
Improving Spatial and Semantic Context of Local Descriptors for Image Retrieval

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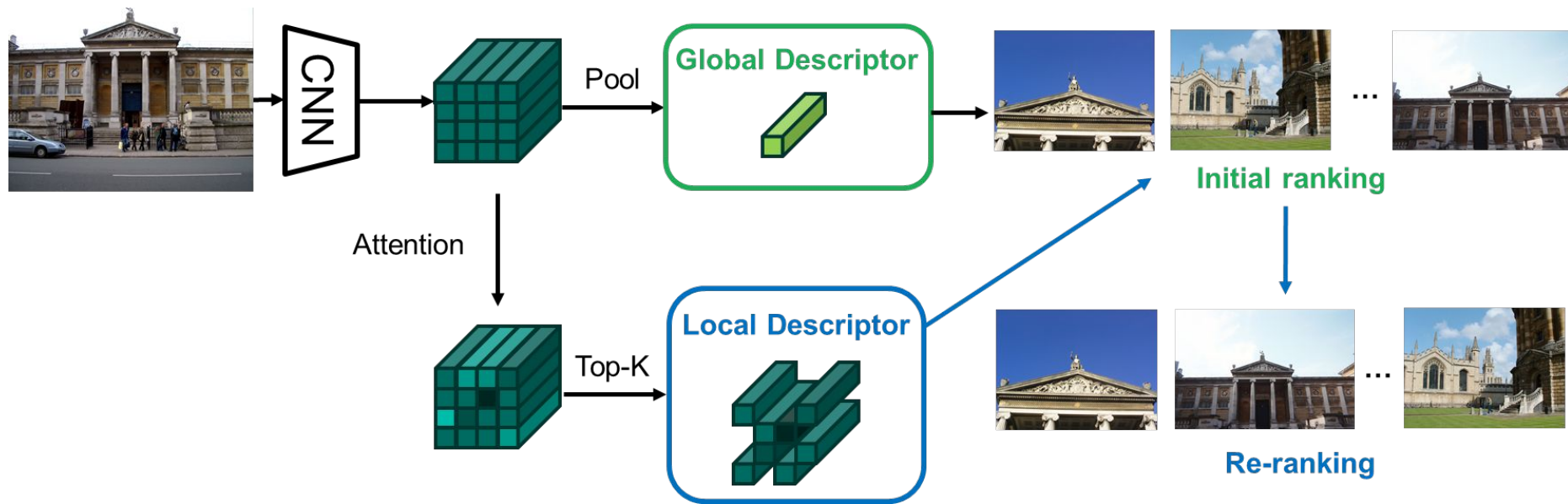
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KAIST

The KAIST logo consists of the letters 'KAIST' in a bold, blue, sans-serif font. Below the text is a light blue, horizontal oval shape that serves as a shadow or base for the letters.

Image Retrieval

- Global descriptors for initial ranking
- Local descriptors for re-ranking based on attention score



Framework of Image Retrieval

1. Global: Initial ranking (speed \uparrow acc \downarrow)
2. Global + local: Initial + re-ranking (speed - acc -)
3. Local + matching: Matching (speed \downarrow acc \uparrow)

1	method	FCN	Mem (GB)	\mathcal{R} Oxford		\mathcal{R} Oxford + \mathcal{R} 1M		\mathcal{R} Paris		\mathcal{R} Paris + \mathcal{R} 1M	
				med	hard	med	hard	med	hard	med	hard
	<i>Global descriptors</i>										
	RMAC (Tolias et al., 2016)	R101	7.6	60.9	32.4	39.3	12.5	78.9	59.4	54.8	28.0
	AP-GeM [†] (Revaud et al., 2019a)	R101	7.6	67.1	42.3	47.8	22.5	80.3	60.9	51.9	24.6
2	GeM+SOLAR (Ng et al., 2020)	R101	7.6	69.9	47.9	53.5	29.9	81.6	64.5	59.2	33.4
	<i>Global descriptors + reranking with local features</i>										
	DELG (Cao et al., 2020)	R50	7.6	75.1	54.2	61.1	36.8	82.3	64.9	60.5	34.8
3	DELG (Cao et al., 2020)	R101	7.6	78.5	59.3	62.7	39.3	82.9	65.5	62.6	37.0
	<i>Local features + ASMK matching (max. 1000 features per image)</i>										
	DEL _F (Noh et al., 2017)	R50 ⁻	9.2	67.8	43.1	53.8	31.2	76.9	55.4	57.3	26.4
	DEL _F -R-ASM _K (Teichmann et al., 2019)	R50 ⁻	27.4	76.0	52.4	<u>64.0</u>	<u>38.1</u>	<u>80.2</u>	58.6	<u>59.7</u>	29.4
	HOW (Tolias et al., 2020)	R50 ⁻	7.9	<u>78.3</u>	<u>55.8</u>	63.6	36.8	80.1	<u>60.1</u>	58.4	<u>30.7</u>
	FIRE (ours)	R50 ⁻	6.4	81.8	61.2	66.5	40.1	85.3	70.0	67.6	42.9
	(standard deviation over 5 runs)			(± 0.6)	(± 1.0)	(± 0.8)	(± 1.1)	(± 0.4)	(± 0.6)	(± 0.7)	(± 0.8)
	(mAP gains over HOW)			($\uparrow 3.5$)	($\uparrow 5.4$)	($\uparrow 2.9$)	($\uparrow 3.3$)	($\uparrow 5.2$)	($\uparrow 9.9$)	($\uparrow 9.2$)	($\uparrow 12.2$)

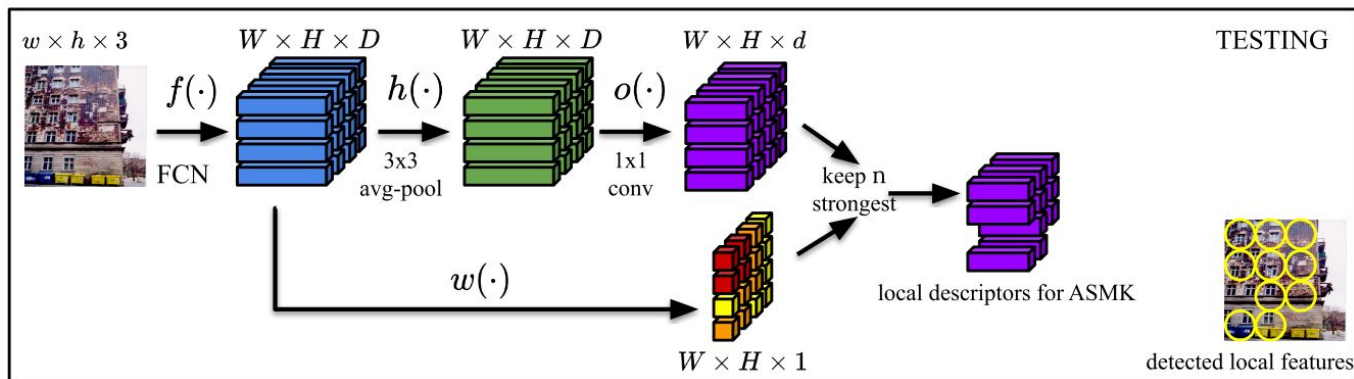
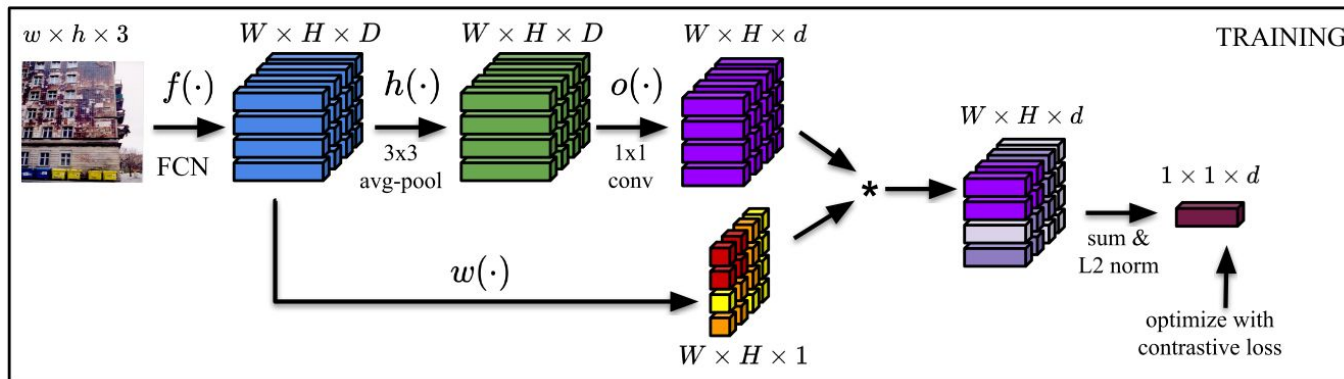
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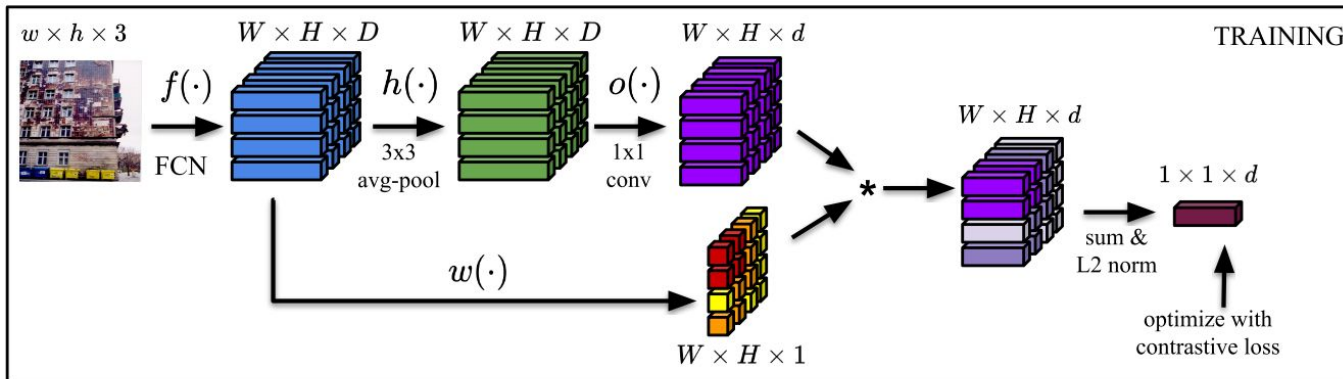
Gathering Local Descriptors

