Augmented Reality

Sung-eui Yoon

Project Guidelines: Project Topics

- **Any topics related to the course theme are okay**
  - **You can find topics by browsing recent papers**

Expectations

- **Mid-term project presentation**
  - **Introduce problems and explain why it is important**
  - **Give an overall idea on the related work**
  - **Explain what problems those existing techniques have**
  - **(Optional) explain how you can address those problems**
  - **Explain roles of each member**

- **Ack. any external slides/codes, etc.**

Expectations

- **Final-term project presentation**
  - **Review materials that you talked for your mid-term project**
  - **Present your ideas that can address problems of those state-of-the-art techniques**
  - **Give your qualitatively (or intuitive) reasons how your ideas address them**
  - **Also, explain expected benefits and drawbacks of your approach**
  - **(Optional) backup your claims with quantitative results collected by some implementations**
  - **Explain roles of each members**
- **Ack. any external slides/codes, etc.**

KAIST

A few more comments

- **Start to implement a paper, if you don't have any clear ideas**
  - **While you implement it, you may get ideas about improving it**

Project evaluation sheet

You name:
ID:

Score table: higher score is better.

Speaker	Novelty of the project and idea (1 ~ 5)	Practical benefits of the method (1 ~ 5)	Completeness level of the project (1 ~ 5)	Total score (3 ~ 15)	Role of each student is clear and well balanced? (Yes or No)
XXX					
YYY					

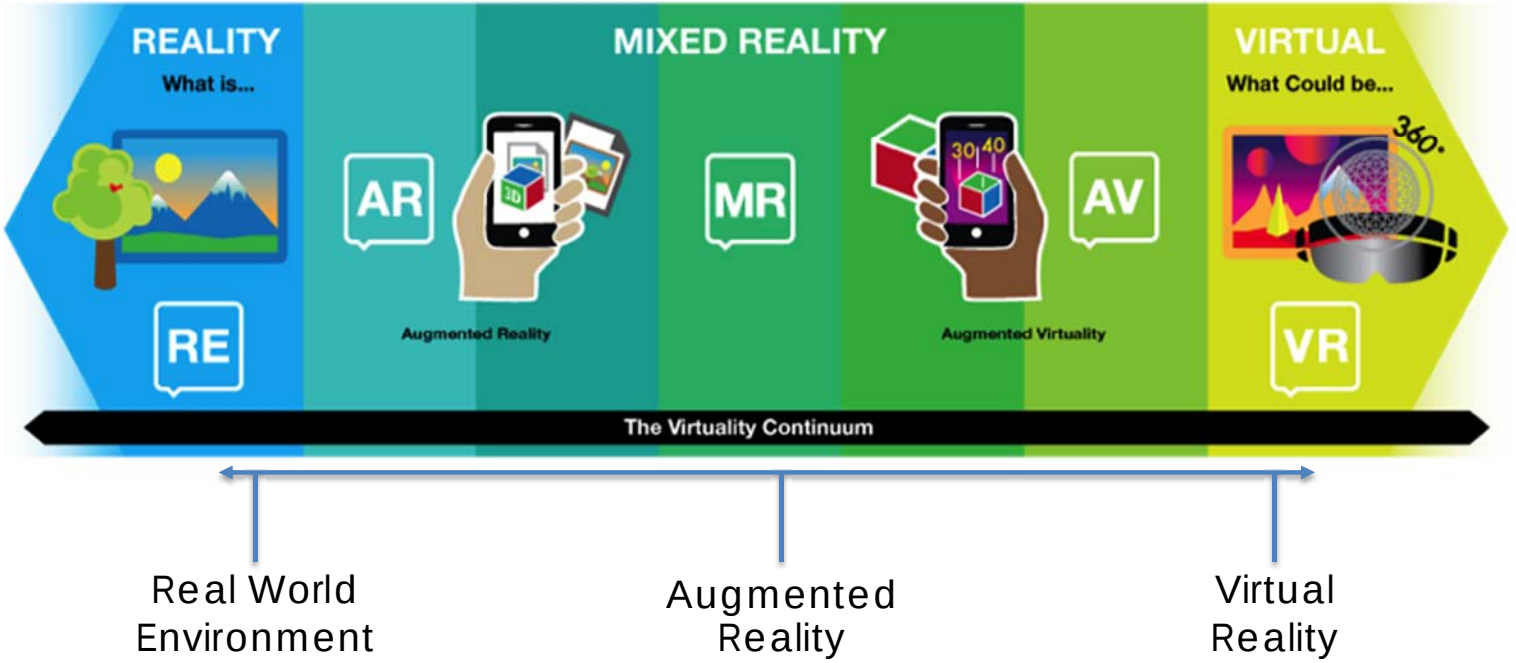
KAIST

Goals for Today

Goals

- Getting acquainted with AR
- Making your own Augmented Reality
- Some of recent techniques

