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# Subdivision Meshes in GPU

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The KAIST logo consists of the word "KAIST" in a bold, blue, sans-serif font. Below the text is a light blue, horizontal oval shape that serves as a shadow or base for the letters.

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- **Introduction**
- **Background**
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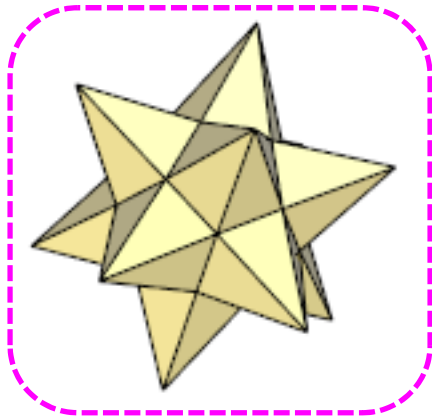
# Introduction

- **The subdivision meshes are developed for representing the characters and objects having smooth shape for the animations and games**
- **Subdivision meshes in the movies**
  - **Geri's Game (Pixar 1997)**
  - **A Bug's Life (Pixar 1998)**
  - **Meet The Robinsons (Disney 2007)**

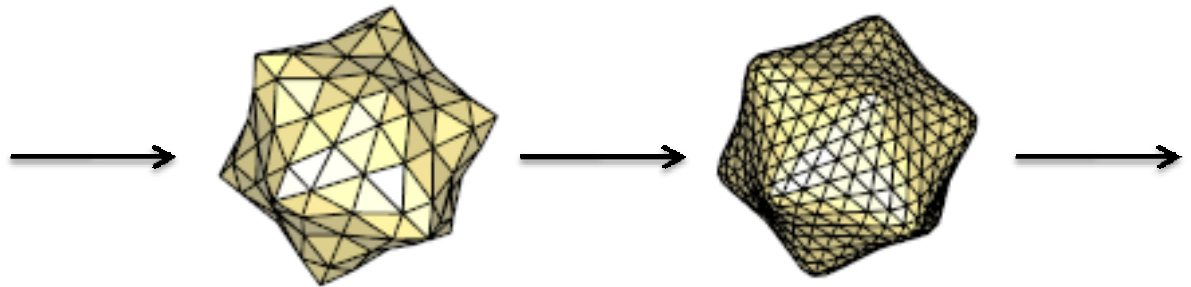


# Subdivision Meshes (1)

- **Recursively refine a polygonal mesh**



Original control mesh

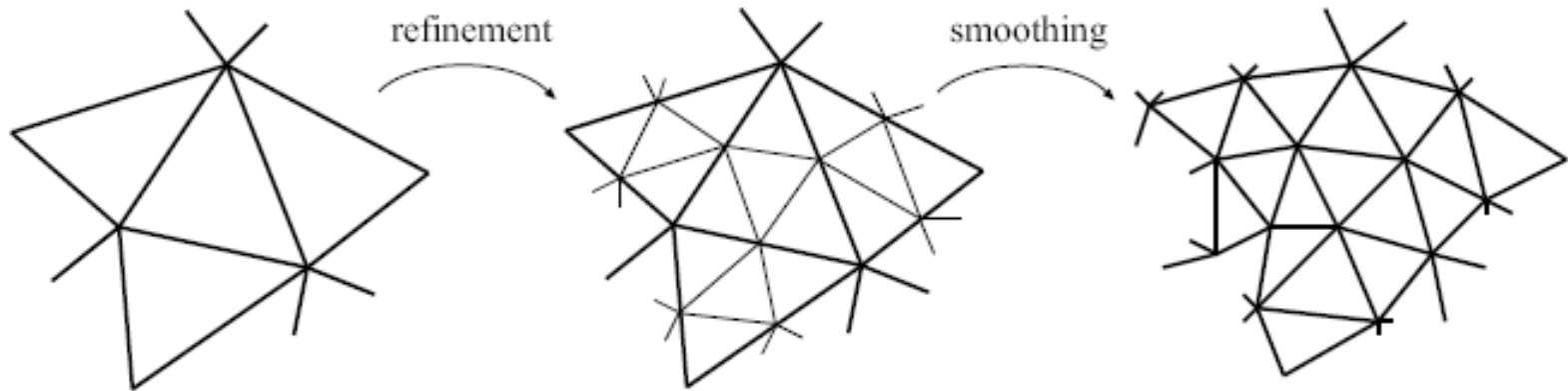


Smoother surface  
by recursive processing

- **Number of iteration determines Level-Of-Detail (LOD)**
- **Provide infinite LOD**

# Subdivision Meshes (2)

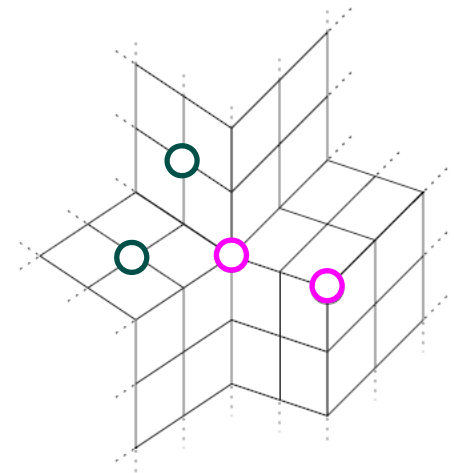
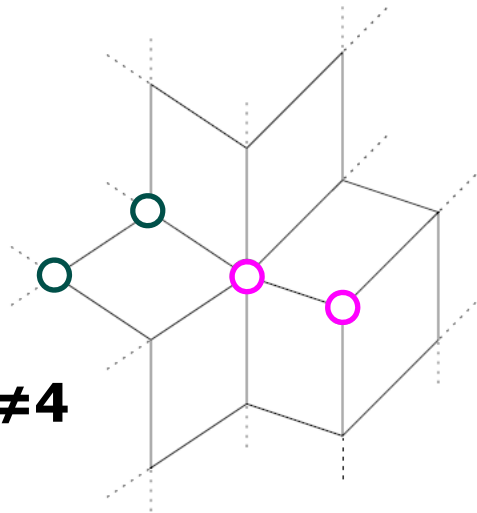
- **Two phase process**
  - **Refinement phase: creates new vertices and reconnects to create new triangles**
  - **Smoothing phase: computes new positions for the vertices**