- Train with aggregate of local features from CNN backbone
- Use top-K local features as descriptors based on attention map



Motivation - Limited Local Context

- Relationships between local descriptors (i.e., local context) are discarded during training & matching



Training is done by simply taking the weighted-sum of local features

$$\alpha = 3, \tau = 0.25$$

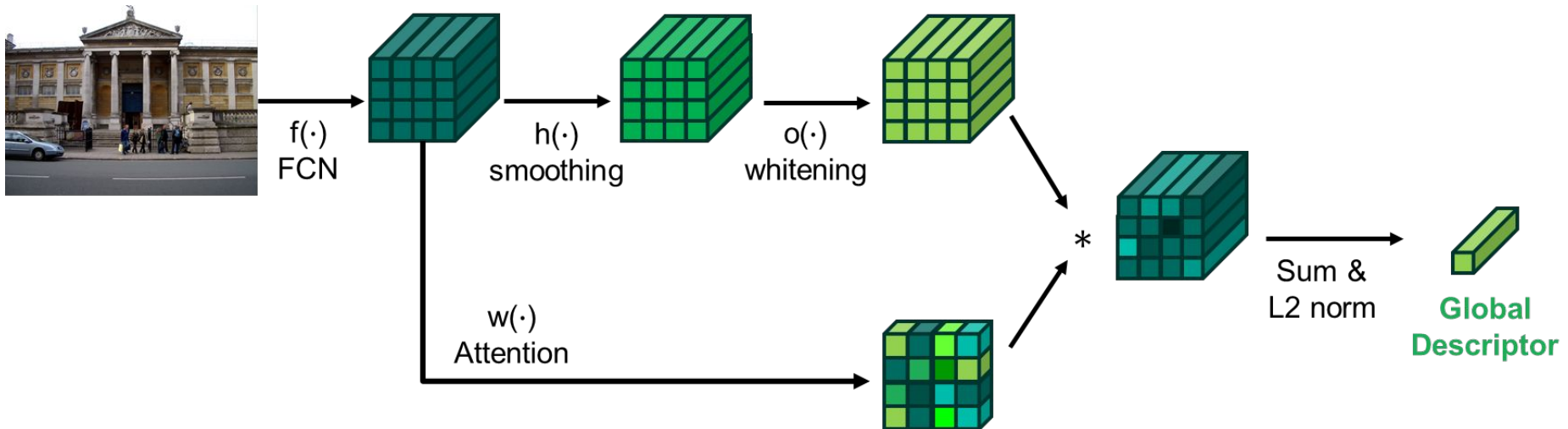


Matching is done by taking the sum of similarity between matched local descriptors (ASMK)

$$\sum_{x \in \mathcal{X}, y \in \mathcal{Y}} (x^T \cdot y)^\alpha$$

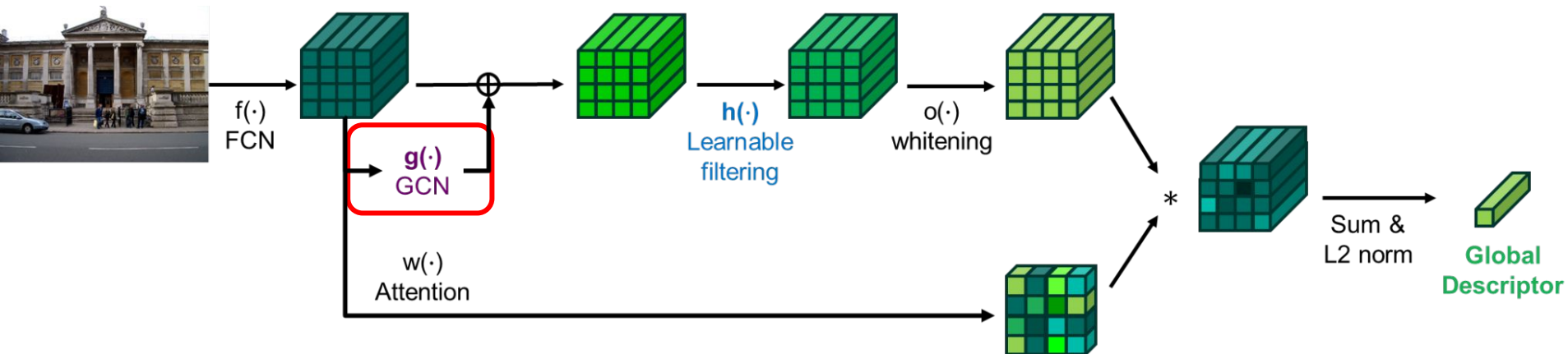
Previous work

- $f(\cdot)$: Feature extractor - R18 / 50
- $h(\cdot)$: Local smoothing - Average pooling
- $o(\cdot)$: Whitening - 1x1 Conv
- $w(\cdot)$: Attention - L2 norm



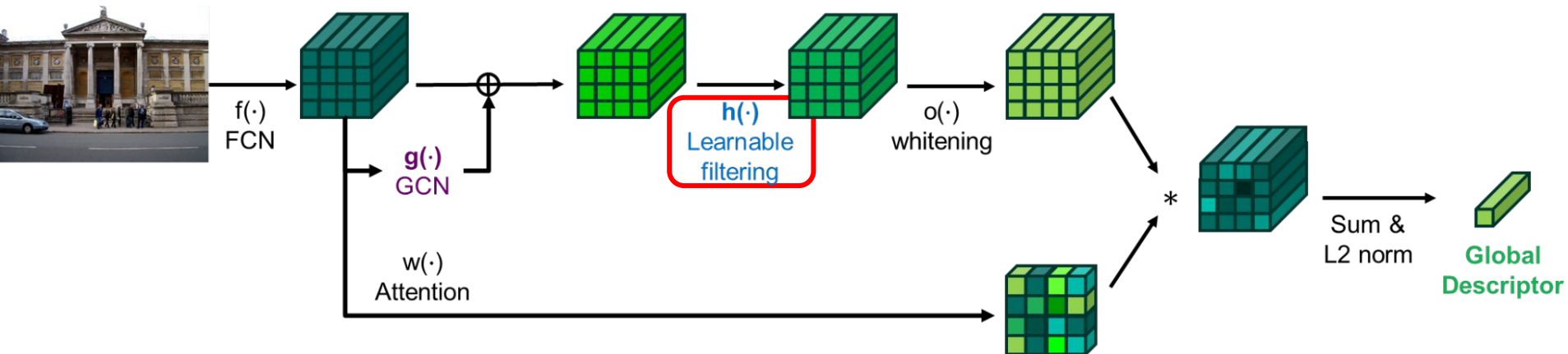
Our Goal

- Provide rich context information for local descriptors
 - Provide semantic information of local descriptors via **graph convolution**
 - Increase the effective region via **learnable smoothing** for local descriptors