What is Augmented Reality?



Milgram, Paul, et al. "Augmented reality: A class of displays on the reality-virtuality continuum." *Photonics for industrial applications*. International Society for Optics and Photonics, 1995.

Photo Source: http://smartideasblog.trekk.com/augmented-or-virtual-how-do-you-like-your-reality

Brief History

- 1968 Ivan Sutherland invents first head-mounted display “Sword-of-Damocles” at University of Utah.
- 2010 Vuforia for AR Mobile Apps was released by Qualcomm.
- 2013 Google announces Google Glass.
- 2015 Microsoft announces the HoloLens.
- 2016 Niantic released Pokémon Go.

Original slides are from Frend, Chauncey. ”Augmented Reality & the UITS Advanced Visualization Lab."

AR today – Industry Examples

AR Coloring Book

(0:00-0:30)

Live Texturing of Augmented Reality Characters from Colored Drawings
IEEE International Symposium on Mixed and Augmented Reality (ISMAR) 2015

HoloLens

Augmented Climbing Wall

(0:00-0:33)

dedicated workshops on Mar. 24th & 31st

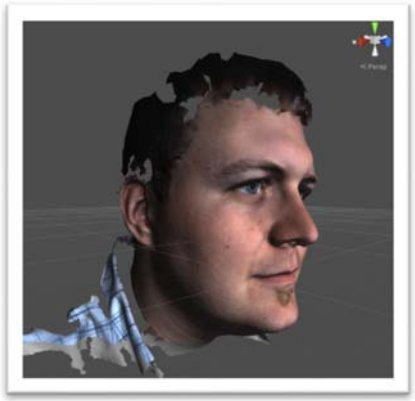
Building Experiences

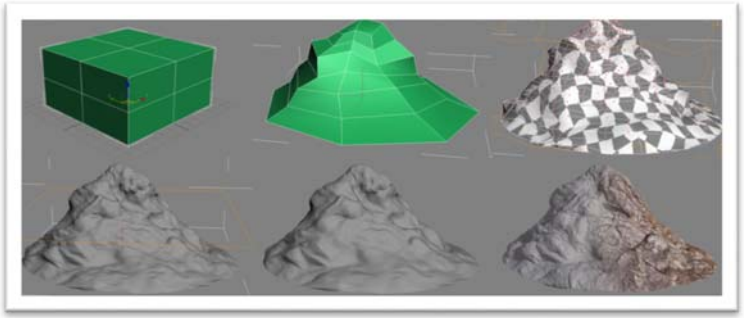
Assets + Display + Interface

Sourcing or Building Data

- 3D Scanning
  - 3D Scanning
  - Photogrammetry
- 3D Authoring
  - Autodesk Maya or Max
  - Sketchup
  - TinkerCAD
- 3D Repositories
  - Sketchup 3D Warehouse
  - Smithsonian X 3D https://3d.si.edu/browser
  - Sketchfab*
  - Thingiverse*

- You can also augment with media
  - Audio
  - 2D media (Image & video)
  - Text





Building Experiences

Assets + **Display** + Interface

Mobile Devices

PC or Mac with Webcam

HoloLens Headset

Building Experiences

Assets + Display + **Interface**

Onboarding AR – Prototyping Tools

No programming required

wikitude

See more.

Building Experiences

Assets + Display + **Interface**

Development Tools

Base Package → **AR Plugins**

AR Technology

- Mobile Device Apps
- Image or Object Markers

- Desktop or Laptop Apps
- Fiducial or Image Markers

- HoloLens device Apps
- Area Learning or Image Markers

What the future may hold

Web Hosted AR Applications

Consumer-grade headsets

Cyber Physical AR Applications

(2:16-3:04)

Resources for you!