# Advantage of Subdivision (1)

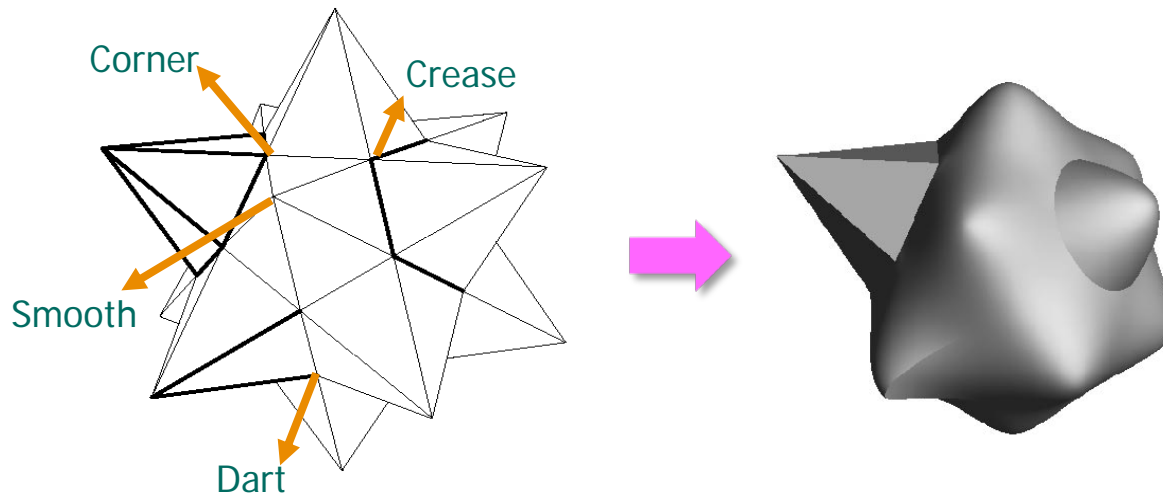
- **Efficiency**
  - Modeling is easy
- **Arbitrary topology**
  - Classic spline approaches have great difficulty with control meshes of arbitrary topology.

**Standard valence : 4**  
(regular point ○ )  
**Extraordinary valence :  $\neq 4$**   
(irregular point ○ )



# Advantage of Subdivision (2)

- Piecewise smooth subdivision [*Hoppe '94*]
- Support more detail surfaces

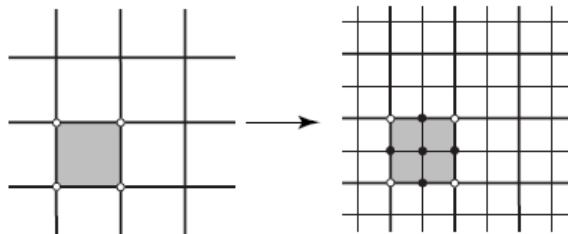


smooth ( $s=0$ ), dart ( $s=1$ ), crease ( $s=2$ ), and corner ( $s>2$ )

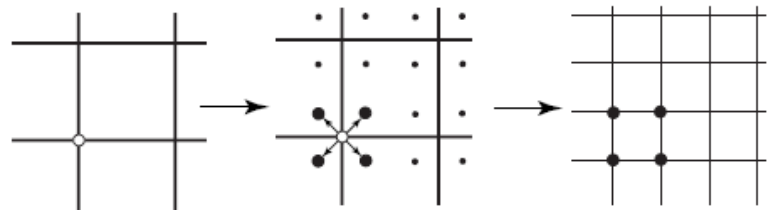
- **Complex geometry**
- **Internal refinement of a mesh reduces consumption of bandwidth (bus, memory, and etc.)**

# Subdivision Scheme Classification

	Face Split		Vertex Split
	Triangular meshes	Quad. meshes	Doo-Sabin ( $C^1$ )
Approximating	Loop ( $C^2$ )	<b>Catmull-Clark (<math>C^2</math>)</b>	Midedge ( $C^1$ )
Interpolating	Modified Butterfly ( $C^1$ )	Kobbelt ( $C^1$ )	Biquartic( $C^4$ )