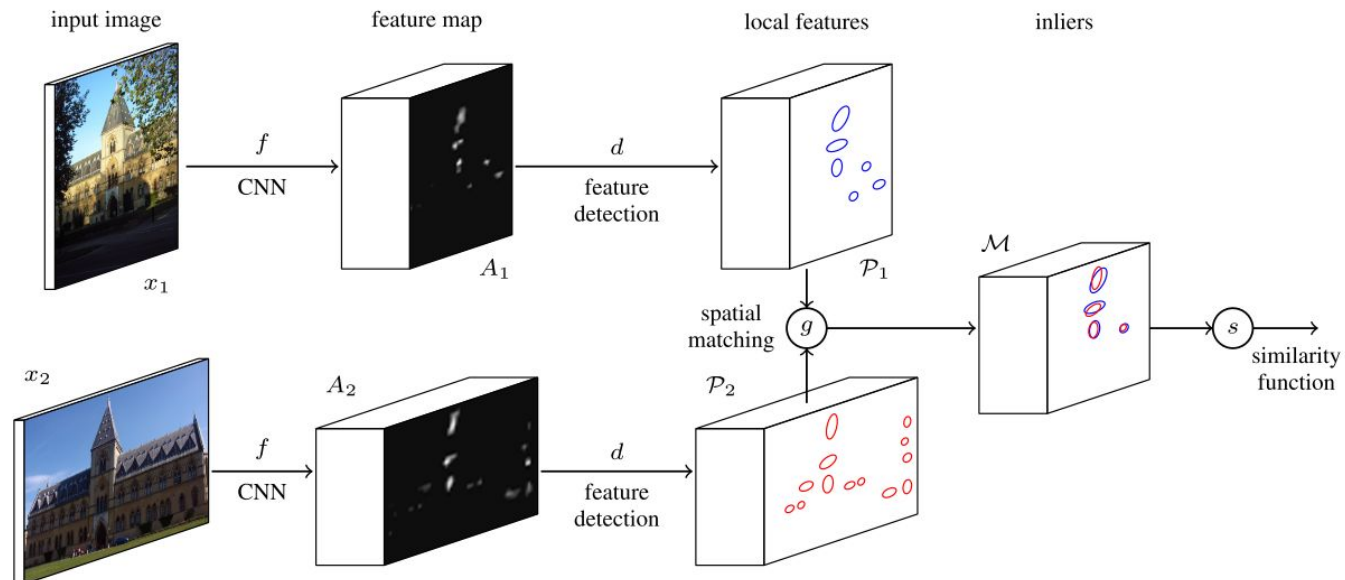
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Related Work: Fitting Ellipses

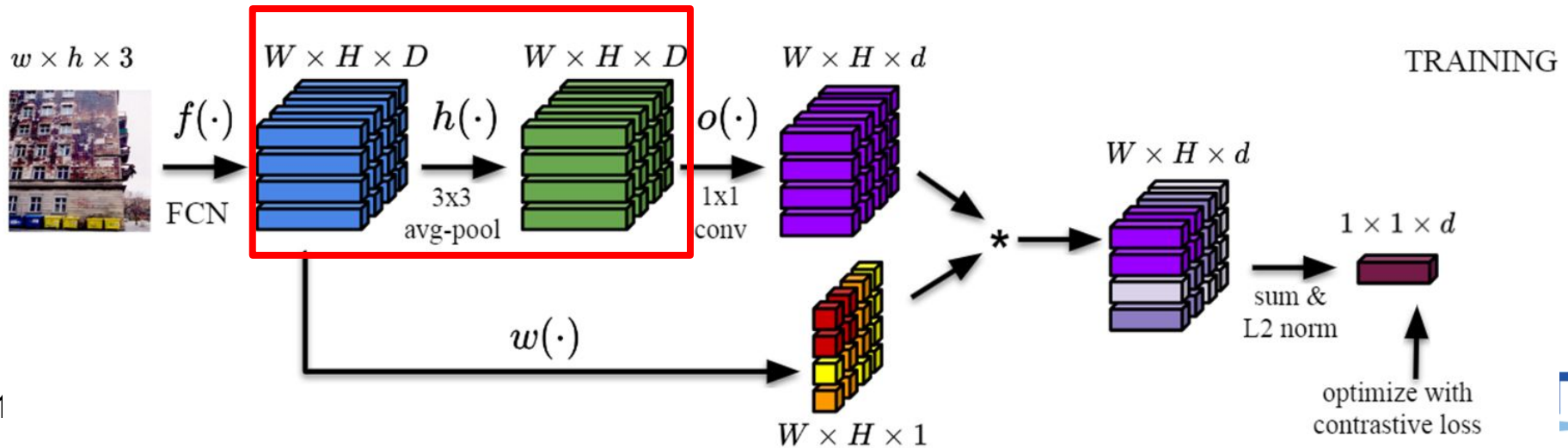
- Simeoni et al. represent a set of local feature as ellipse for matching
- Ellipses are aggregated as global descriptor for matching or used for re-ranking, but doesn't directly use them for retrieval



Related Work: Local Smoothing

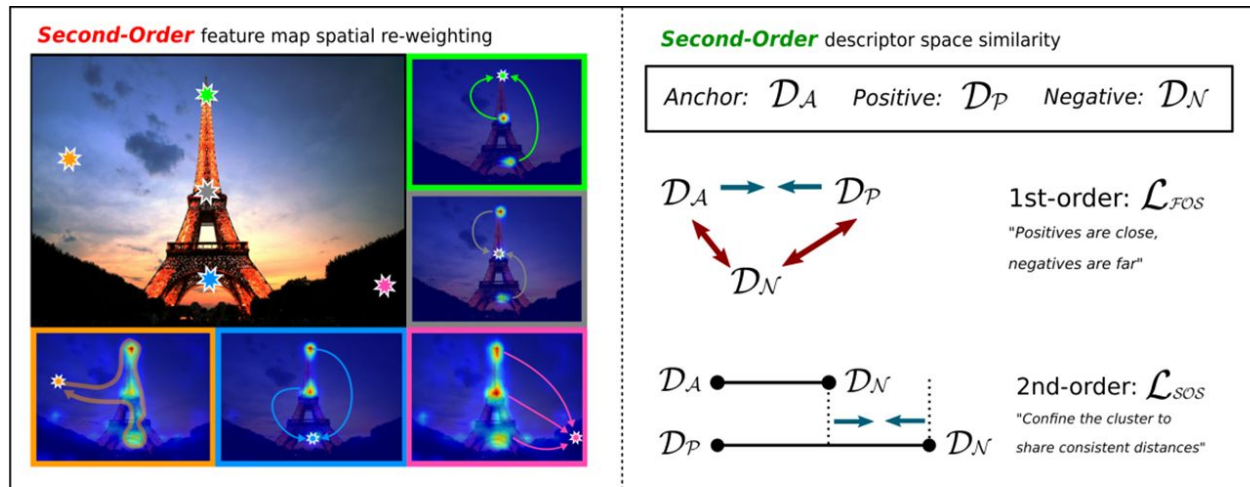
- Tolias et al. apply spatial avg. pooling to diffuse sparse local features to neighbors
- **Limitation:**
 - Unwanted smoothing may happened, reducing the importance of local descriptor