Base Package

Tutorials https://unity3d.com/learn

AR Plugins

Vuforia Basics Tutorial By: Chauncey
https://www.youtube.com/watch?v=qbI9PrSUo5w

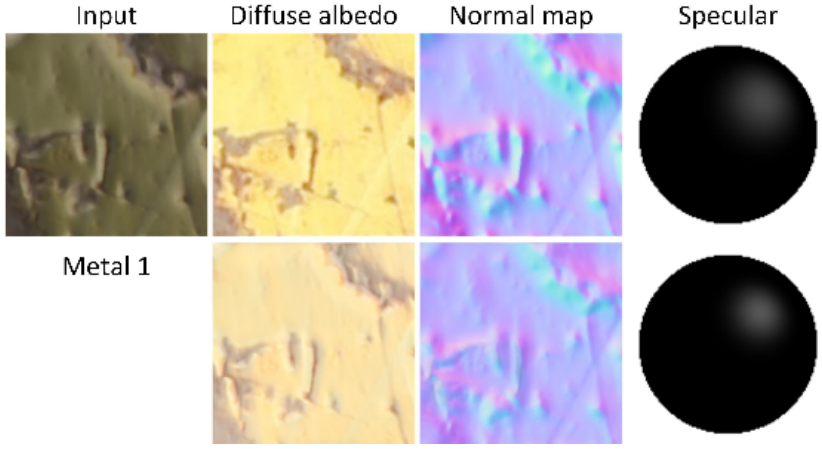
AR YouTube Playlist

Technical Components

- Robotics parts
  - Simultaneous localization and mapping (SLAM)
- Computer vision parts
  - Geometry, light, and materials estimation
- Graphics parts
  - Rendering virtual objects
- Machine learning
  - Understand various things
- AR spans various fields

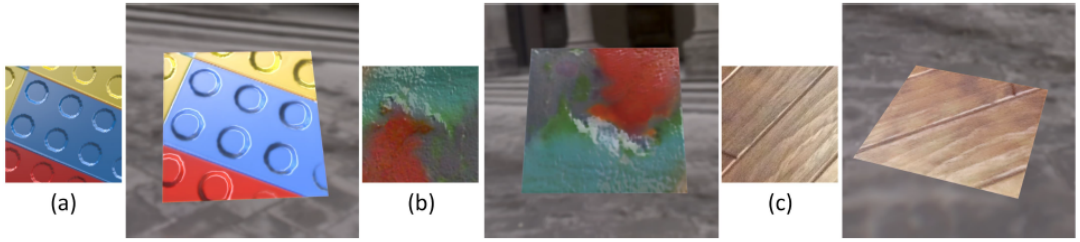
Modeling Surface Appearance from a Single Photography using Self-Augmentation [Li et al.]

- **Assume the anisotropic Ward BRDF model**
  - **Diffuse albedo and normal map per each pixel**
  - **Specular parameters for each image**