Face Split



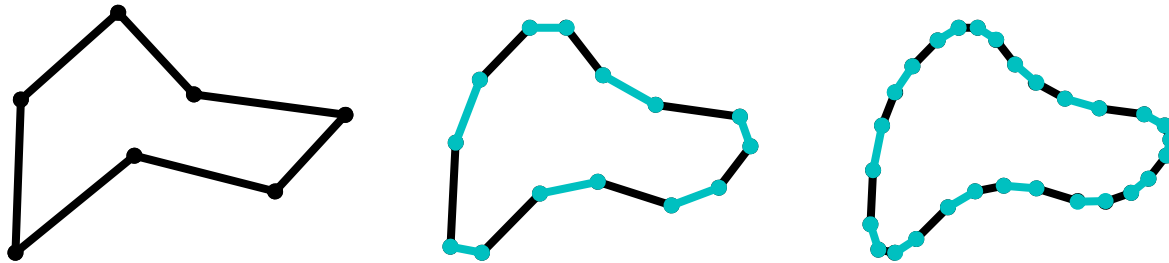
Vertex Split



# Subdivision Schemes

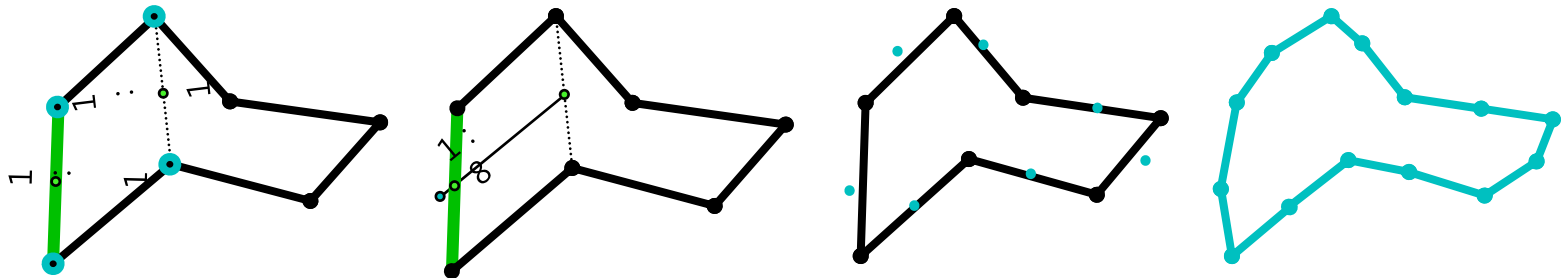
- *Approximating*

- The limit curve does not lie on the vertices of the initial polygon because the vertices are discarded (or updated).



- *Interpolating*

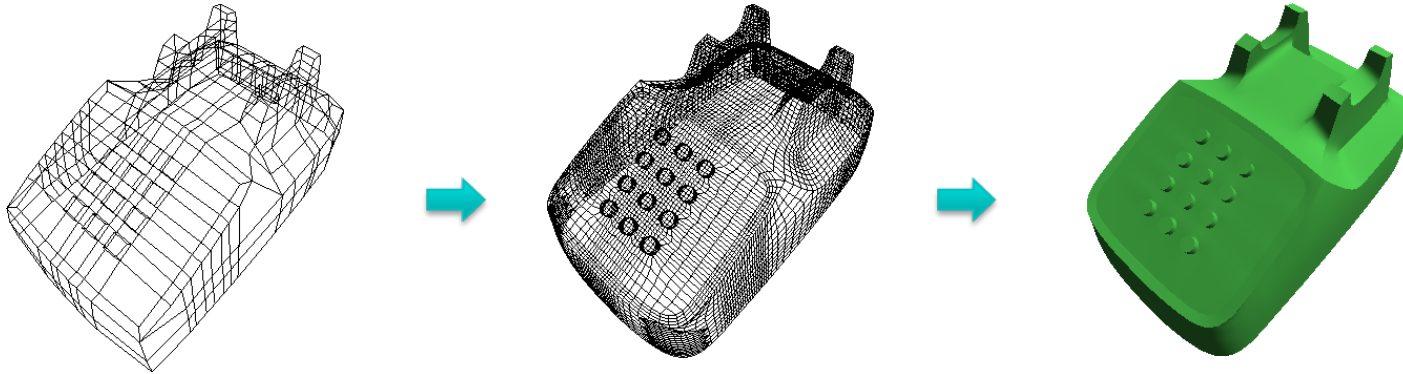
- Keep all the points from the previous subdivision step



# Catmull-Clark Subdivision (1)

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- Good results for most kinds of control mesh

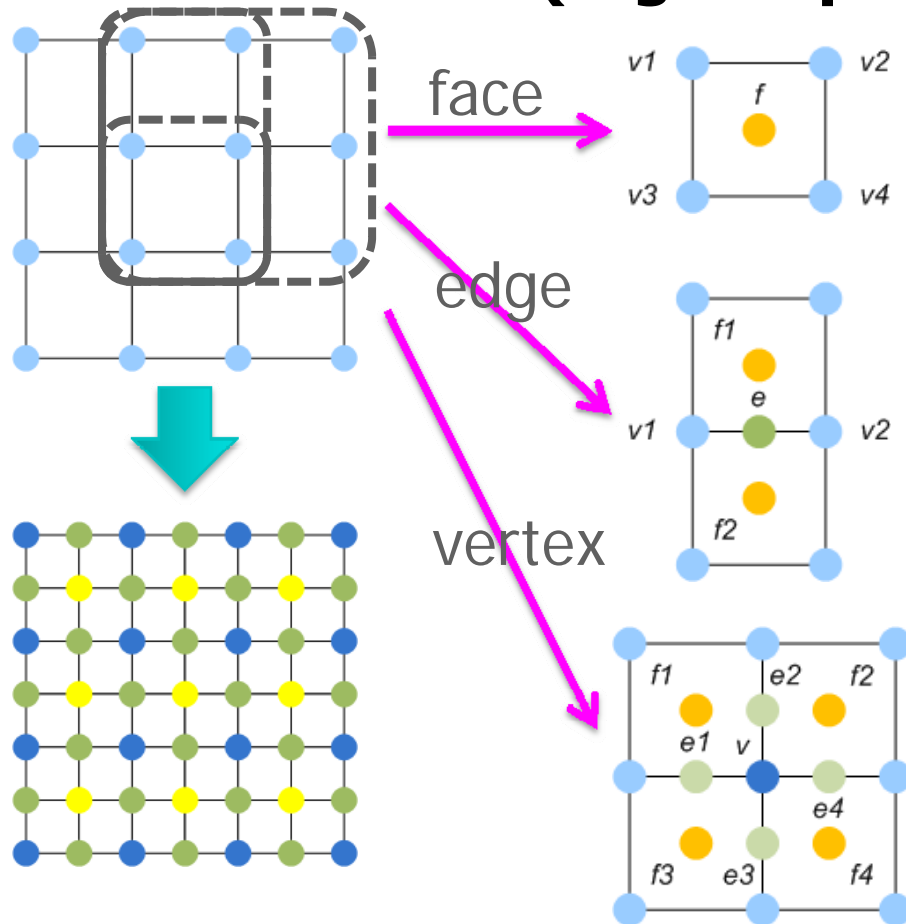


*[Bolz '02]*

- Most of modeling tools use Catmull-Clark subdivision
  - Autodesk 3ds Max
  - Autodesk Maya
  - PIXAR RenderMan

