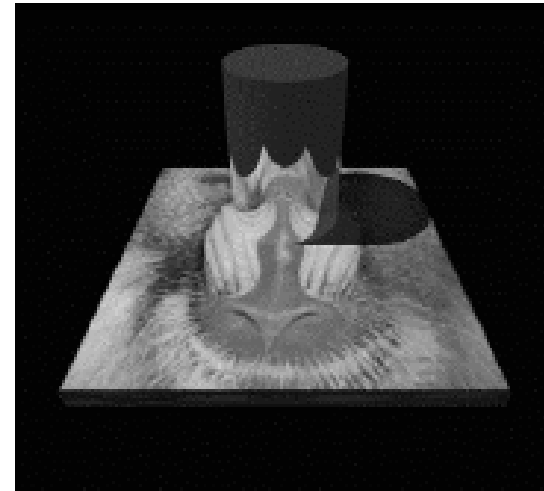
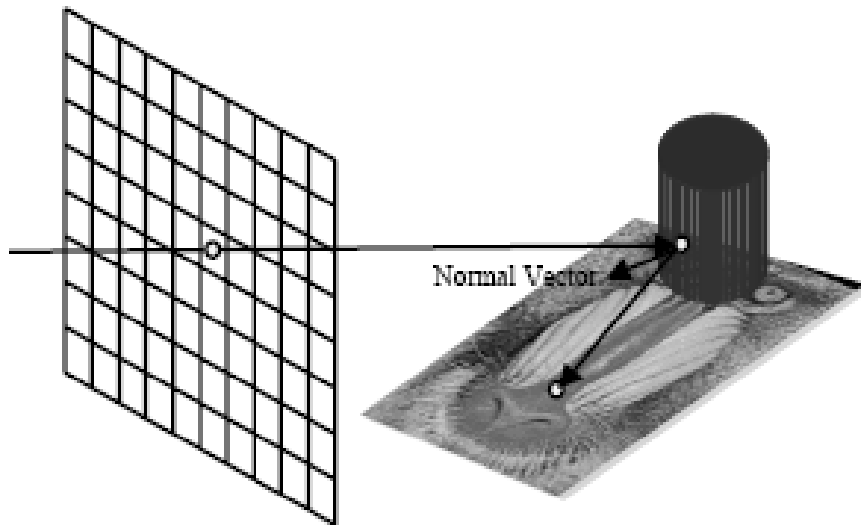
- **Cast ray from the intersection point to each light source**
 - **Shadow rays**



From kavita's slides

Reflections

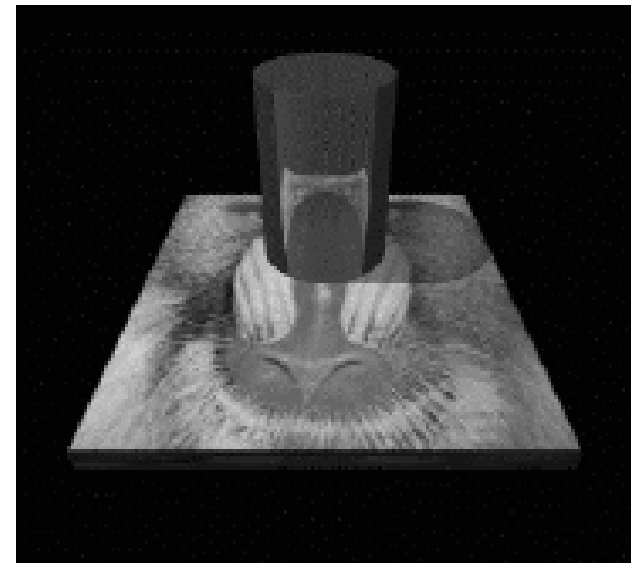
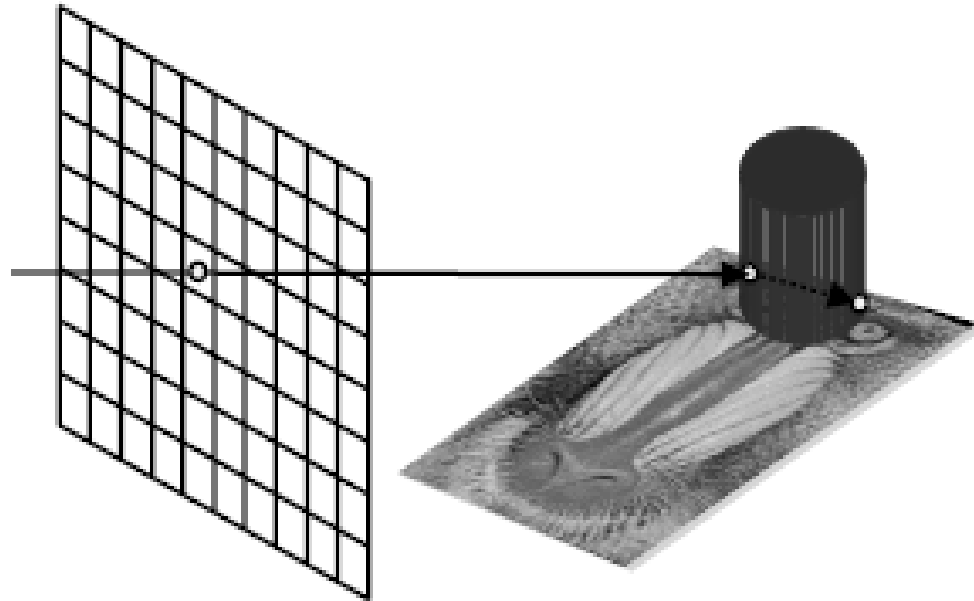
- **If object specular, cast secondary reflected rays**



From kavita's slides

Refractions

- **If object transparent, cast secondary refracted rays**



From kavita's slides

An Improved Illumination Model [Whitted 80]

- **Phong model**

$$I_r = \sum_{j=1}^{\text{numLights}} (k_a^j I_a^j + k_d^j I_d^j (\hat{N} \cdot \hat{L}_j) + k_s^j I_s^j (\hat{V} \cdot \hat{R})^{n_s})$$

- **Whitted model**

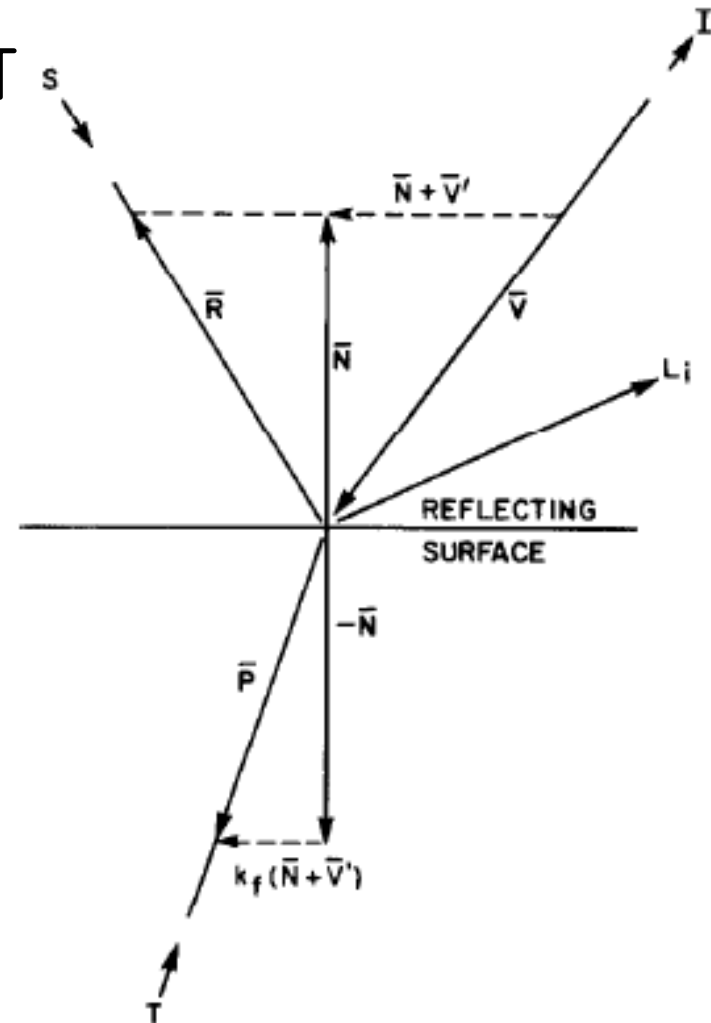
$$I_r = \sum_{j=1}^{\text{num_Visible_Lights}} (k_a^j I_a^j + k_d^j I_d^j (\hat{N} \cdot \hat{L}_j)) + k_s S + k_t T$$

- **S and T are intensity of light from reflection and transmission rays**
- **Ks and Kt are specular and transmission coefficient**