Method	Loss	Validation		ROxford		Tiny-GLD ₂		
		mAP	$ \mathcal{C}_X $	mAP	$ \mathcal{C}_X $	μ AP	$ \mathcal{C}_X $	
5: R18 _{$\hat{h}\hat{o}\hat{w}$}	CE	75.5 \pm 1.3	391.0 \pm 8.2	63.7 \pm 1.6	442.3 \pm 9.7	64.0 \pm 1.8	427.5 \pm 15.6	w/o smoothing
8: R18 _{$\hat{h}\hat{o}\hat{w}$}	CE	77.0 \pm 0.9	279.6 \pm 5.6	65.4 \pm 0.5	320.6 \pm 6.8	68.6 \pm 1.8	300.9 \pm 11.4	w/ smoothing



Related Works - SOLAR

- Re-weighting local descriptor
- Confine clusters with second-order loss
- **Limitation:**
 - Attention map requires expensive computational cost

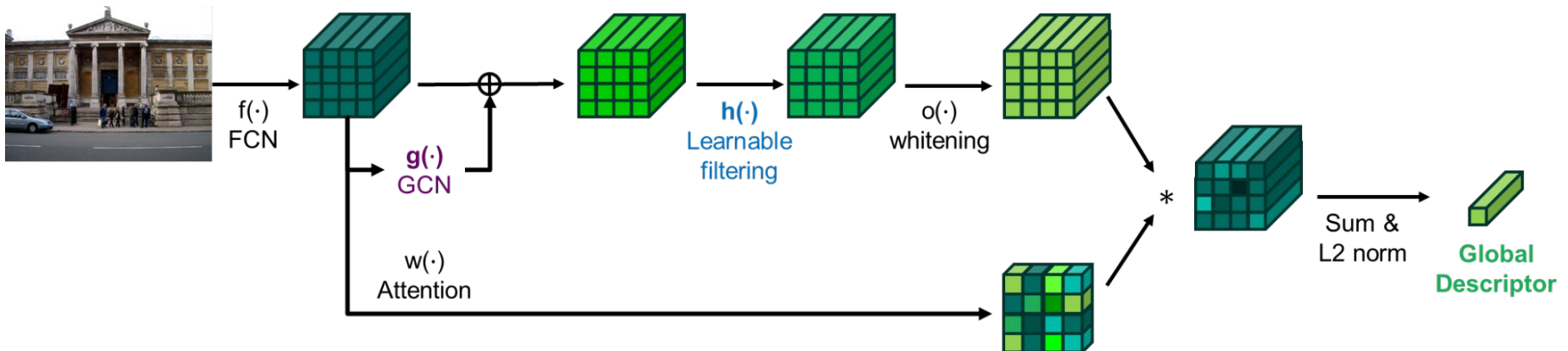
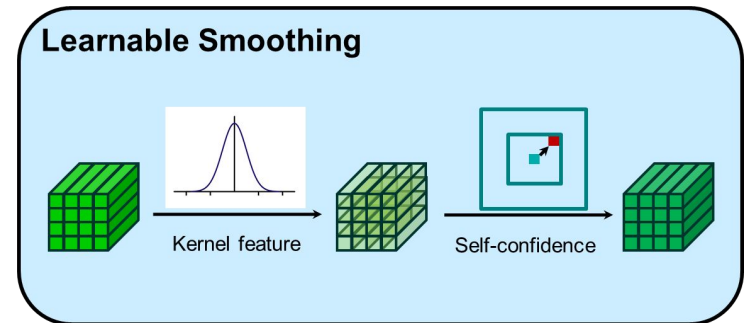
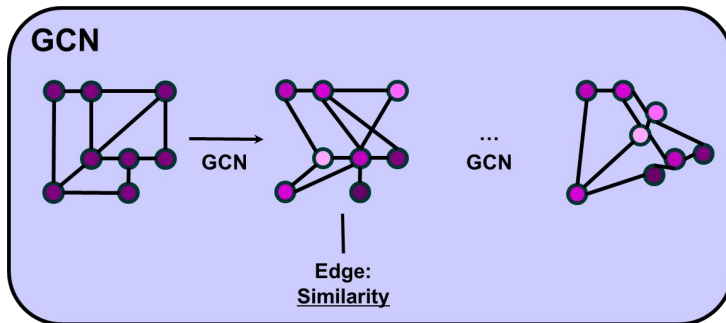


Re-weighting local descriptors
prior to GeM

Distribute global descriptors
in descriptor space

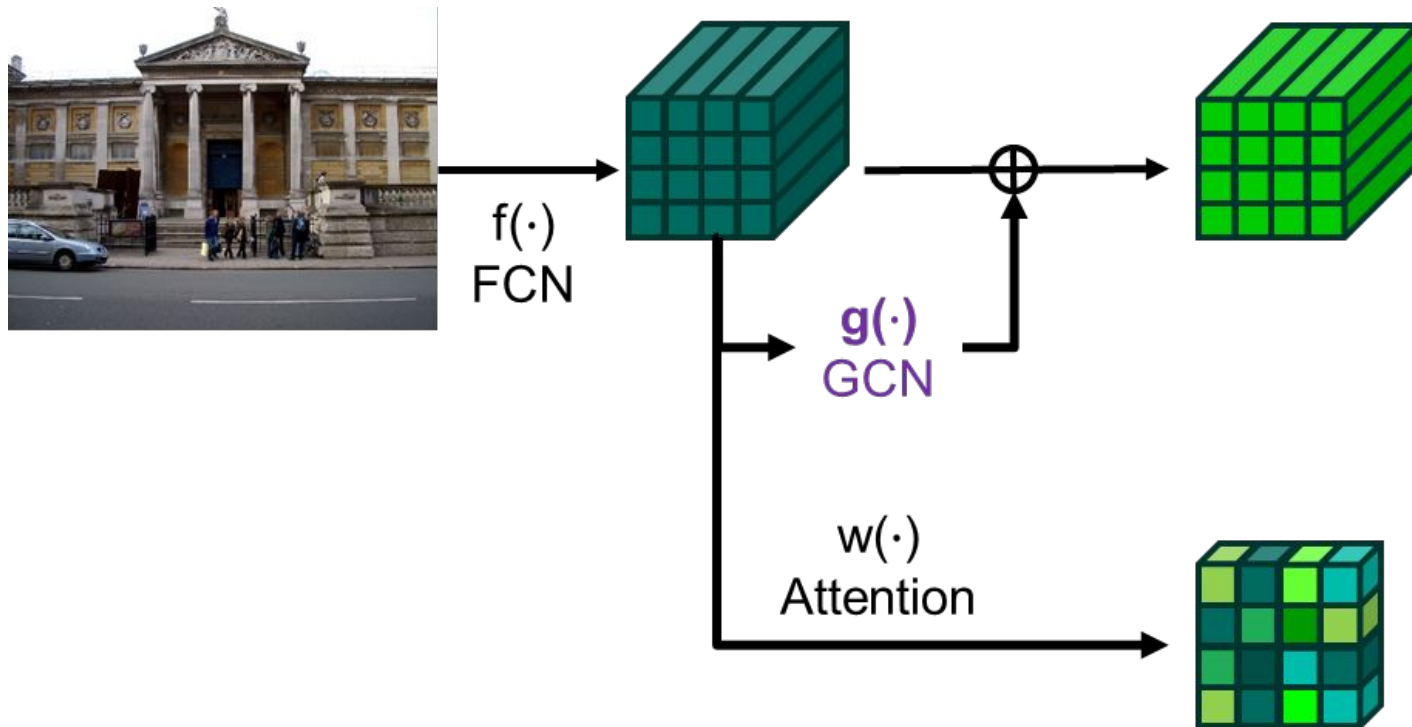
Overall Method

- Semantic context re-weighting : Semantic context
- Learnable smoothing : Local spatial context



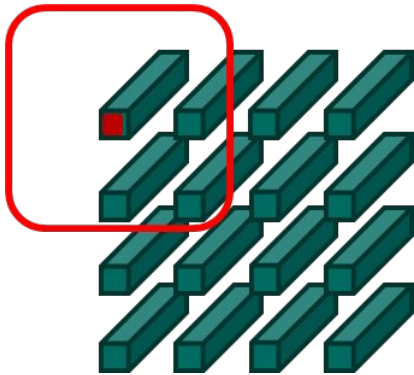
Method 1. Graph-based Refinement

- Learnable smoothing focus on limited region of locality
- Re-weight local features via GCN
- GCN captures semantic information