# Catmull-Clark Subdivision (2)

- Subdivision rules (regular point)



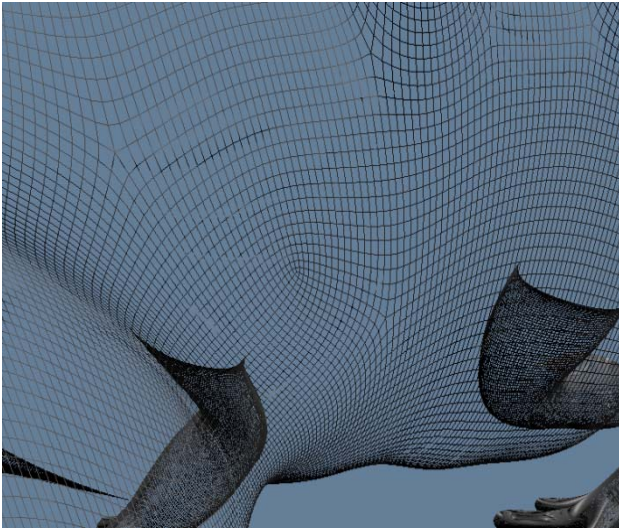
$$f = \frac{v1 + v2 + v3 + v4}{4}$$

$$e = \frac{v1 + v2 + f1 + f2}{4}$$

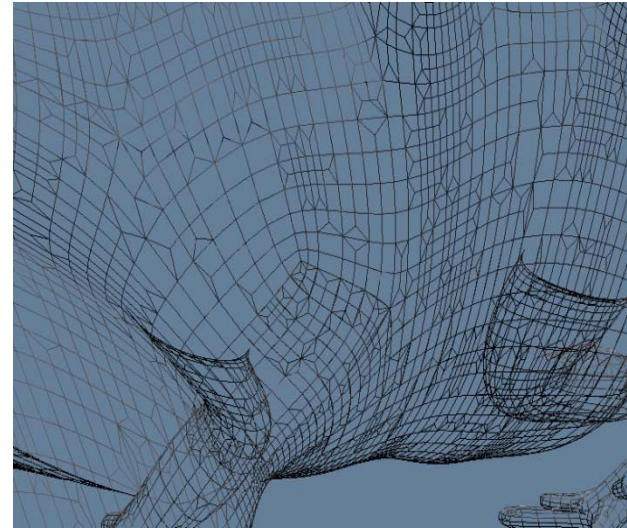
$$v = \frac{\text{prev. } v + 2 \times \text{avg. } e' + \text{avg. } f}{4}$$

# Adaptive Subdivision

- **No generation of unnecessary vertices**
- **Improve performance with almost same quality**



Uniform subdivision  
(Level = 4)

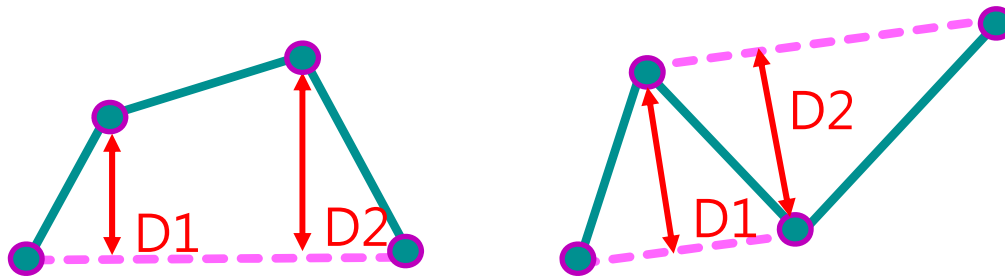


Adaptive subdivision (Max.  
level = 4)

# LOD Selection

- **Curvature**

- Flatness test
- LOD is calculated from  $\text{Max}(D1, D2)$

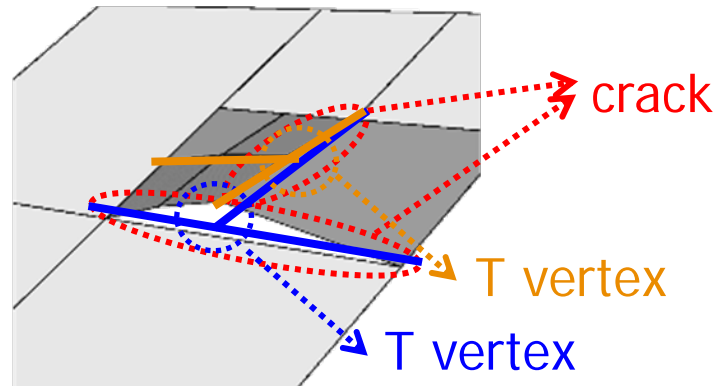


- **Projected length (edge) or area (face)**



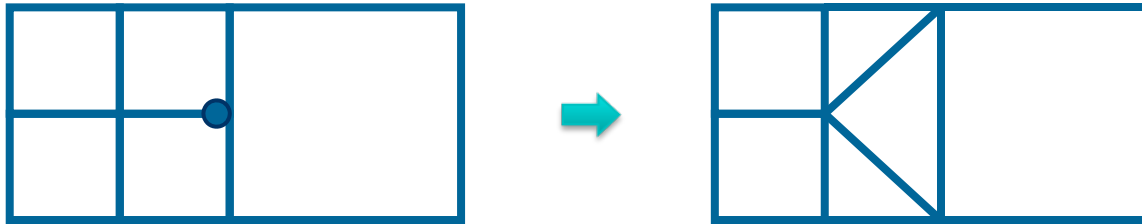
# Crack

- Adaptive subdivision has possibility to create cracks
- Cracks are created if each patch has different LOD