Ground truth

Reconstructed ones

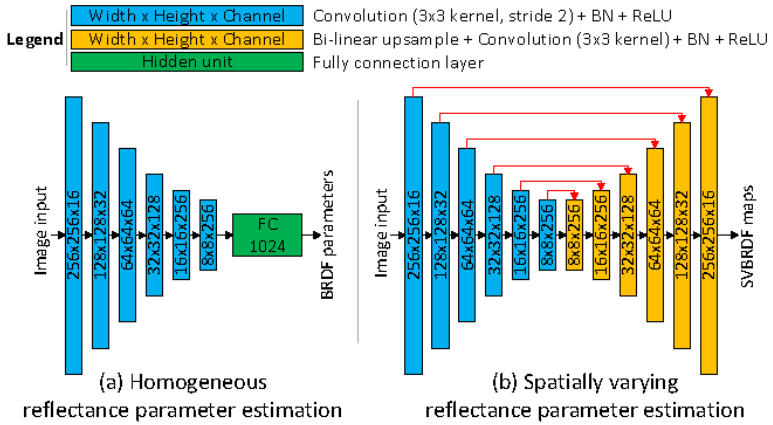


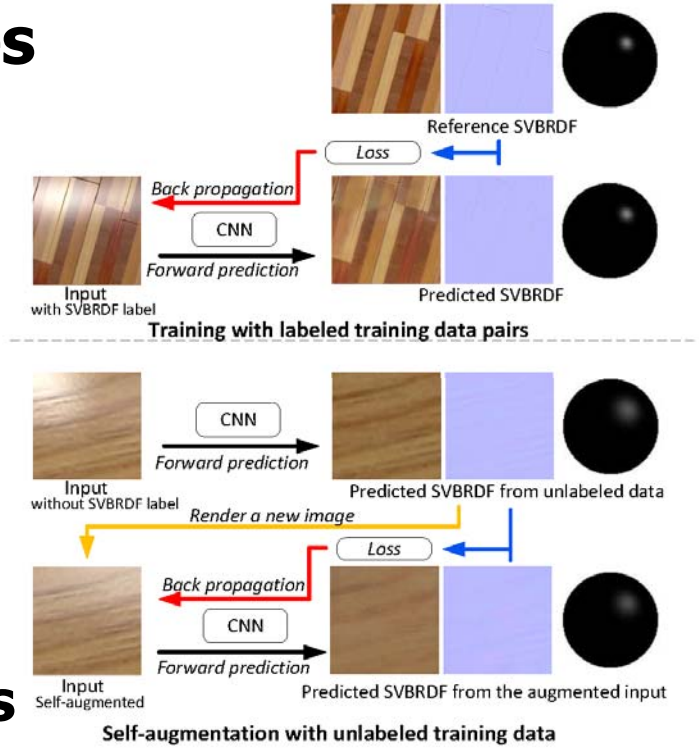
Original images with relighted images

KAIST

Network Architectures

- **Two separate architectures**





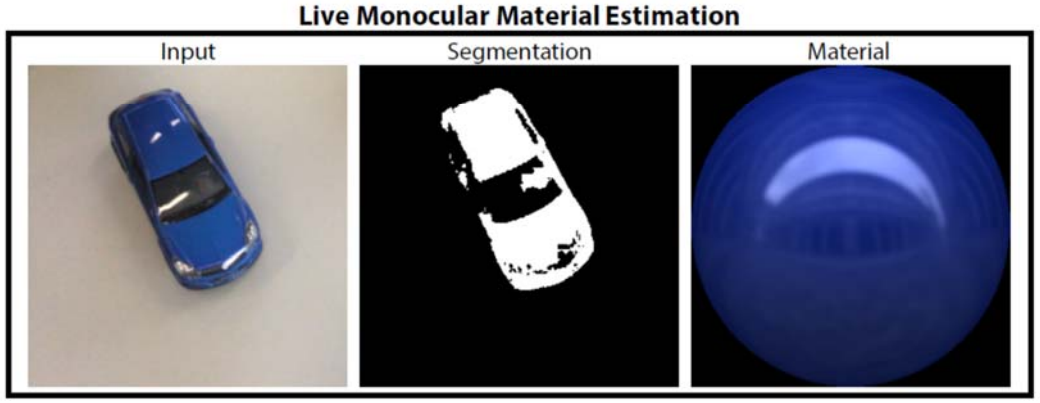
- **Self-augmentation**
  - **Use unlabeled image and reconstruct parameters**
  - **Generate its corresponding image**
  - **Use them as training pairs with labeled ones**

KAIST

LIME: Live Intrinsic Material Estimation [Meka et al. CVPR 18]

- **Estimate specular information of an object in the RGB image**
  - **Starts with the rendering equation, but ends up with assuming the Phone illumination: diffuse and specular terms**

$$\mathrm{BP}(\mathbf{x},\mathbf{n},\boldsymbol{\omega}_i,\boldsymbol{\omega}_o) = \underbrace{\mathbf{m}_d(\boldsymbol{\omega}_i \cdot \mathbf{n})}_{\text{diffuse}} + \underbrace{\mathbf{m}_s(\mathbf{h}\cdot\mathbf{n})^s}_{\text{specular}}. \qquad (3)$$