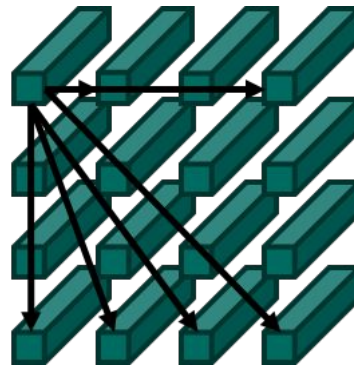


Method 1.1 Graph Structure

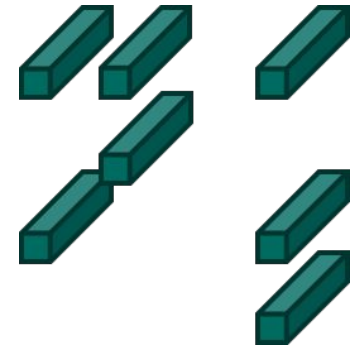
- Nodes are connected with edges (similarity)
- Each GCN propagates messages to next block
- Can consider global semantic context



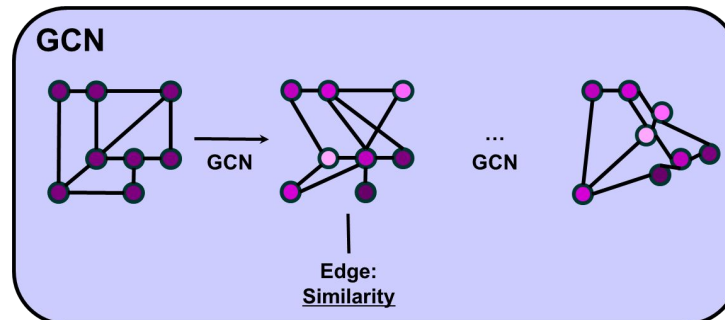
 Learnable smoothing



Calculate similarity for all nodes



Connected nodes can consider global context



Attention Map Visualization

HOW



Ours



Attention Map Visualization

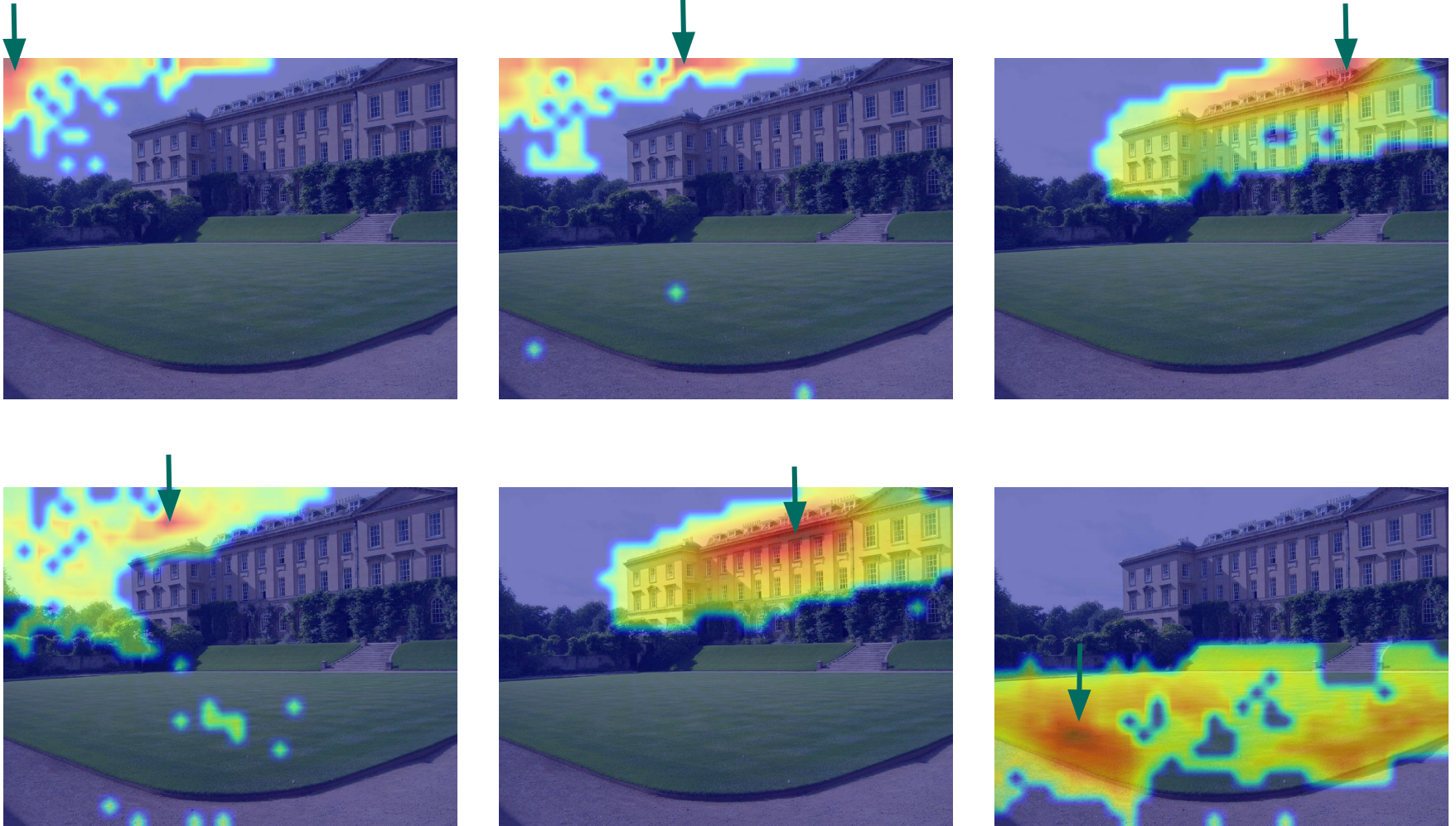
HOW



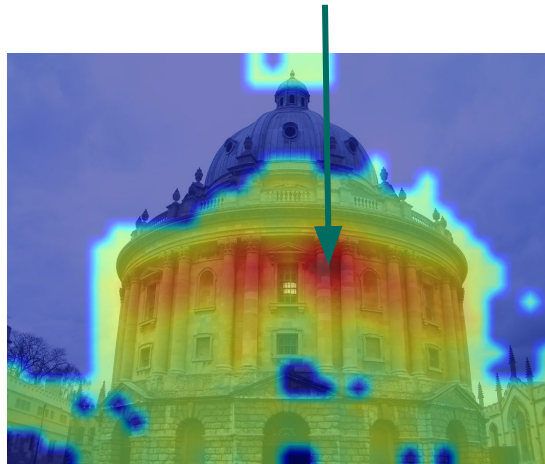
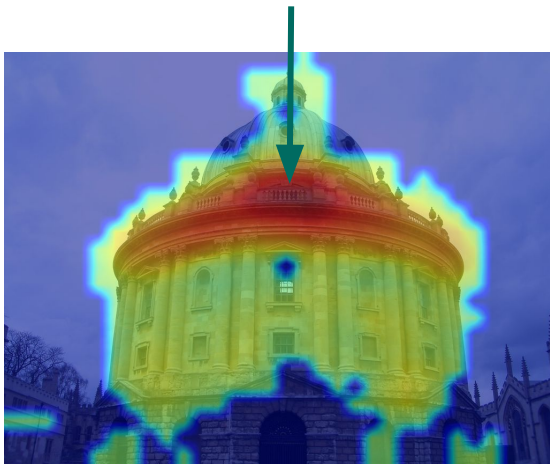
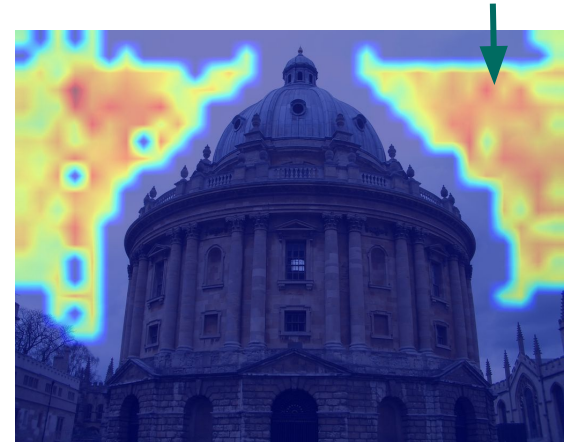
Ours