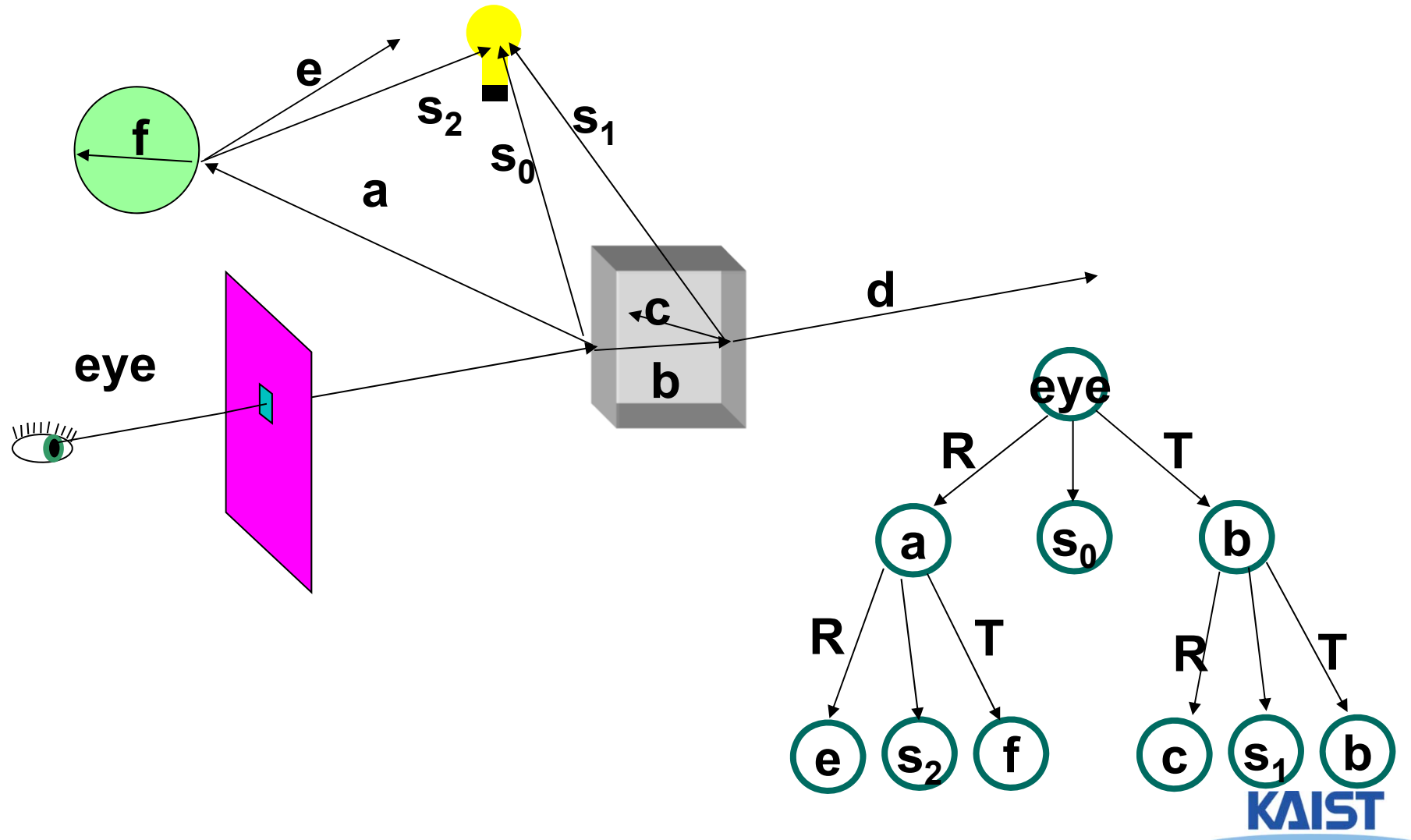
An Improved Illumination Model [Whitted 80]

$$I_r = \sum_{j=1}^{\text{numLights}} (k_a^j I_a^j + k_d^j I_d^j (\hat{N} \cdot \hat{L}_j)) + k_s S + k_t T$$

Computing reflection and transmitted/refracted rays is based on Snell's law



Ray Tree



Overall Algorithm of Ray Tracing

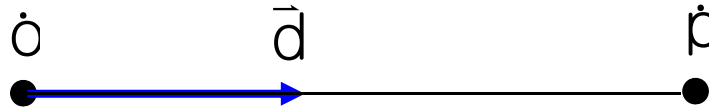
- Per each pixel, compute a ray, R

Def function RayTracing (R)

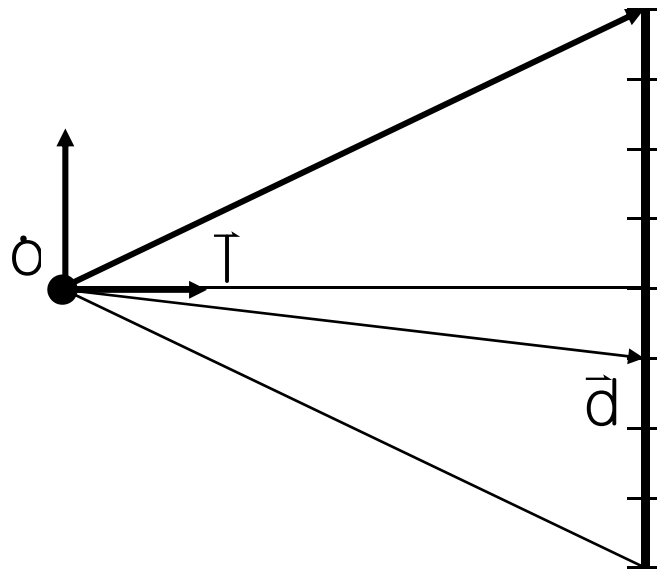
- Compute an intersection against objects
- If no hit,
 - Return the background color
- Otherwise,
 - Compute shading, c
 - General secondary ray, R'
 - Perform $c' = \text{RayTracing}(R')$
 - Return $c+c'$

Ray Representation

- **We need to compute the first surface hit along a ray**
 - **Represent ray with origin and direction**
 - **Compute intersections of objects with ray**
 - **Return the closest object**

$$p(t) = o + t\vec{d}$$


Generating Primary Rays

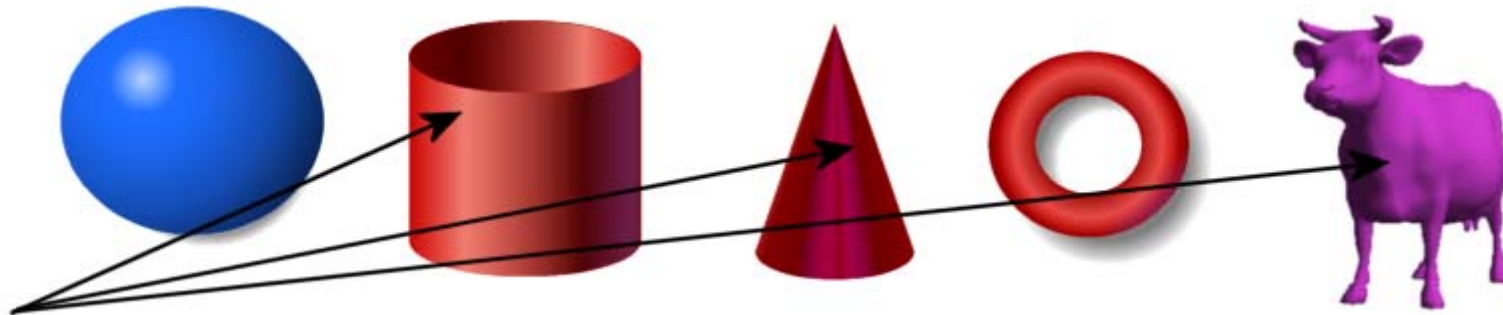


Generating Secondary Rays

- **The origin is the intersection point p_0**
- **Direction depends on the type of ray**
 - **Shadow rays – use direction to the light source**
 - **Reflection rays – use incoming direction and normal to compute reflection direction**
 - **Transparency/refraction – use snell's law**

Intersection Tests

Go through all of the objects in the scene to determine the one closest to the origin of



Strategy: Solve of the intersection of the Ray with a mathematical description of the object