KAIST



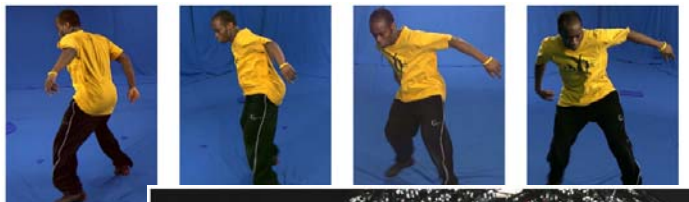
Real-Time Geometry, Albedo, and Motion Reconstruction Using a Single RGB-D Camera

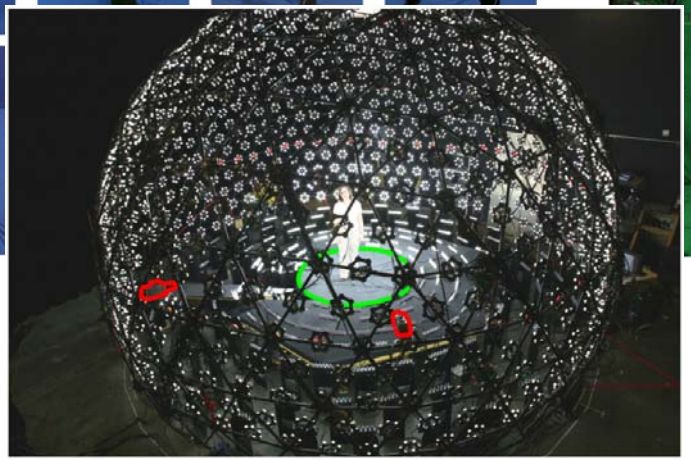
Kaiwen Guo[1], Feng Xu[1], Tao Yu[1,2], Xiaoyang Liu[1], Qionghai Dai[1], Yebin Liu[1]

Tsinghua University[1] Beihang University[2]

KAIST

Offline Volumetric Performance Capture



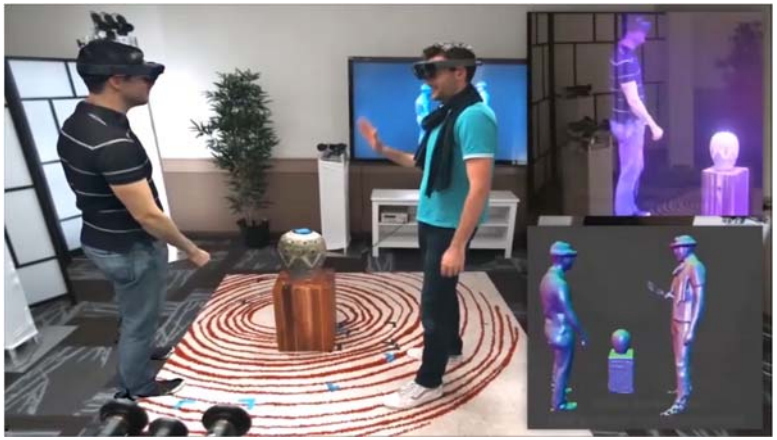


[Starck and Hilton, 2007], [Liu et al., 2009]

[Vlasic et al. 2009], [Debevec, Light Stage], [Collet et al. 2015]