Edge connection map

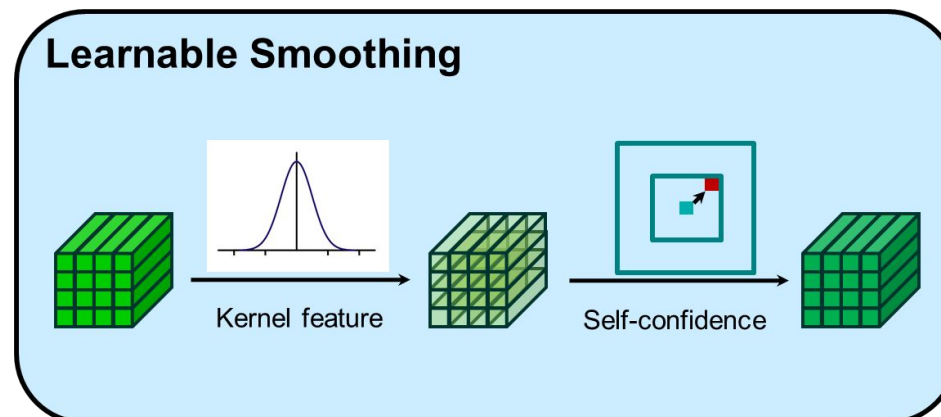
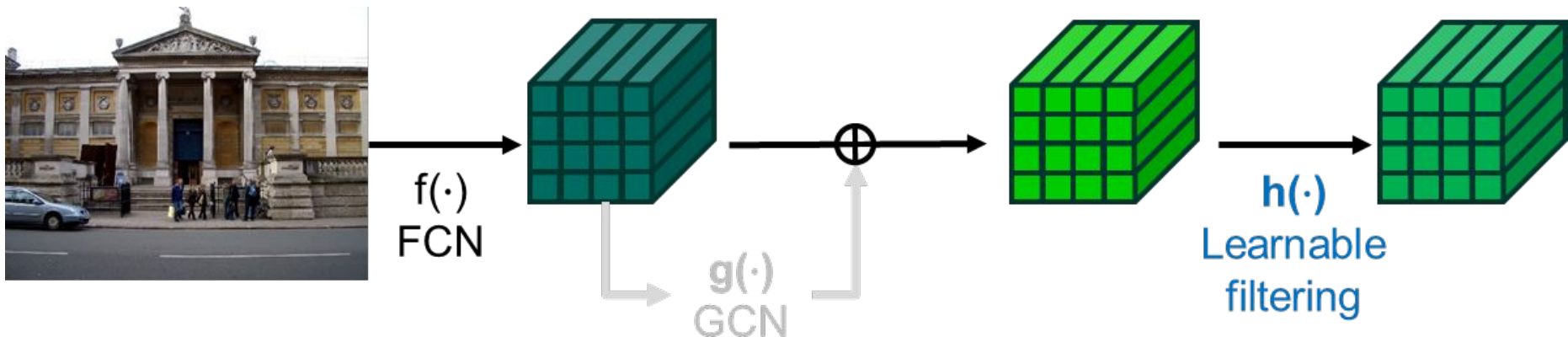


Edge connection map



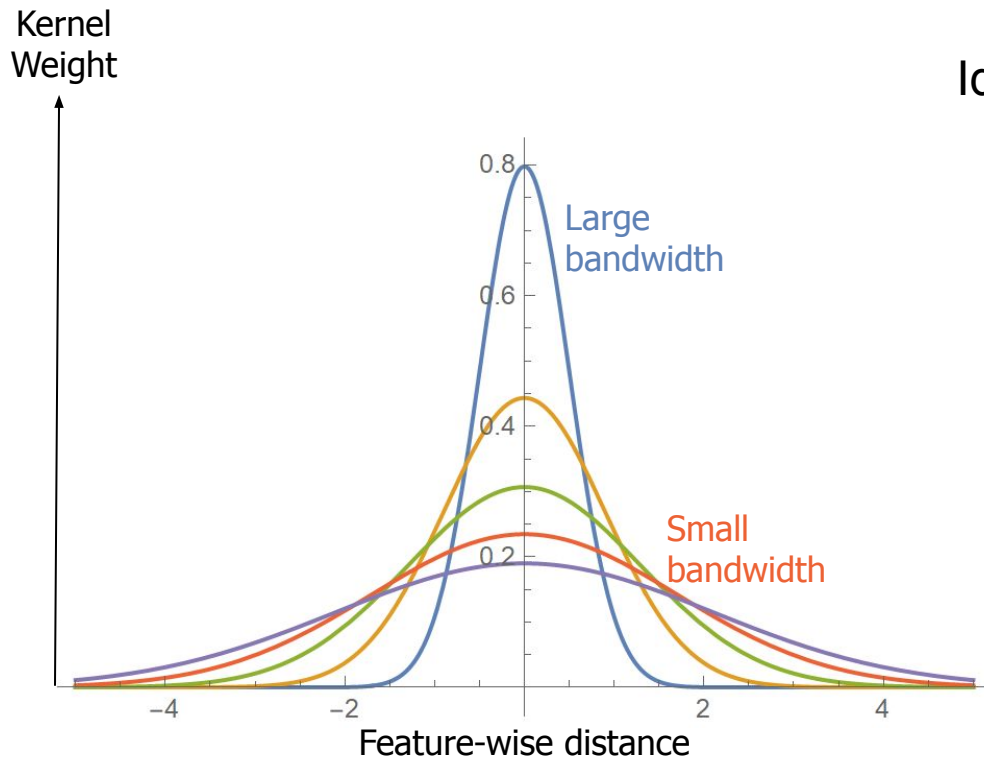
Method 2. Learnable Smoothing

- Gather neighbor local feature based on learned weight
- Learnable kernel bandwidth (receptive field) for smoothing
- Estimate self-confidence to reduce burstiness

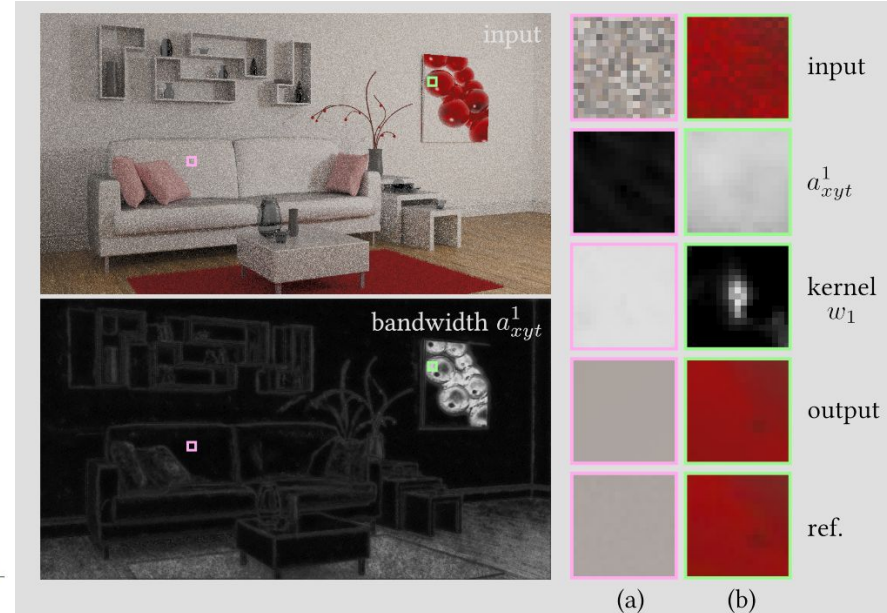


Method 2.1 Learnable Bandwidth

- Gaussian kernel with learnable bandwidth
 - Larger bandwidth (Narrow): Spatially non-correlated info.
 - Smaller bandwidth (Wide): Spatially correlated info.