Simple Strategy

- **Parametric ray equation**

- Gives all points along the ray as a function of the parameter

$$\vec{p}(t) = \vec{o} + t \vec{d}$$

- **Implicit surface equation**

- Describes all points on the surface as the zero set of a function

$$f(\vec{p}) = 0$$

- **Substitute ray equation into surface function and solve for t**

$$f(\vec{o} + t \vec{d}) = 0$$

Ray-Plane Intersection

- **Implicit equation of a plane:**

$$\vec{n} \cdot \vec{p} - d = 0$$

- **Substitute ray equation:**

$$\vec{n} \cdot (\vec{o} + t \vec{d}) - d = 0$$

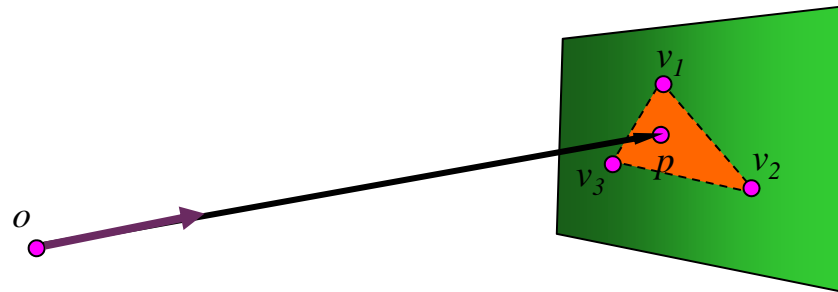
- **Solve for t:**

$$t (\vec{n} \cdot \vec{d}) = d - \vec{n} \cdot \vec{o}$$

$$t = \frac{d - \vec{n} \cdot \vec{o}}{\vec{n} \cdot \vec{d}}$$

Generalizing to Triangles

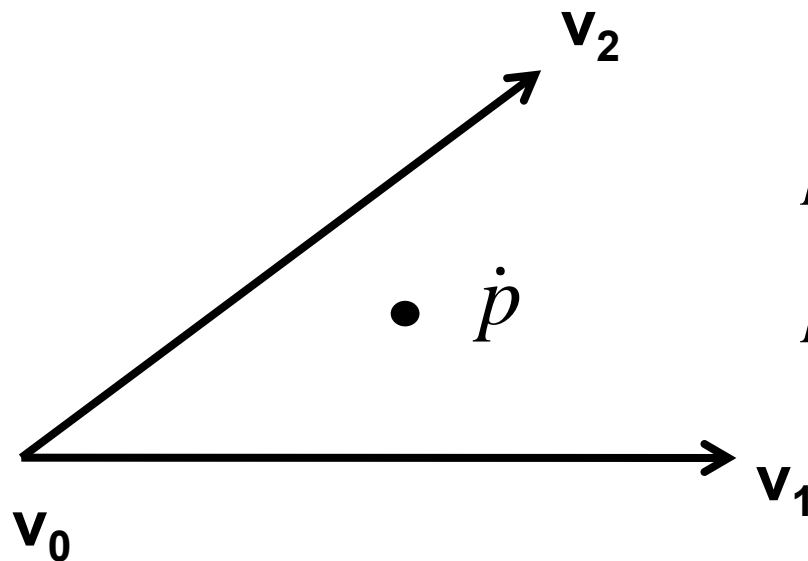
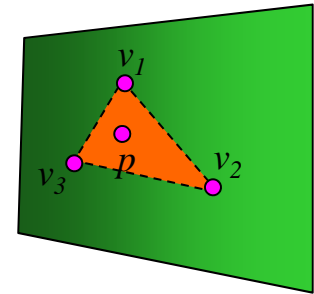
- Find of the point of intersection on the plane containing the triangle
- Determine if the point is inside the triangle
 - Barycentric coordinate method
 - Many other methods



Barycentric Coordinates

- Points in a triangle have positive barycentric coordinates:

$$\dot{p} = \alpha \dot{v}_0 + \beta \dot{v}_1 + \gamma \dot{v}_2 \quad , \text{where } \alpha + \beta + \gamma = 1$$



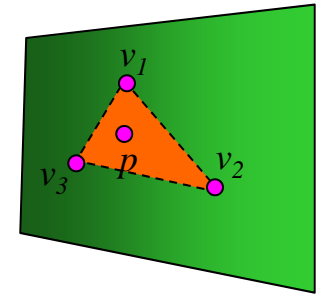
$$\dot{p} = \dot{v}_0 + \beta(\dot{v}_1 - \dot{v}_0) + \gamma(\dot{v}_2 - \dot{v}_0)$$

$$\dot{p} = (1 - \beta - \gamma)\dot{v}_0 + \beta\dot{v}_1 + \gamma\dot{v}_2$$

Barycentric Coordinates

- **Points in a triangle have positive barycentric coordinates:**

$$\dot{p} = \alpha \dot{v}_0 + \beta \dot{v}_1 + \gamma \dot{v}_2 \quad , \text{where } \alpha + \beta + \gamma = 1$$

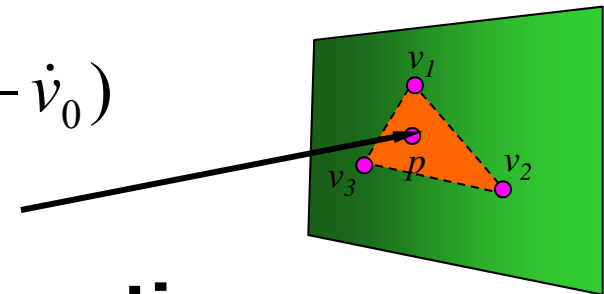


- **Benefits:**
 - **Barycentric coordinates can be used for interpolating vertex parameters (e.g., normals, colors, texture coordinates, etc)**

Ray-Triangle Intersection

- **A point in a ray intersects with a triangle**

$$\dot{p}(t) = \dot{v}_0 + \beta(\dot{v}_1 - \dot{v}_0) + \gamma(\dot{v}_2 - \dot{v}_0)$$

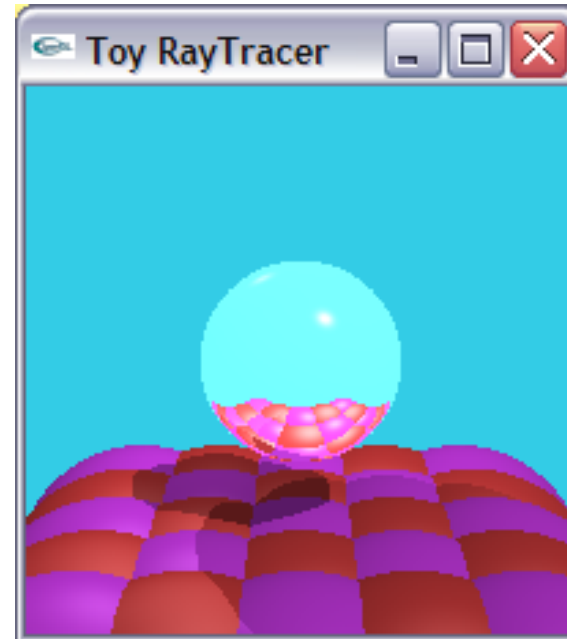


- **Three unknowns, but three equations**
- **Compute the point based on t**
- **Then, check whether the point is on the triangle**

Pros and Cons of Ray Tracing

Advantages of Ray Tracing:

- Very simple design
- Improved realism over the graphics pipeline

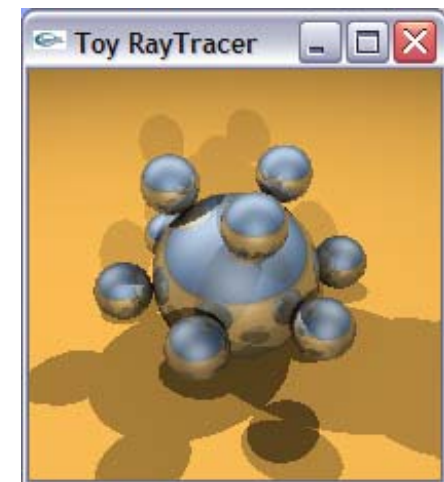


Disadvantages:

- Very slow per pixel calculations
- Only approximates full global illumination
- Hard to accelerate with special-purpose H/W