KAIST

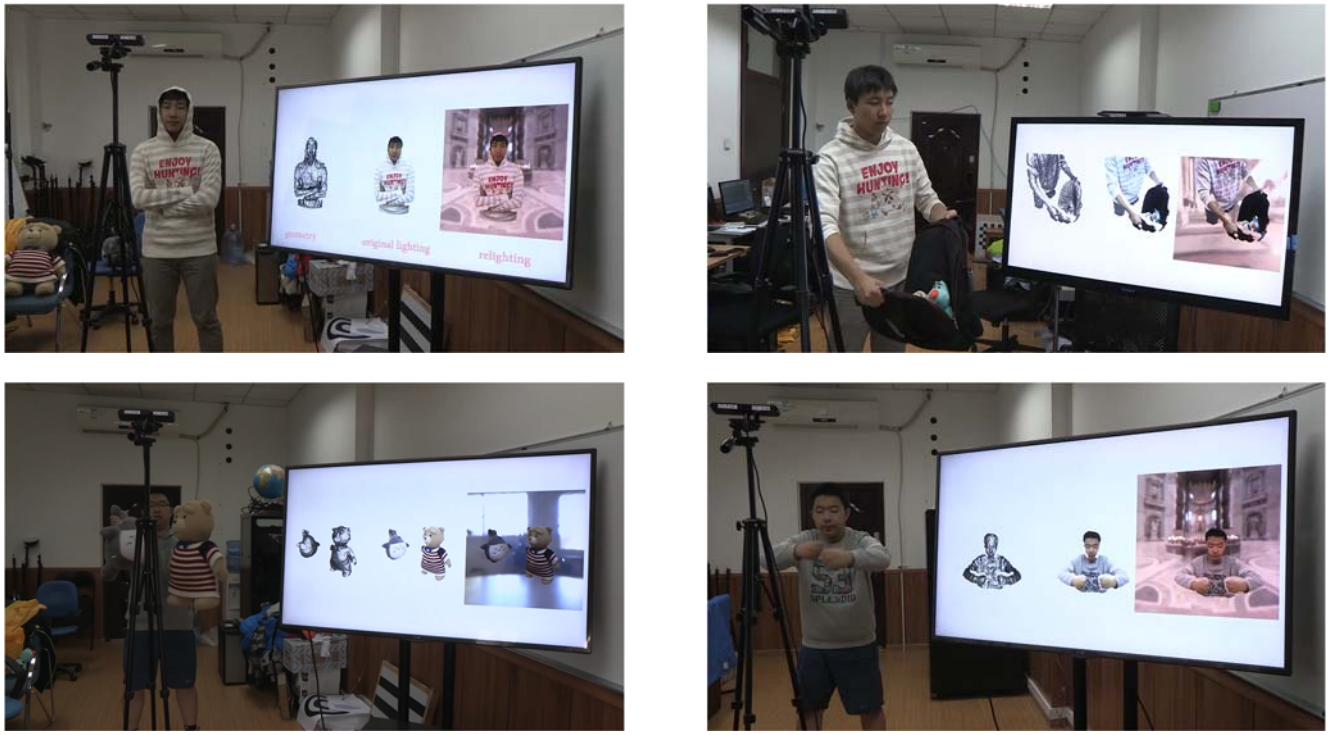
Real-time Volumetric Performance Capture



[Fusion4D, Dou et al. 2016], [Holoportation, Orts-Escolano et al. 2016]

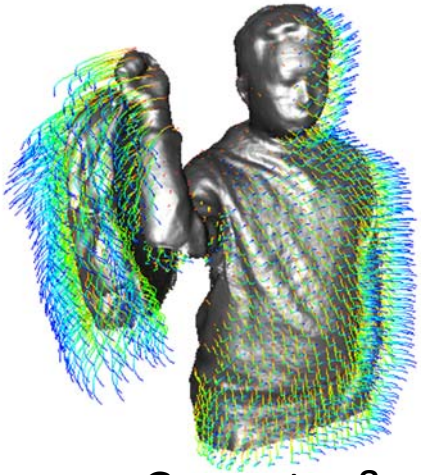
KAIST

Real-time Single-view Volumetric Capture



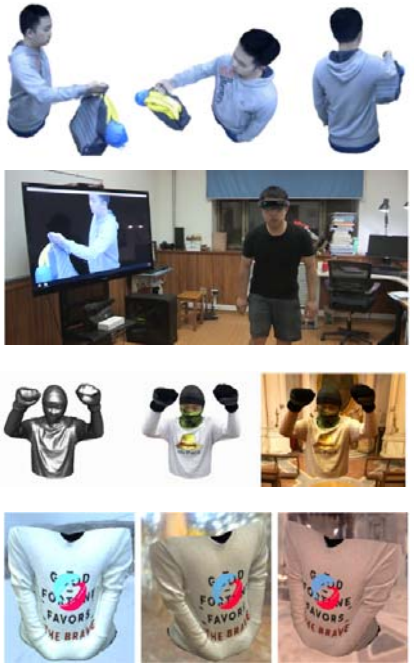
KAIST

Key Idea: Joint Optimization considering Shading



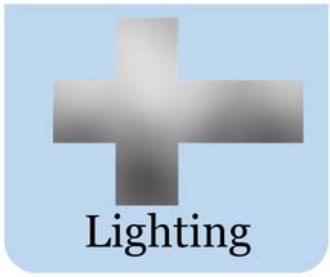
Geometry & Motion

Appearance (diffuse objects)