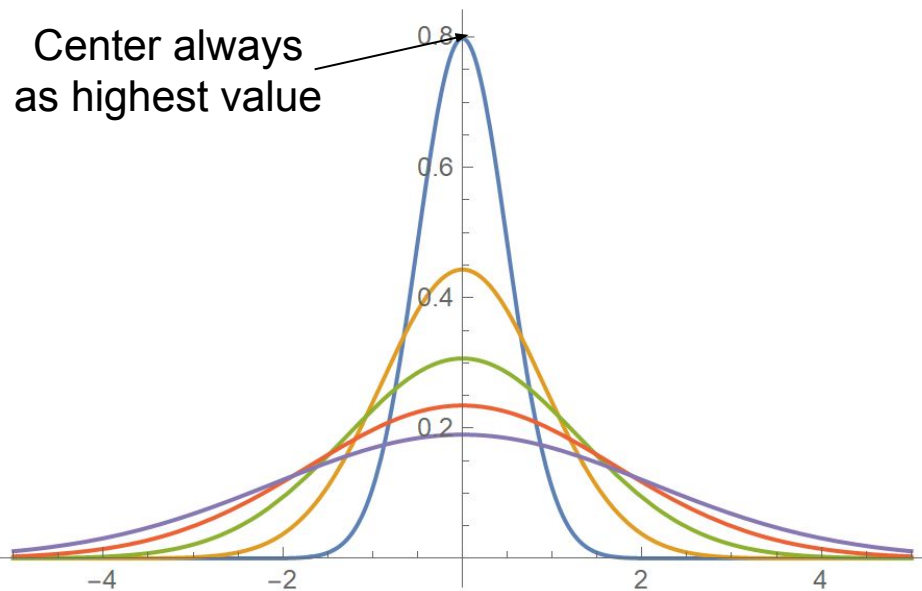


Identify high-frequency region for denoising

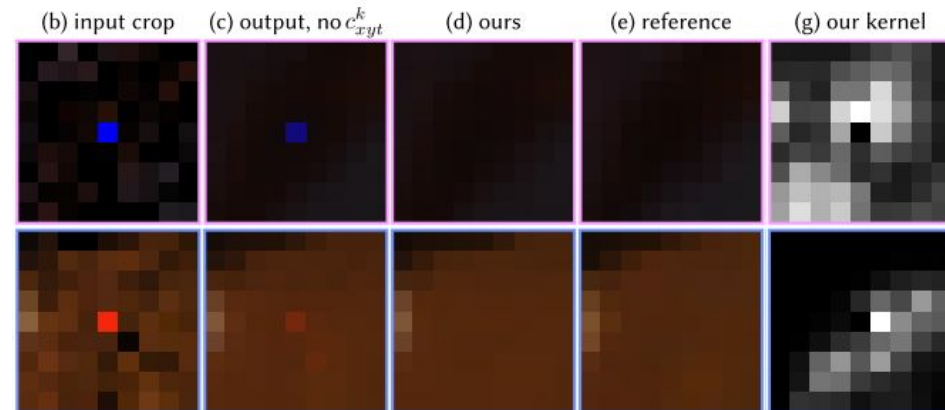


Method 2.2 Learnable Self-Confidence

- Gaussian filter always show highest value on center
- Center (itself) may contain irrelevant feature
- Self-confidence allows to reject itself when it is not relevant for image retrieval



Helps to reject when the center pixel is an outlier for denoising



Kernel Visualization

- Refines local features to highlight all important region

Local feature attention



Average Pooling



Learnable Pooling



Kernel Visualization

- Refines local features to highlight all important region

Local feature attention



Average Pooling



Learnable Pooling



Kernel Visualization

- Refines local features to highlight all important region

Local feature attention



Average Pooling



Learnable Pooling



Kernel Visualization

- Self-confidence highlights less highlighted region
- Large bandwidth for edge details

Local feature attention



Self-confidence



Bandwidth

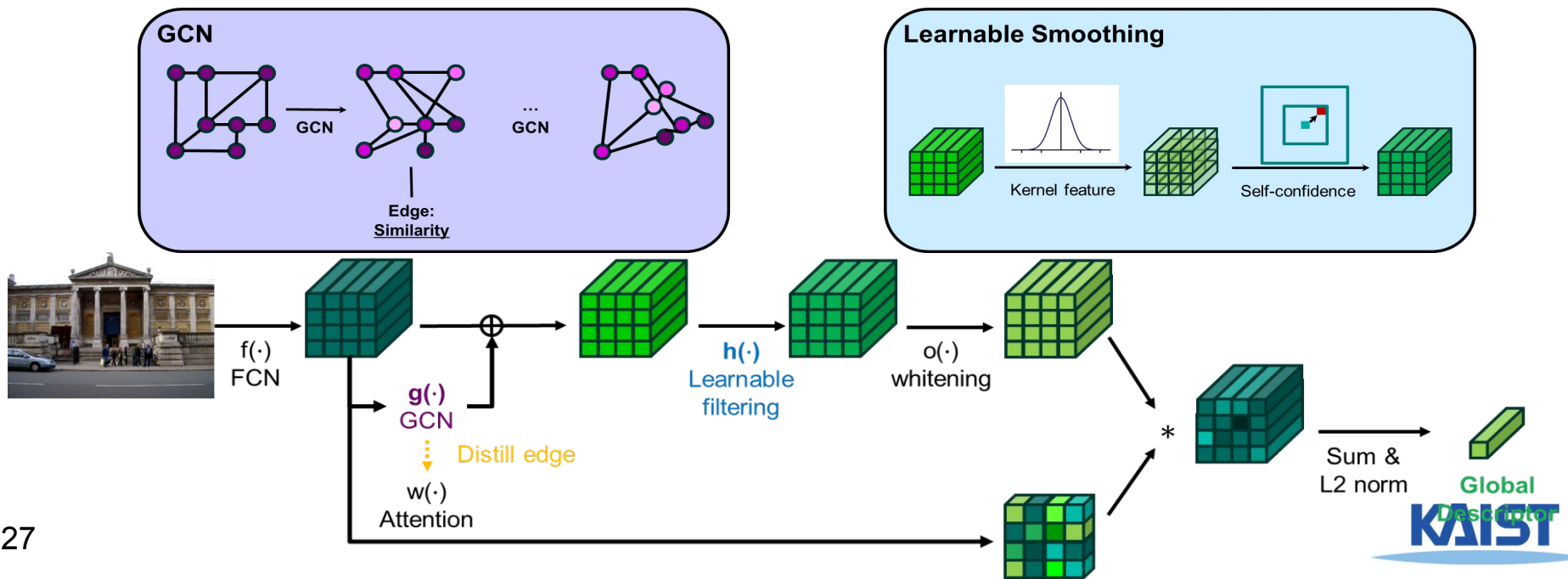


Learnable Pooling



Experiment Details

- Use ImageNet pretrained ResNet-18 as backbone
- Finetune backbone with small learning rate, while training GCN and smoothing with large learning rate on SfM dataset
 - o 1:10 ratio



Numerical Results

- Slight increase in performance
- Could not fully merge the advantages of both methods at the end

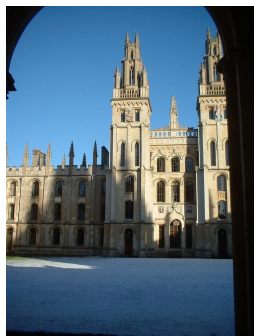
Method	SFM_val	R_Oxford		R_Paris	
		M	H	M	H
HOW	85.2	74.2	52.1	80.0	59.3
+ Learnable filter	85.1	75.0	51.8	80.9	61.3
+ GCN	86.1	75.3	53.3	80.7	60.9
+ Both	84.9	75.3	53.2	80.5	60.2