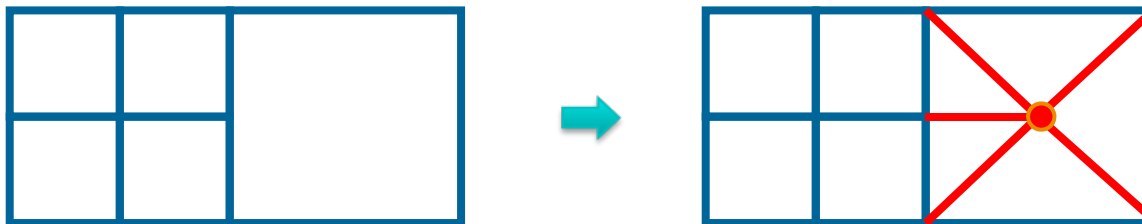


# Crack Elimination

- Remove vertex



- Generate a face point & edge points



# Why GPU?

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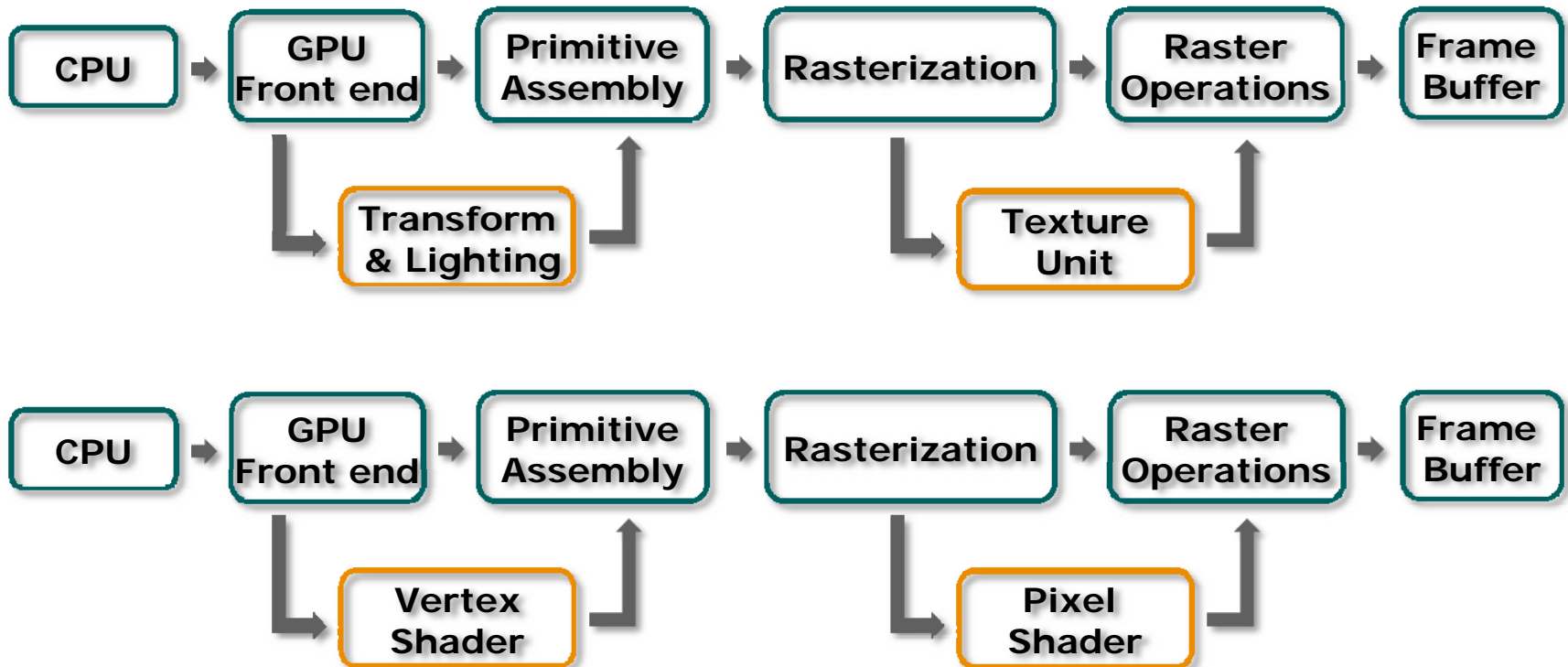
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- **GPU has programmability enough for general computation**
  - **A programmable shader replaces a traditional fixed function unit as core processor**
- **GPU is faster than CPU for parallel processing of independent workloads**
  - **Integrated more arithmetic units (an arithmetic unit is simpler than that of CPU)**
  - **Enhanced matrix calculation (support dot product and multiply-and-add instructions)**
  - **Control path is optimized for non-data hazard workloads (efficient and simple)**