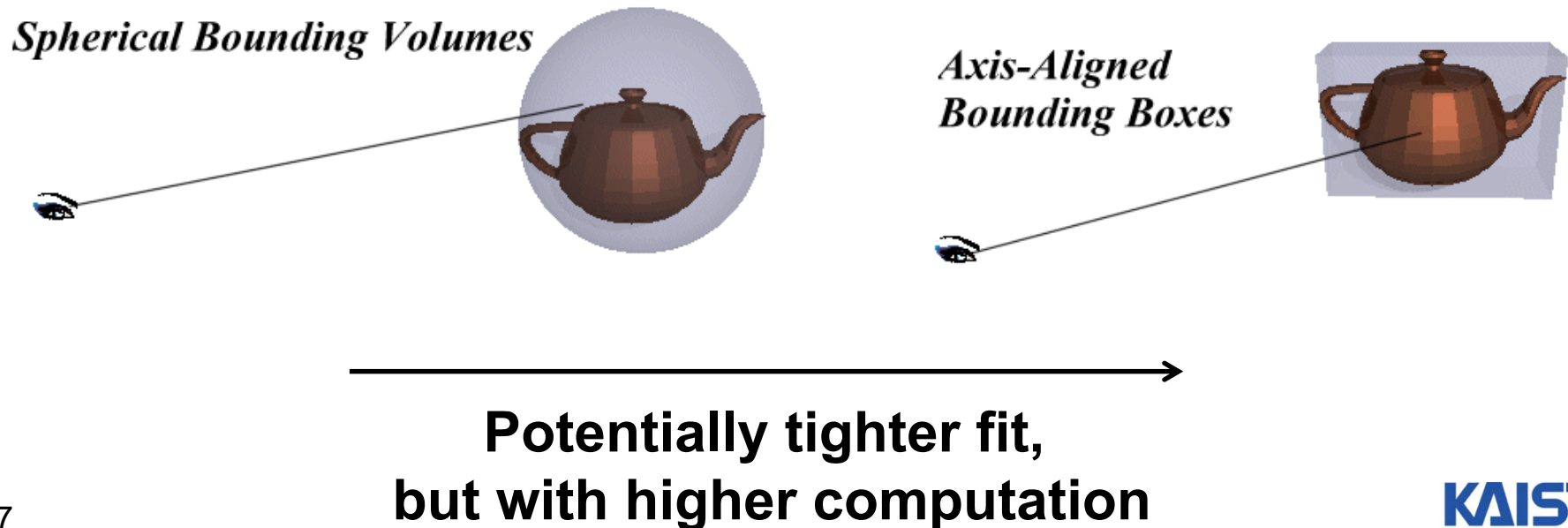
Acceleration Methods

- **Rendering time for a ray tracer depends on the number of ray intersection tests per pixel**
 - The number of pixels X the number of primitives in the scene
- **Early efforts focused on accelerating the ray-object intersection tests**
- **More advanced methods required to make ray tracing practical**
 - **Bounding volume hierarchies**
 - **Spatial subdivision**



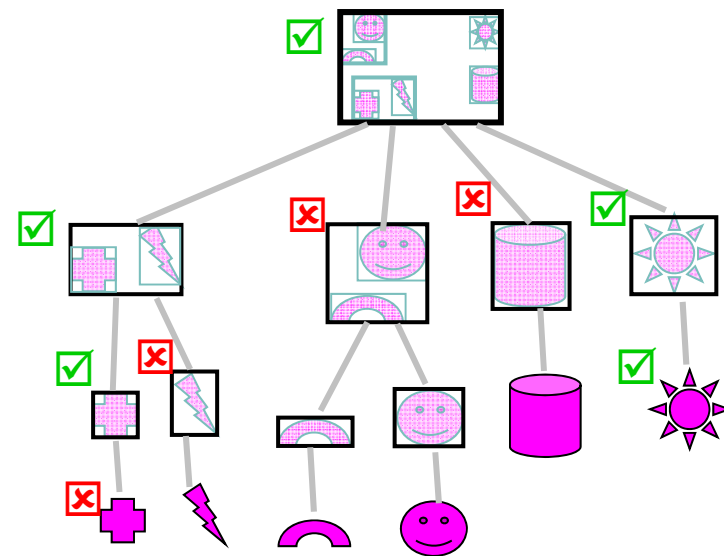
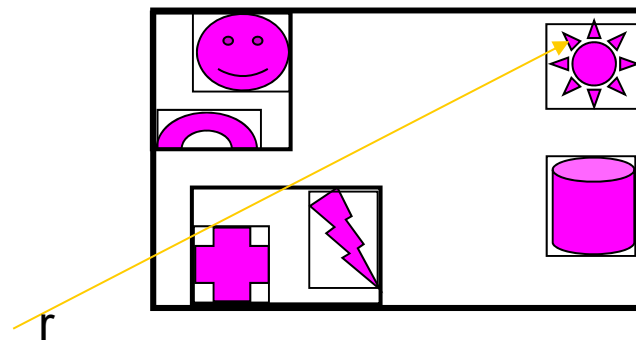
Bounding Volumes

- **Enclose complex objects within a simple-to-intersect objects**
 - If the ray does not intersect the simple object then its contents can be ignored
 - The likelihood that it will strike the object depends on how tightly the volume surrounds the object.



Hierarchical Bounding Volumes

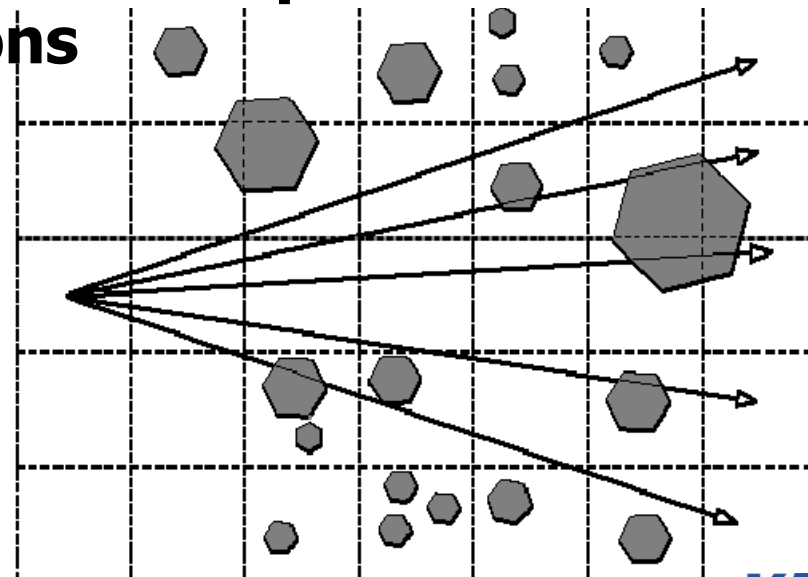
- Organize bounding volumes as a tree
- Each ray starts with the root BV of the tree and traverses down through the tree