Visual Results

HOW



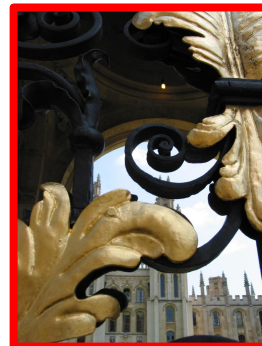
Rank #1



Rank #2



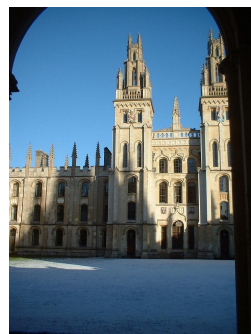
Rank #3



Rank #4



Ours



Visual Results

HOW



Rank #1



Rank #2



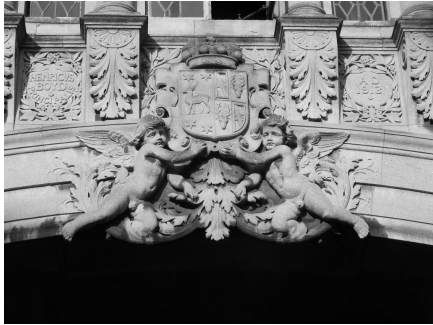
Rank #6



Rank #7

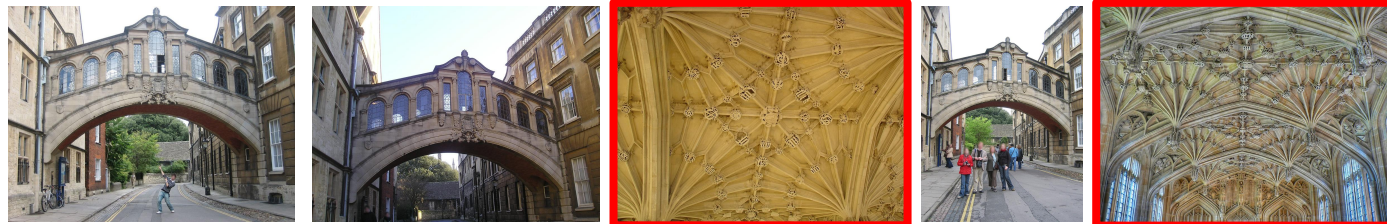
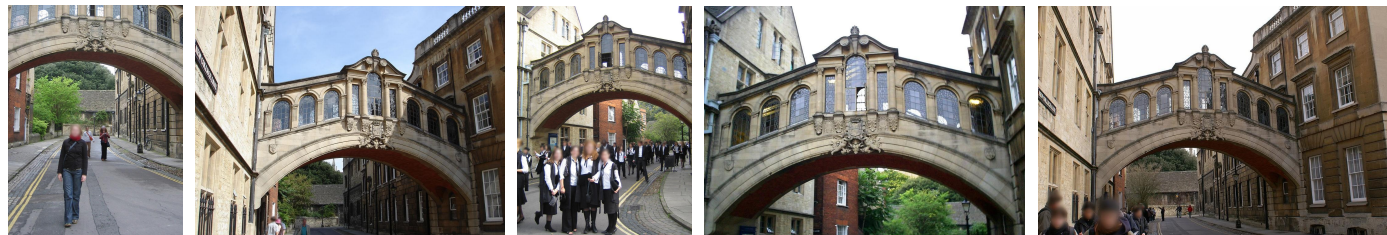


Ours

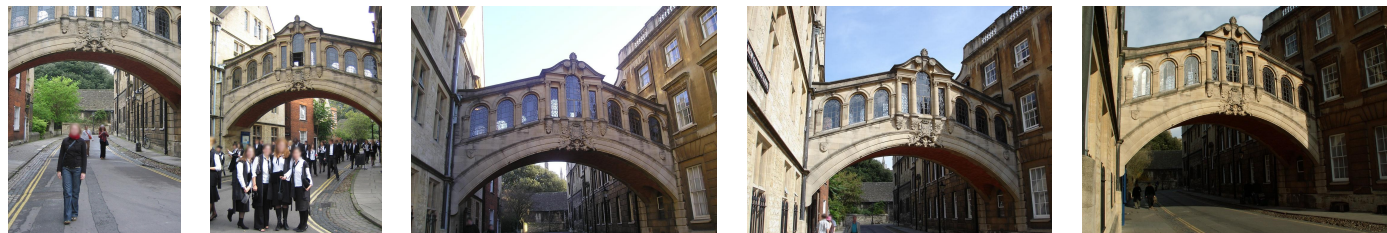


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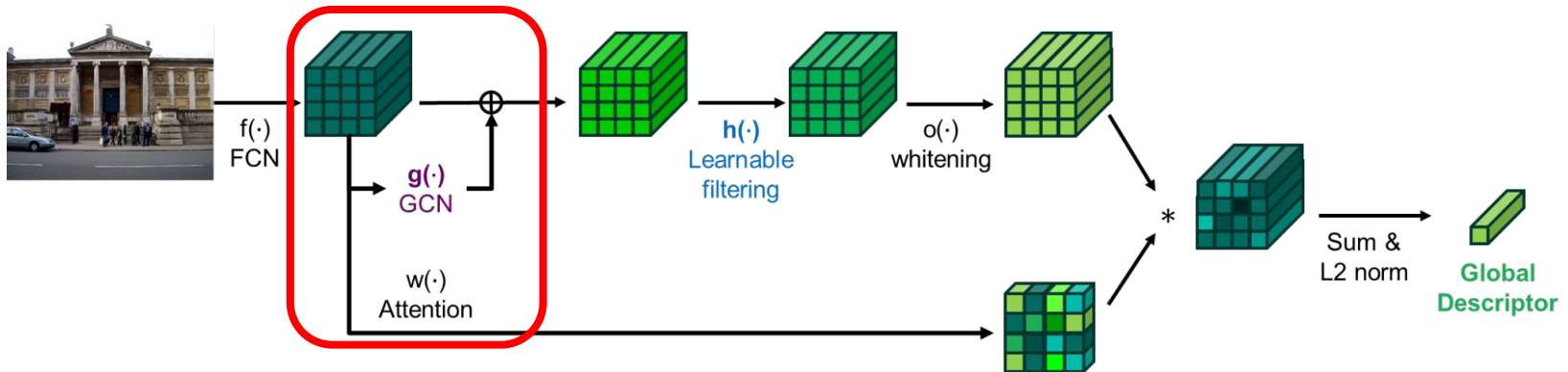


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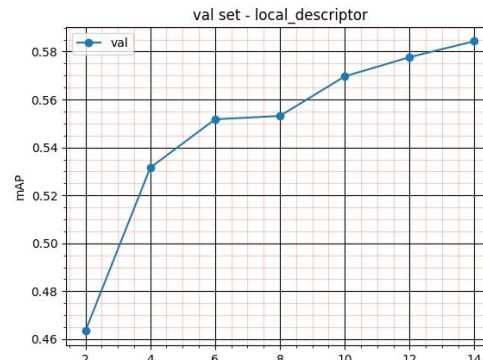


Limitation

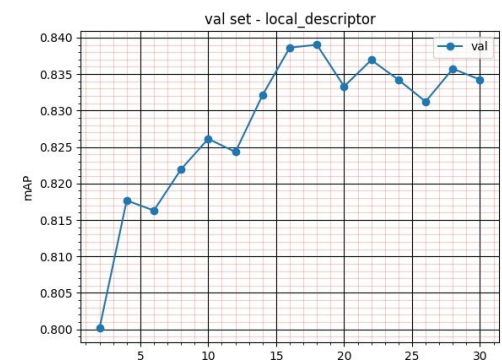
- Hard to compare with general method (i.e., self attention)
 - o Could not converge the training with self attention
- Could not apply our work on various backbones



GCN could be generalized to self-attention, but find it hard to optimize



Val. plot w/ self attention



Val. plot w/ GCN

Summary

- Provide local context to the local descriptors for better matching
 - Graph-based Refinement
 - Learnable Smoothing
- Found substantial increase in performance for retrieval
- Shown that our method could be also used for better localization

<Contributions>

KB: Local descriptor matching baseline + Learnable Filter

JH: Graph-base Refinement + Localization + Visualizations

Appx. Kernel Size

- Smaller kernel gives better performance
- Extensive smoothing on local features may harm the performance

Filter size	SFM_val	R_Oxford		R_Paris	
		M	H	M	H
3	85.1	75.0	51.8	80.9	61.3
5	83.9	74.0	51.0	79.8	59.0
7	84.0	73.4	50.9	80.0	59.1