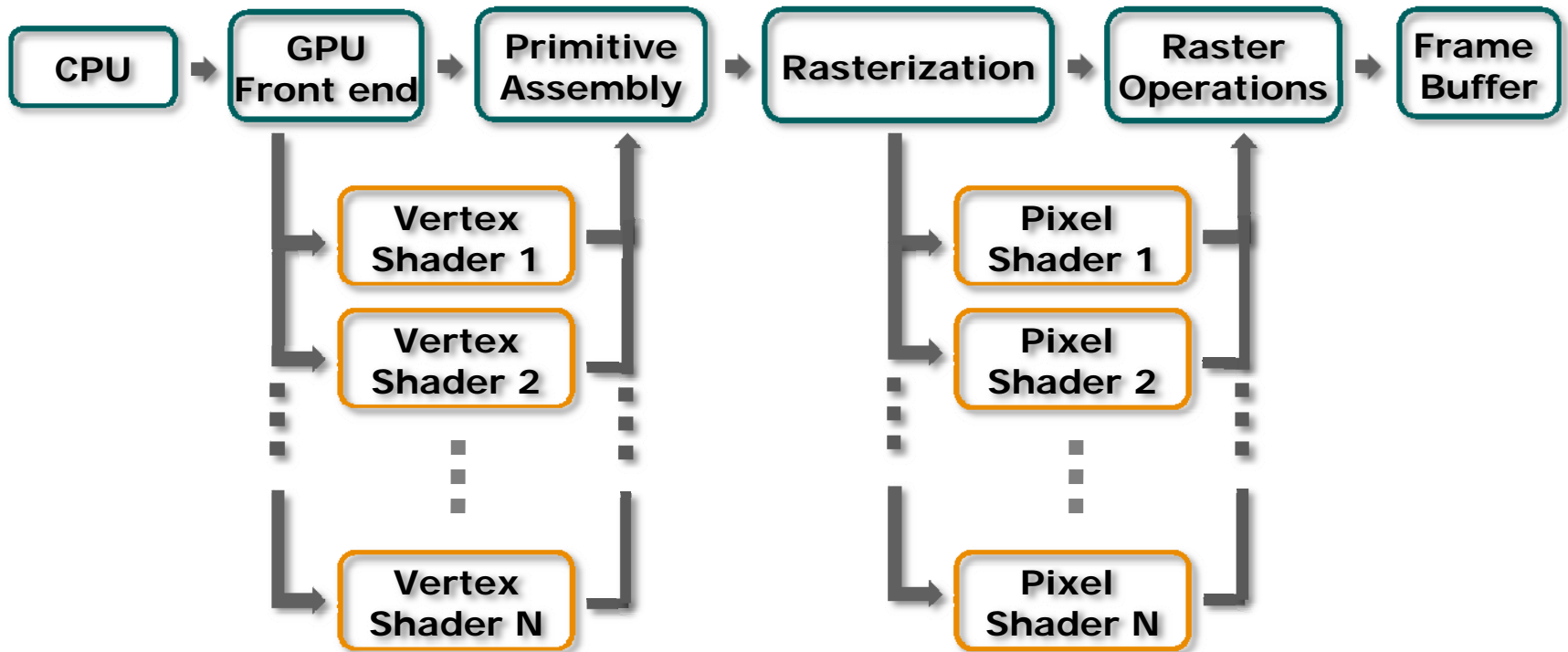
# Programmable Shader of GPU

- Traditional fixed-function unit → Programmable shader



# Parallel Processing

- Handle independent workloads



# GPU Limitations

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- **Program length limitation**
  - **Maximum code length is limited.**
  - **Shader program switching overhead is very heavy.**
  - **But this problem can be solved at the next version of shader model.**
- **Weak data feedback**
  - **Optimized for unidirectional data flow (input-to-framebuffer)**
  - **Some extensions support data feed back features but limited.**

# Previous Works (1)

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- **Bolz, J. and Schröder, P. 2002. Rapid Evaluation of Catmull-Clark Subdivision Surfaces**
  - **CPU implementation using SIMD instruction**
  - **Pre-computation of tables for all depth and valences**
    - **Poor flexibility and large tables**
  - **Adaptive subdivision**
  - **Final subdivided vertices send to GPU**
    - **No gain of CPU-to-GPU data transfer bandwidth**

# Previous Works (2)

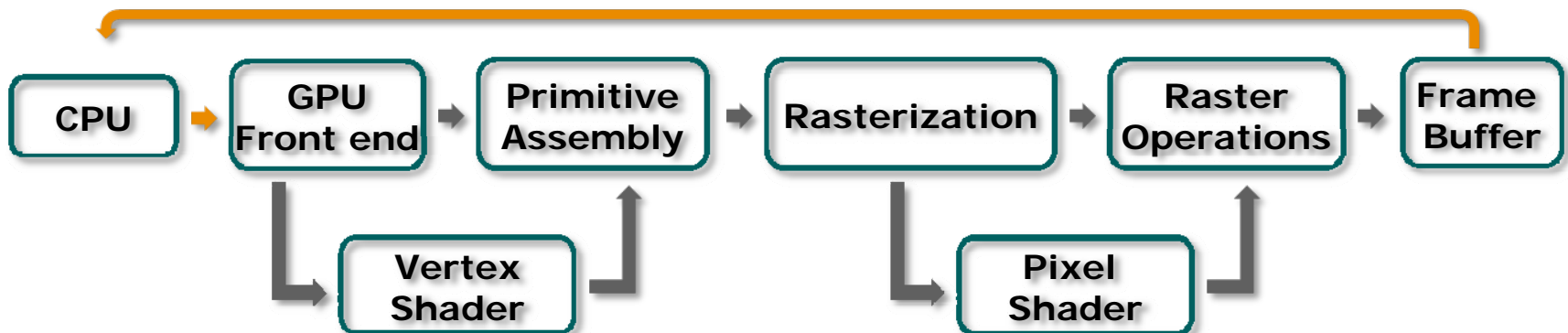
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- **Bolz, J. and Schröder, P. 2002. Evaluation of subdivision surfaces on programmable graphics hardware**
  - **GPU implementation version of their previous work**
  - **Final subdivided vertices send to CPU and re-send to GPU for rendering**
    - **The data should be sent to vertex shader input for rendering, but there was no path from frame buffer or texture memory to vertex shader in that time**