KAIST

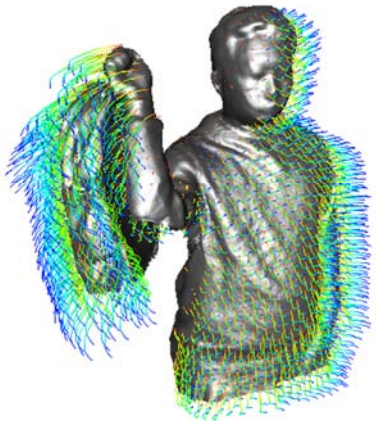
Overview



Color

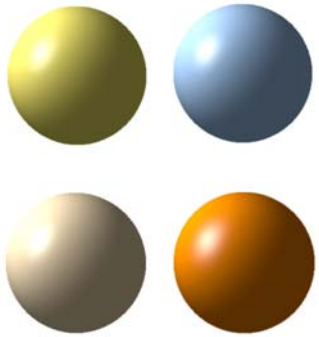
Depth

Input



Motion

Geometry



Albedo (color)

Output

Assume diffuse objects

KAIST

Learning to Predict Indoor Illumination from a Single Image

Marc-André Gardner, Kalyan Sunkavalli, Ersin Yumer, Xiaohui Shen,
Emiliano Gambaretto, Christian Gagné, Jean-François Lalonde

Université Laval, Québec, Canada
Adobe Systems Inc., San Jose, USA

Illumination is key

Current approaches and limitations

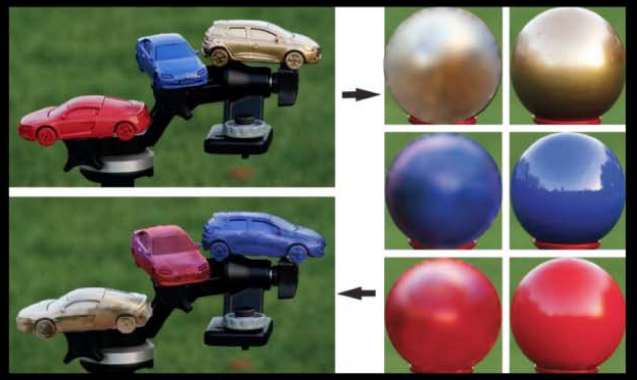
Calibration objects

[Debevec, 1998]

Specialized hardware

[Tocci, 2011], [Manakov, 2013]

Scene knowledge



[Rematas, 2015]