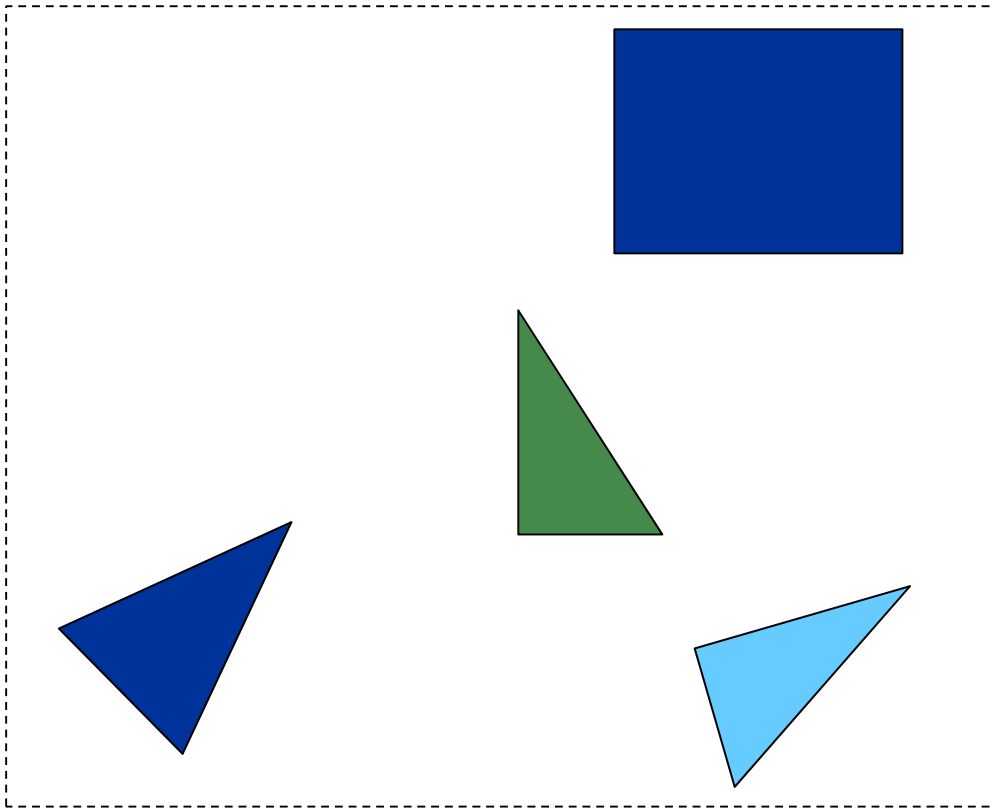
Spatial Subdivision

Idea: Divide space in to subregions

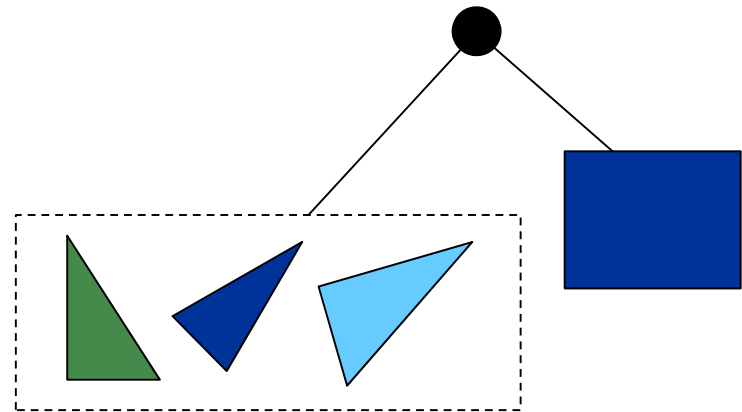
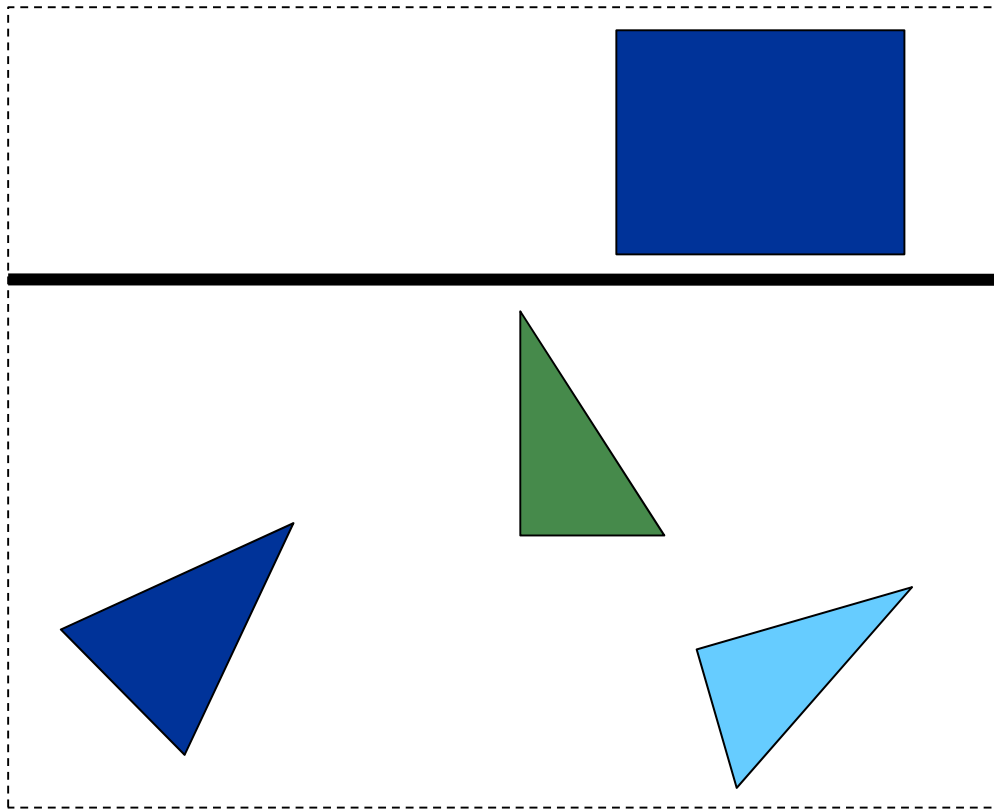
- **Place objects within a subregion into a list**
- **Only traverse the lists of subregions that the ray passes through**
- **“Mailboxing” used to avoid multiple test with objects in multiple regions**
- **Many types**
 - Regular grid
 - Octree
 - BSP tree
 - kd-tree



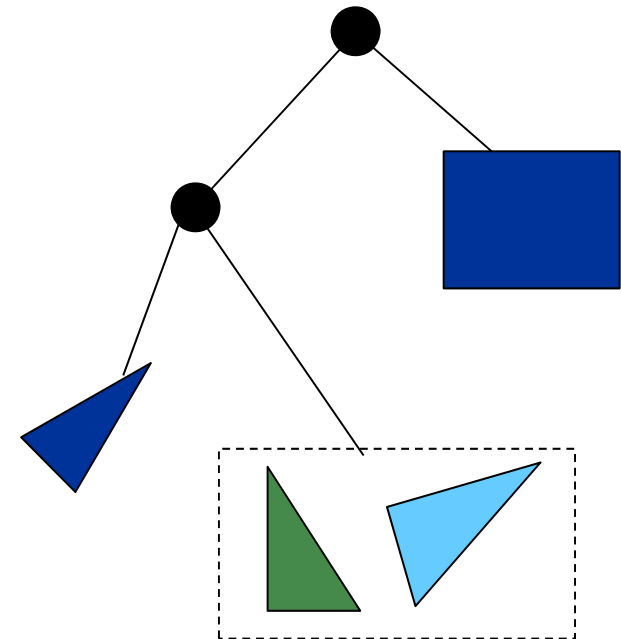
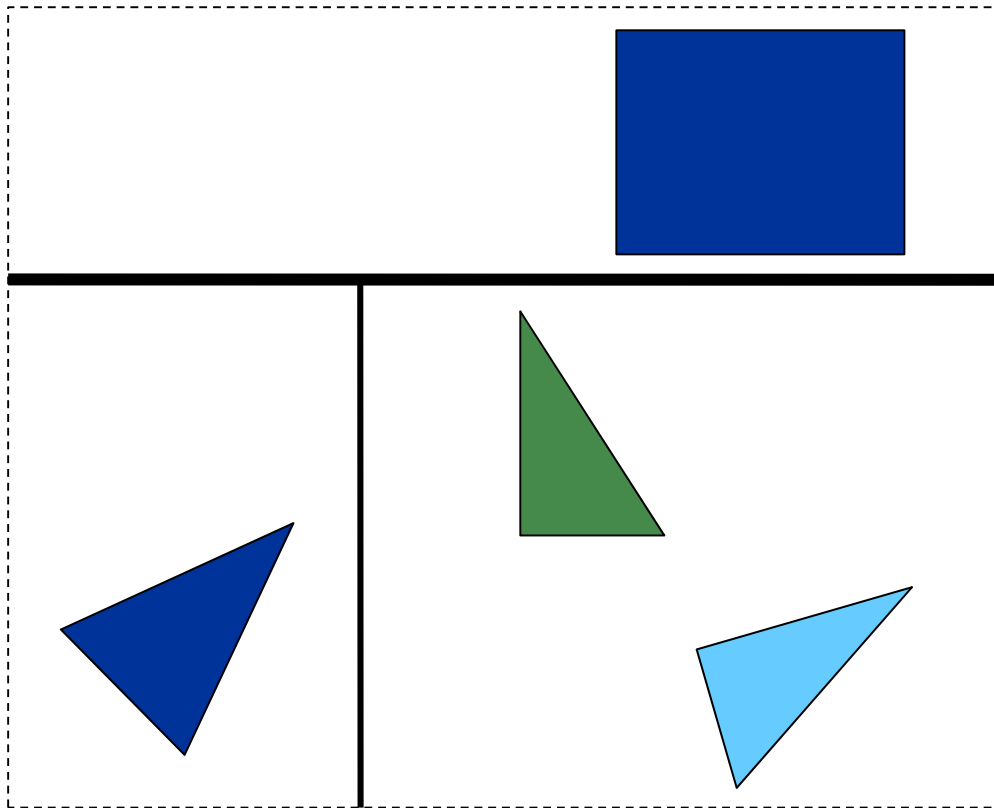
Kd-tree: Example