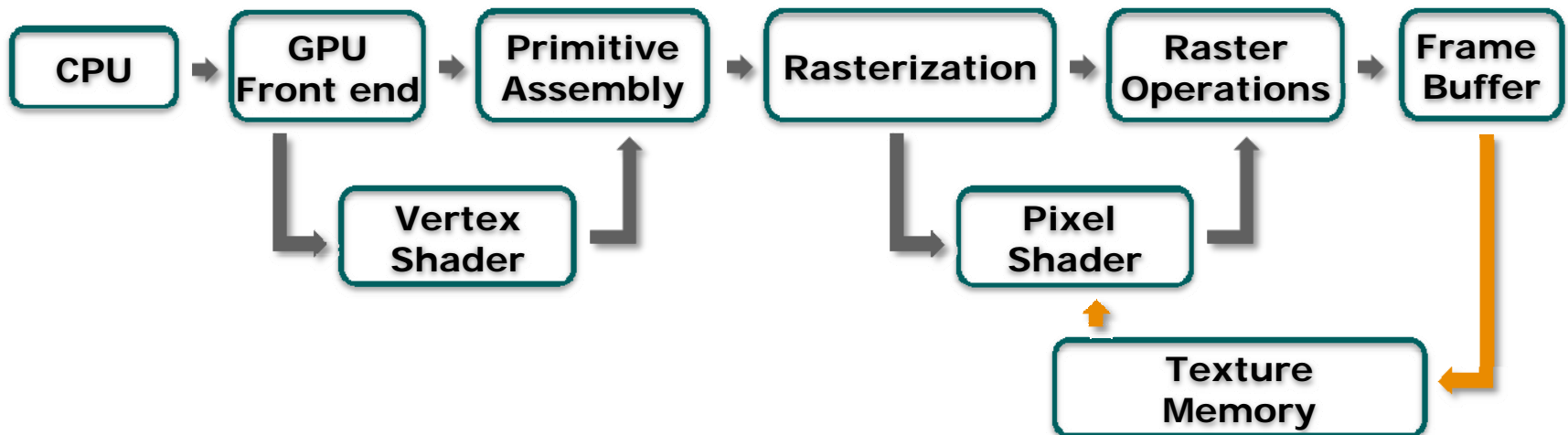
# Previous Works (3)

- **Bunel. 2005. Adaptive Tessellation of Subdivision Surfaces with Displacement Mapping (GPU Gem2)**
  - Pixel shader program on GPU for subdivision
  - Adaptive subdivision using flatness test at each level
  - CPU read the flatness test results from the video memory and decides which patches need further tessellation for adaptive subdivision



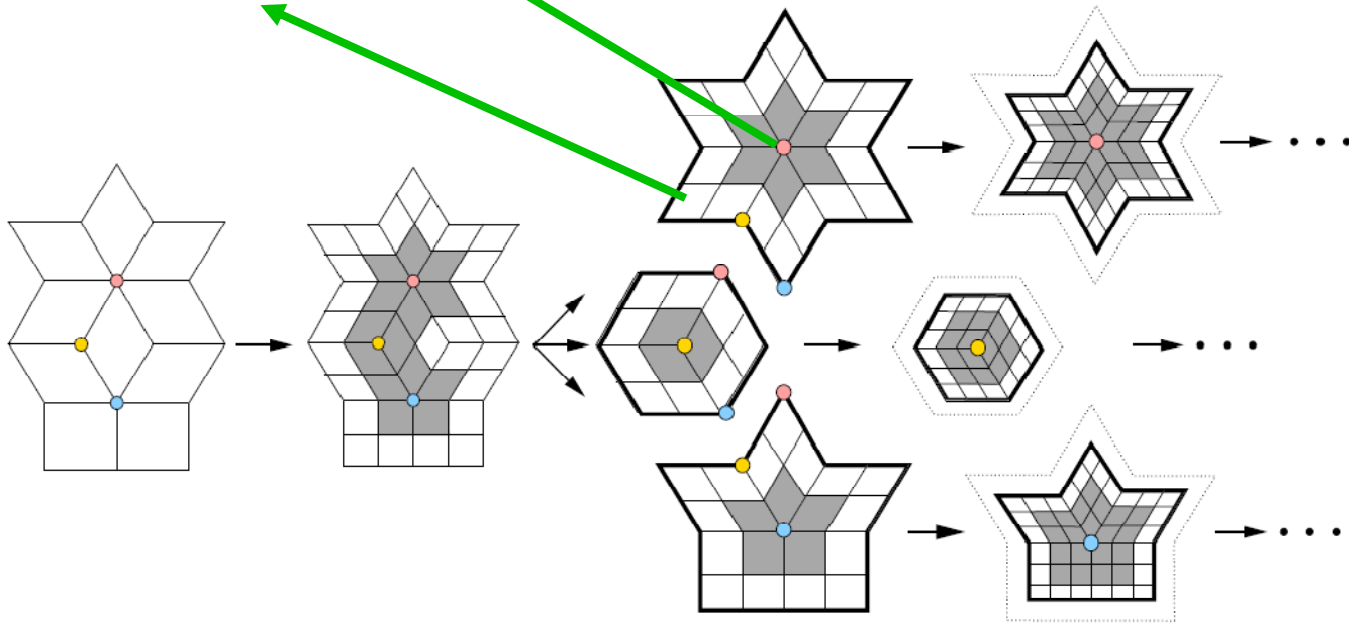
# Previous Works (3) – cont'd

- All patches are subdivided by only one level at every subdivision iteration
  - Good locality between a patch and its neighbors
  - Poor locality between a current patch and the same patch of the next iteration
- Use copy-to-texture for feedback of the intermediate data