Our approach

No calibration

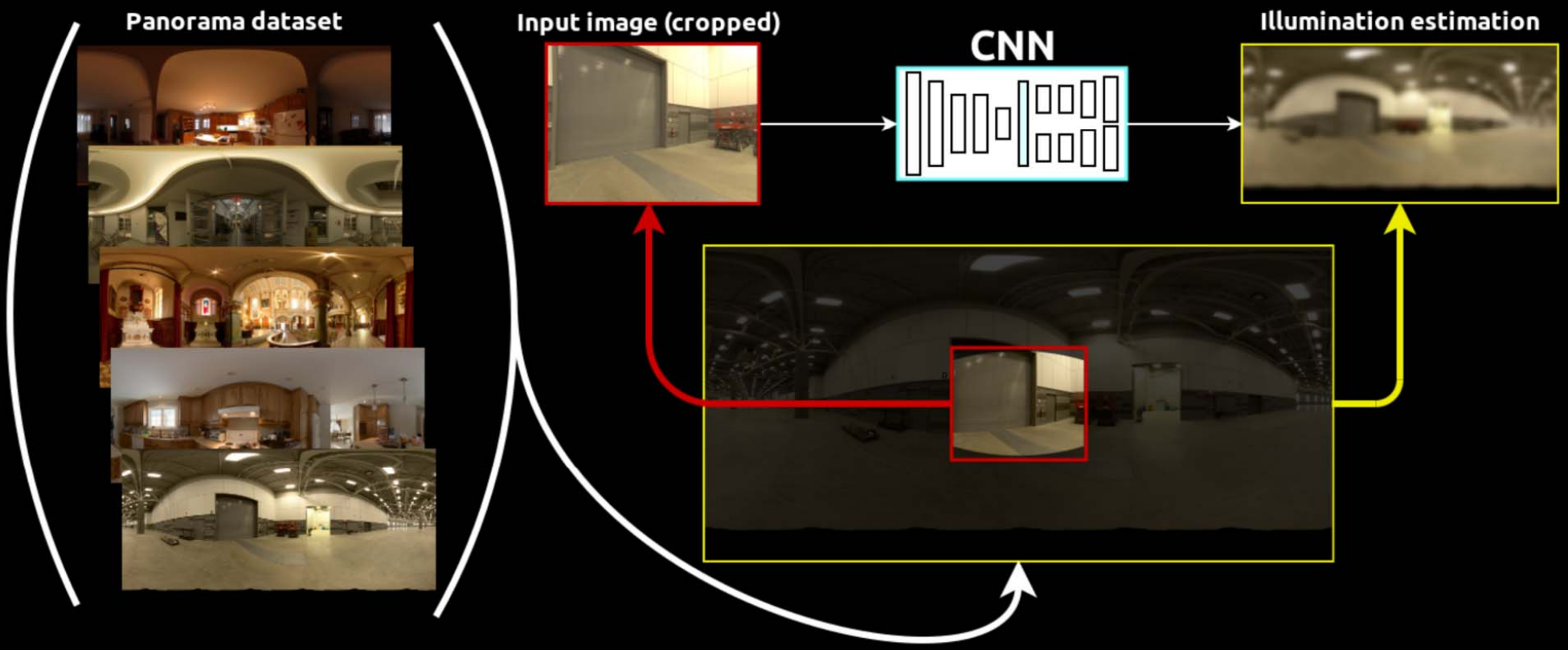
Any camera

No prior knowledge

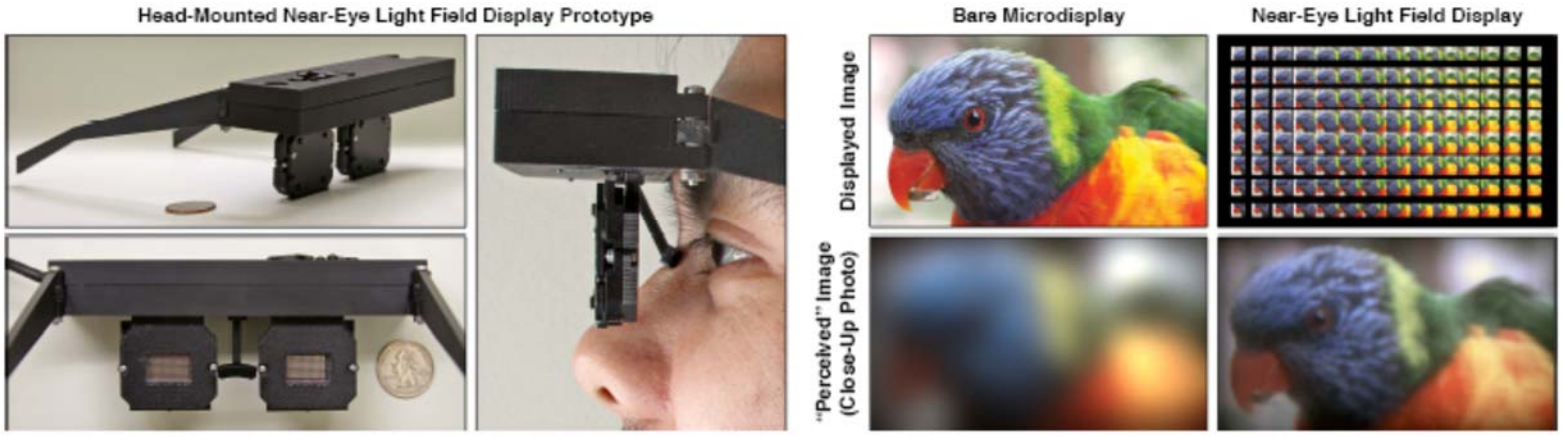
Our goal

Given a single indoor LDR image, recover a whole HDR environment map

End-to-end learning approach



Near-Eye Light Field Display [ToG 13]



- **Use a microlens array for supporting the light field**

KAIST

Goals for Today were:

- **Getting acquainted with AR**
- **Making your own Augmented Reality**
- **Some of recent techniques**

KAIST