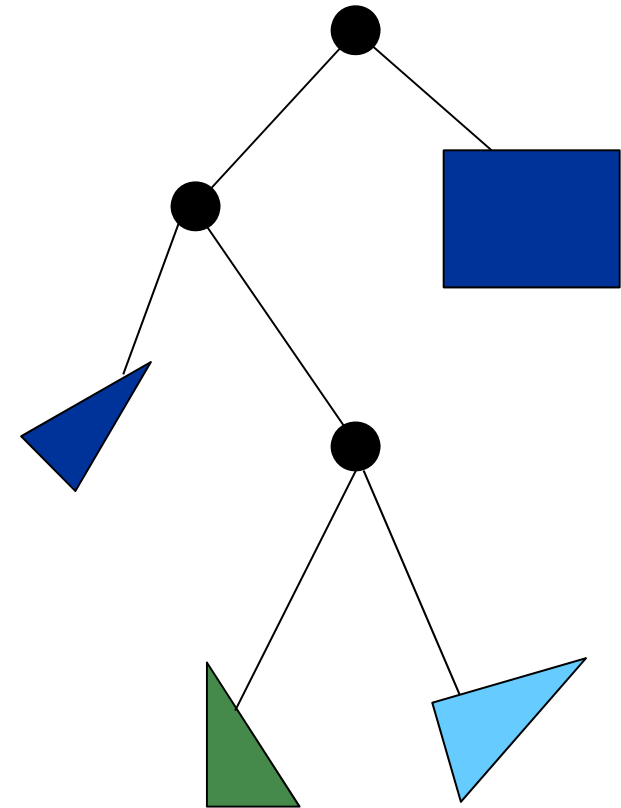
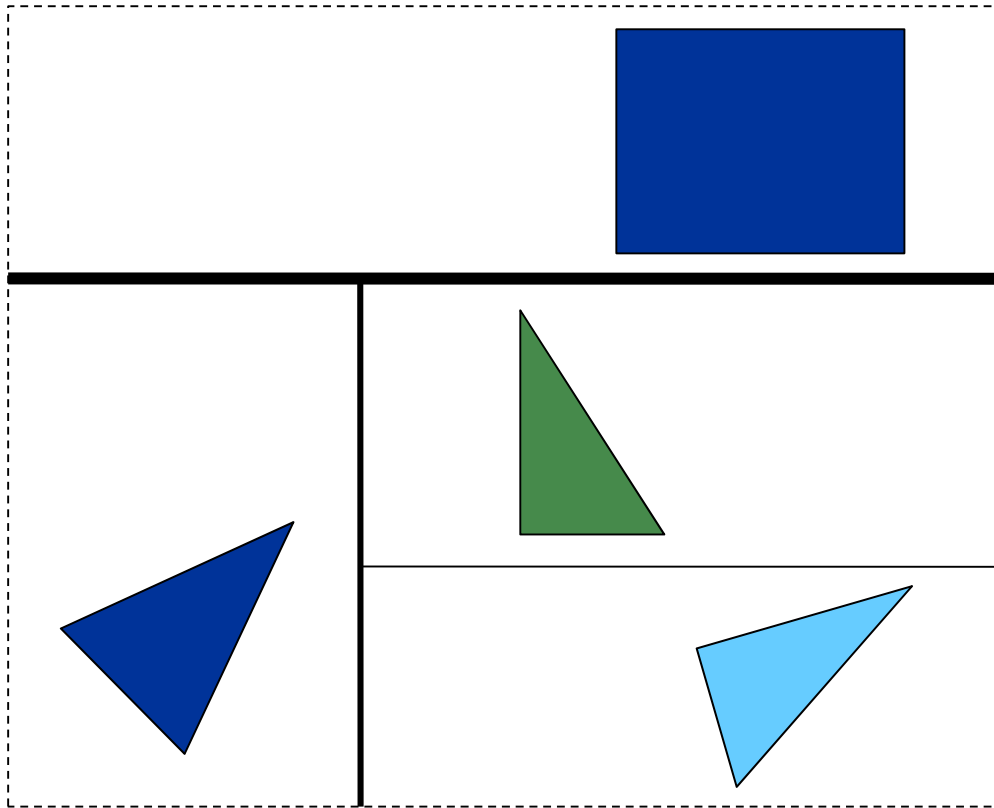
Kd-tree: Example



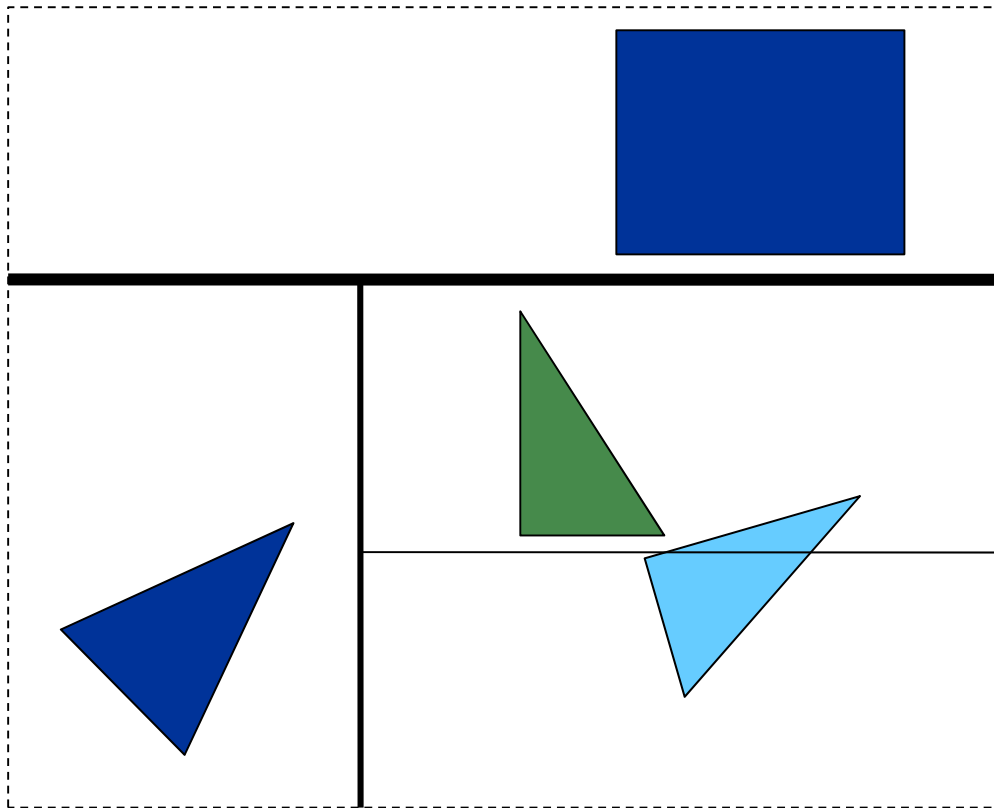
Kd-tree: Example



Example

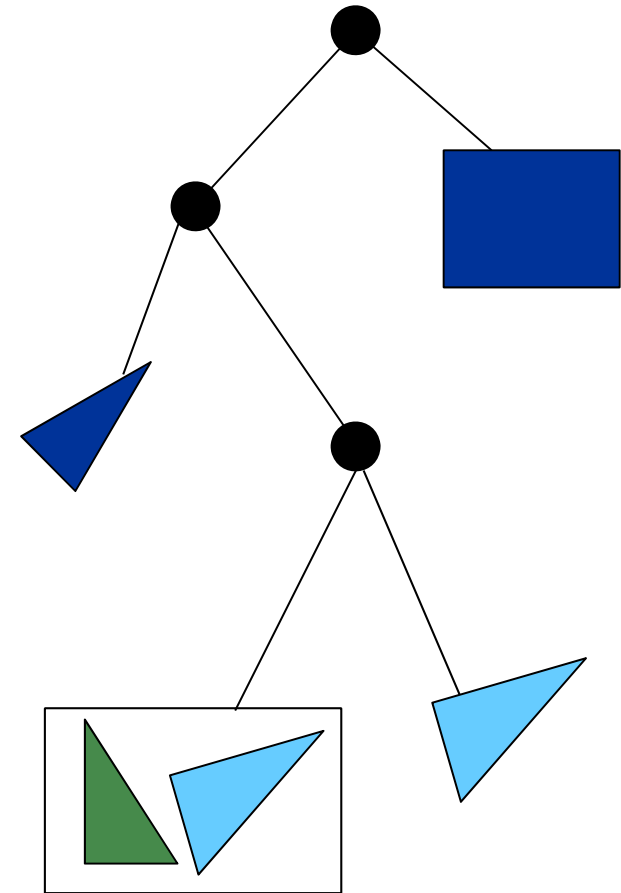
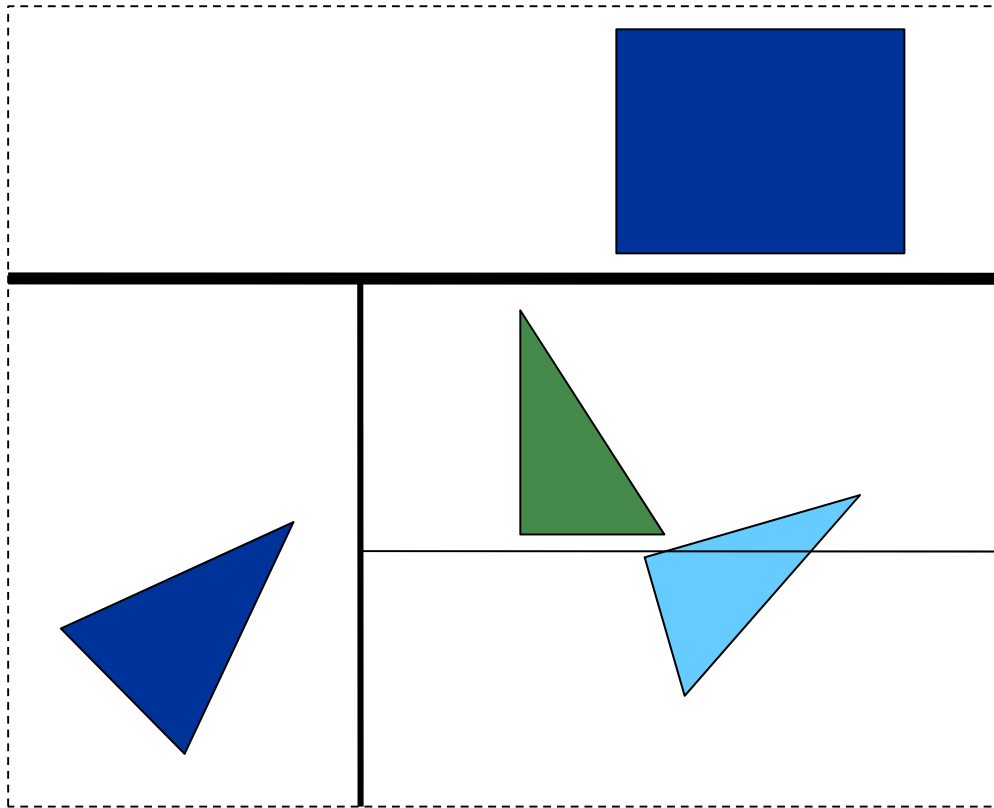


Kd-tree: Example



What about triangles overlapping the split?

Kd-tree: Example



Other Optimizations

- **Shadow cache**
- **Adaptive depth control**
- **Lazy geometry loading/creation**

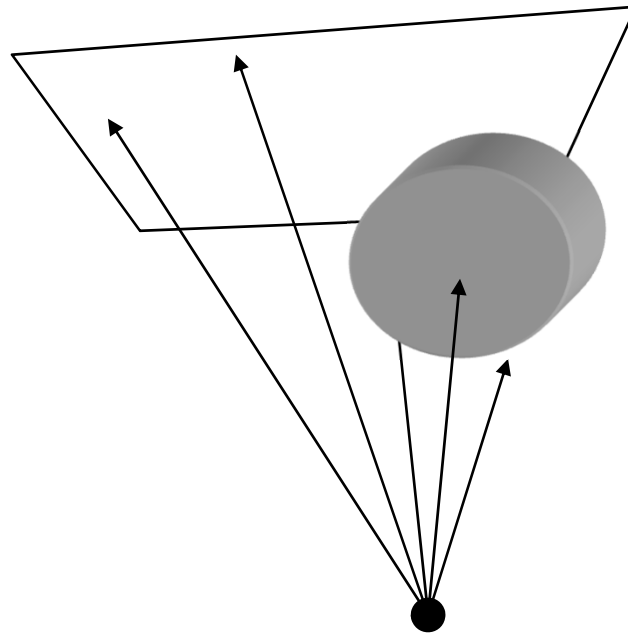
Distributed Ray Tracing [Cook et al. 84]

- Cook et al. realized that ray-tracing, when combined with randomized sampling, which they called “jittering”, could be adapted to address a wide range of rendering problems:



Soft Shadows

- **Take many samples from area light source and take their average**
 - **Computes fractional visibility leading to penumbra**

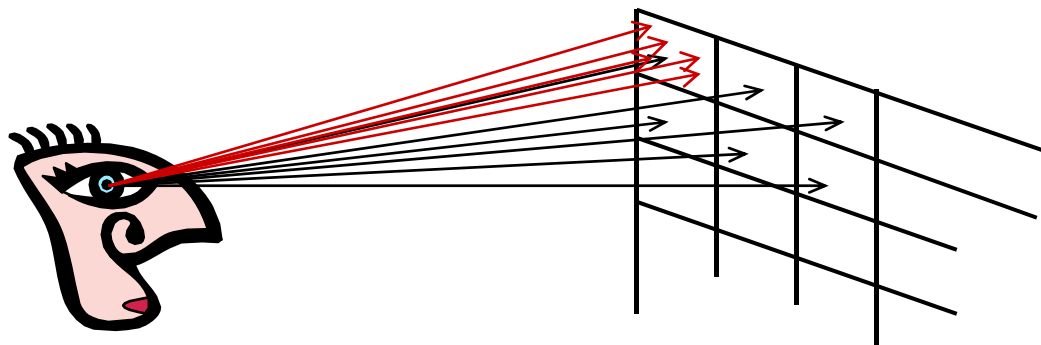


Antialiasing

- **The need to sample is problematic because sampling leads to aliasing**
- **Solution 1: super-sampling**
 - **Increases sampling rate, but does not completely eliminate aliasing**
 - **Difficult to completely eliminate aliasing without prefiltering because the world is not band-limited**

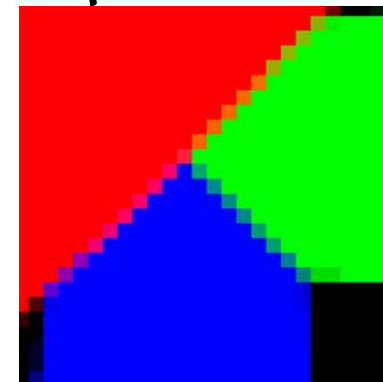
Antialiasing

- **Solution 2: distribute the samples randomly**
 - **Converts the aliasing energy to noise which is less objectionable to the eye**

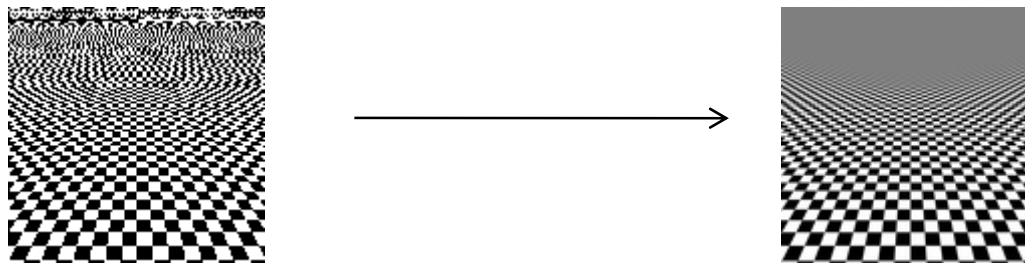
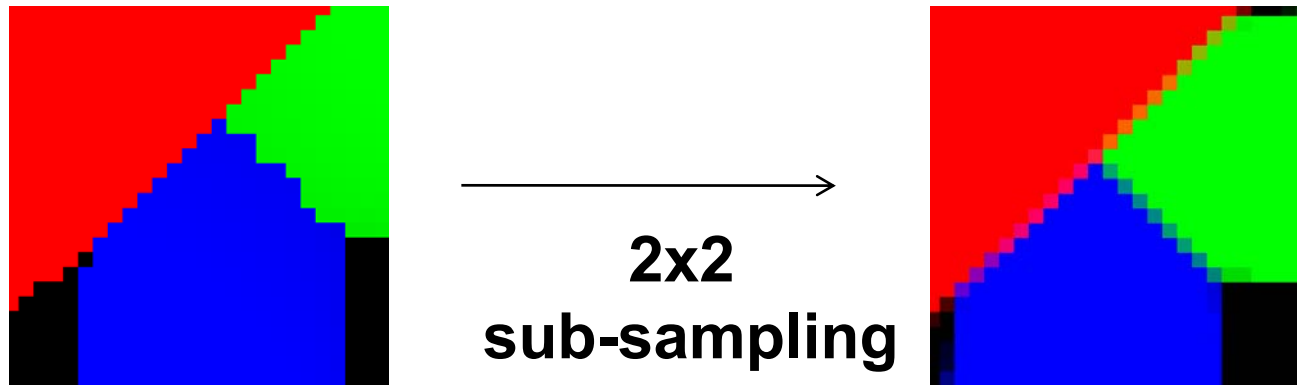


Instead of casting one ray per pixel, cast several sub-sampling.

Instead of uniform sub-sampling, jitter the pixels slightly off the grid.

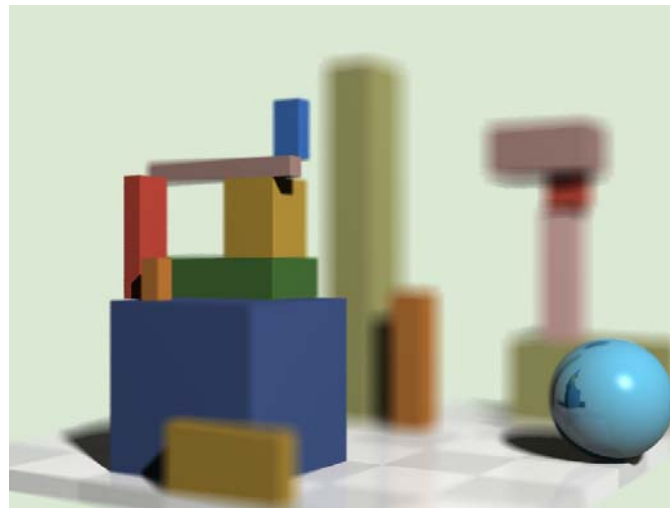


Jittering Results for Antialiasing

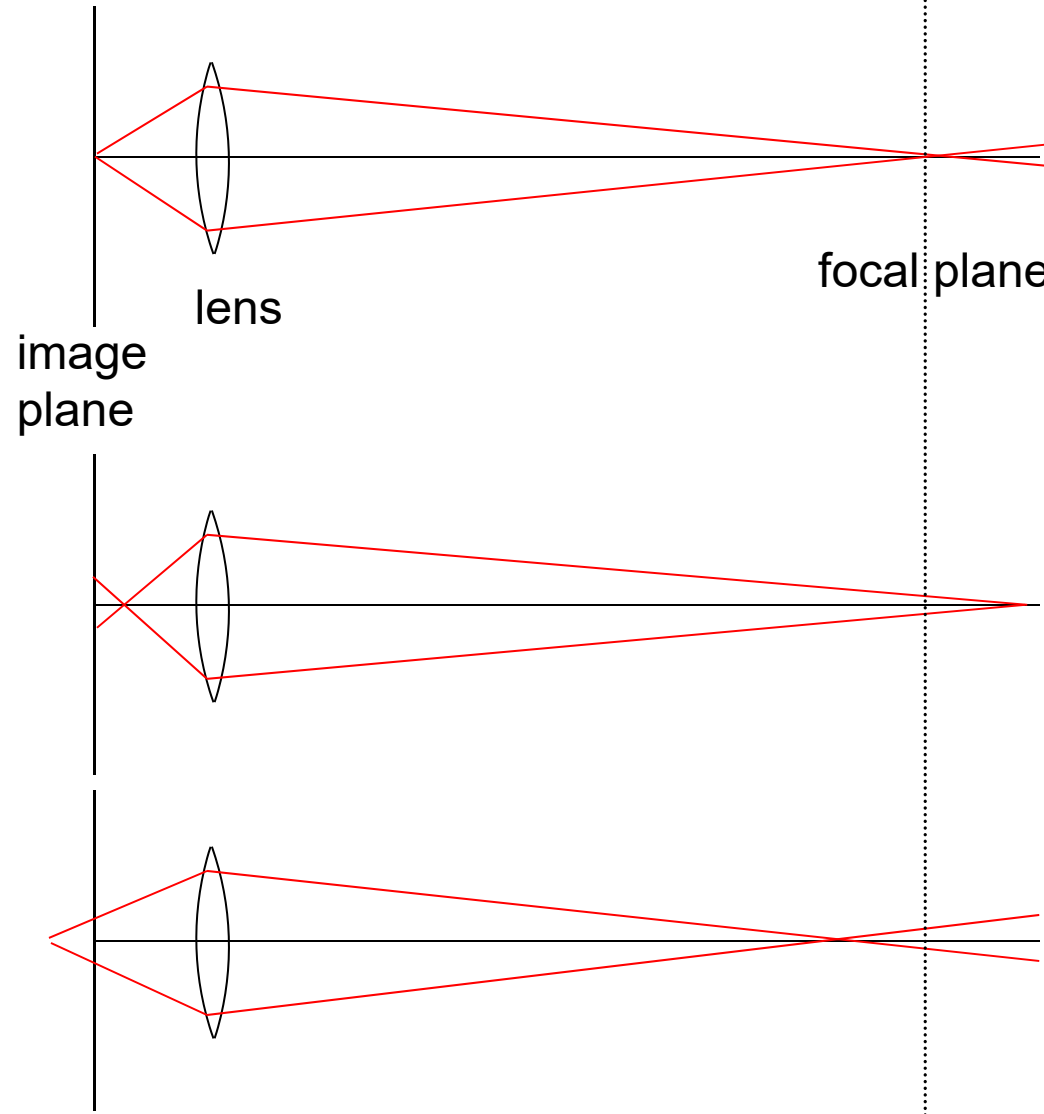


Depth-of-Field

- **Rays don't have to all originate from a single point.**
- **Real cameras collect rays over an aperture**
 - **Can be modeled as a disk**
 - **Final image is blurred away from the focal plane**
 - **Gives rise to depth-of-field effects**

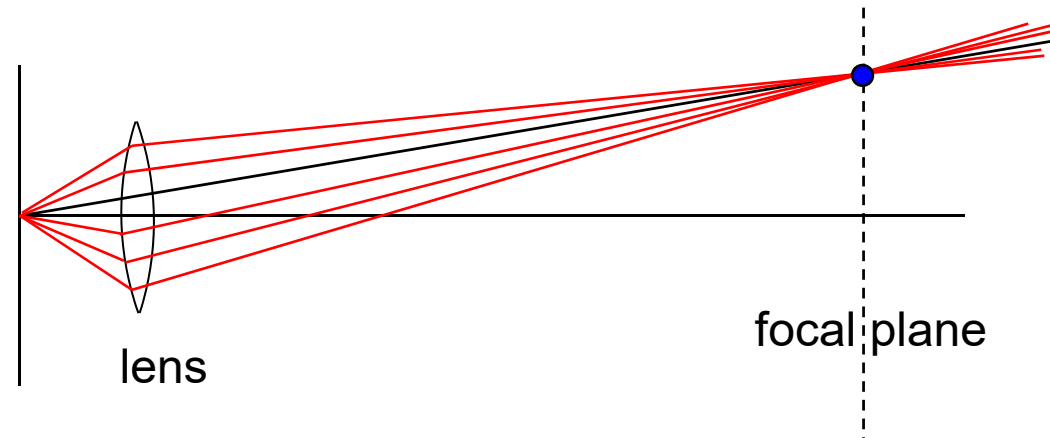


Depth of Field



Depth of Field

- **Start with normal eye ray and find intersection with focal plane**
- **Choose jittered point on lens and trace line from lens point to focal point**

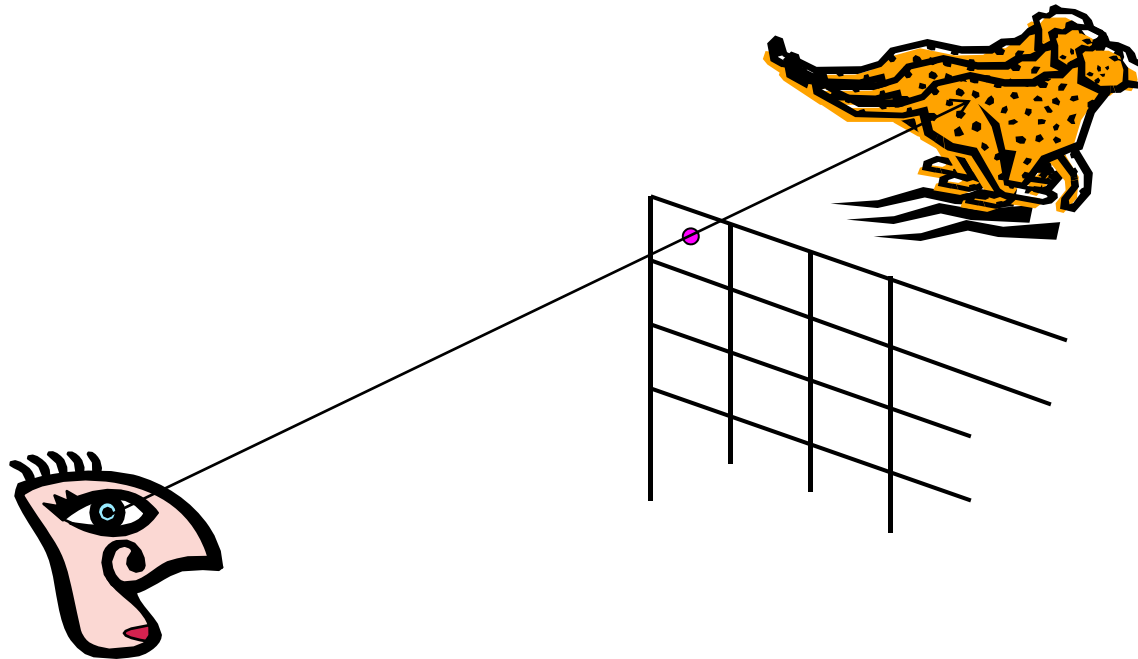


Motion Blur



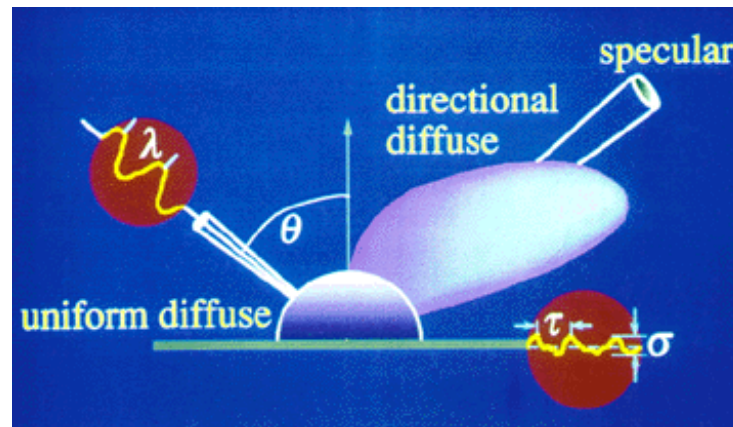
- **Jitter samples through time**
 - **Simulate the finite interval that a shutter is open on a real camera**

Motion Blur



Complex Interreflection

- **Model true reflection behavior as described by a full BRDF**
- **Randomly sample rays over the hemisphere, weight them by their BRDF value, and average them together**
 - **This technique is called “Monte Carlo Integration”**



Related Courses

- **CS580: Advanced Computer Graphics**
 - Focus on rendering techniques that generate photo-realistic images
- **CS482: Interactive Computer Graphics**
 - Interactive global illumination implemented by rasterization approaches
 - Techniques used in recent games
 - I'll teach it at Fall of 2018