# Previous Works (4)

- **Le-Jeng Shiue 2005. A Real-time GPU subdivision Kernel**
  - **Regular processing using fragment mesh**
    - **Irregular point is placed at center**
    - **1-ring regular point meshes are overlapped**





# Previous Works (4) – cont'd

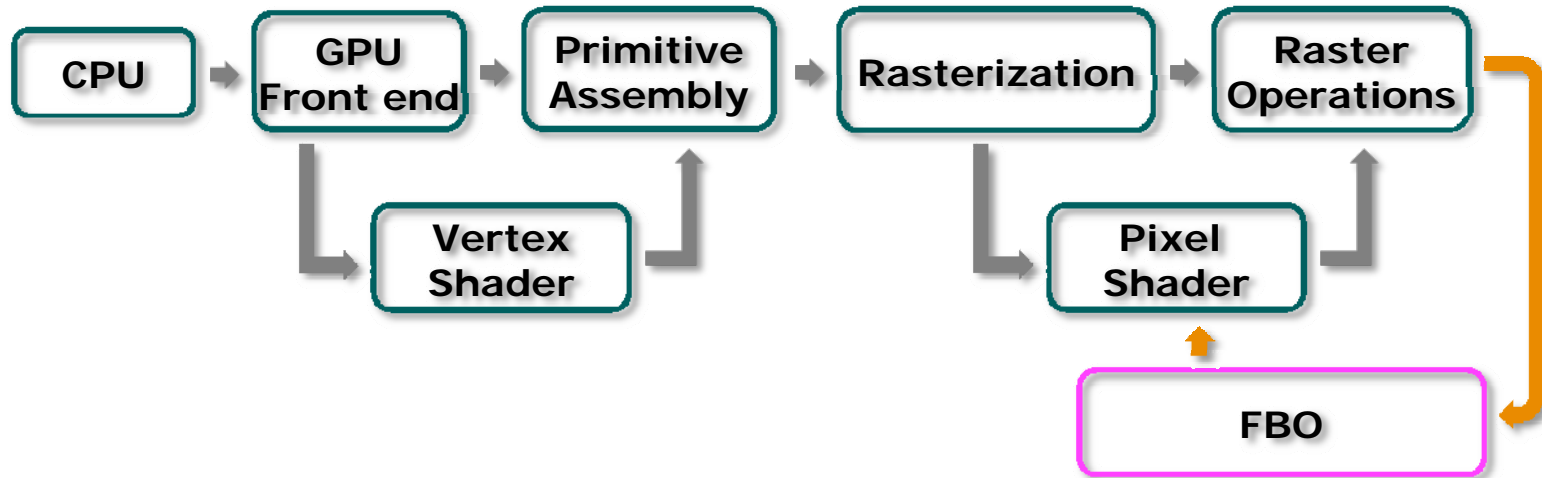
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- **Processing of irregular points causes inefficient memory access and shader context switching (regular point shader program and irregular point shader program)**
- **All fragment meshes have regular pattern**
  - **1-irregular point & regular points**
  - **Can be used of united shader program**
- **Few information about adaptive subdivision**

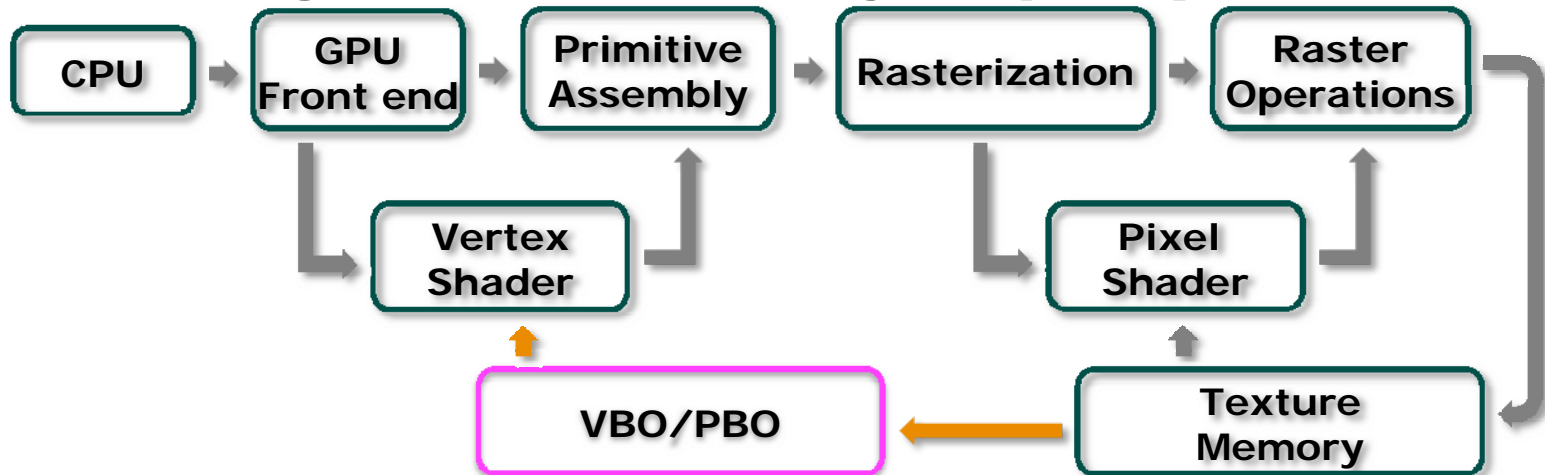
# Previous Works (5)

- **Minho Kim. 2005. Real-time Loop Subdivision on the GPU**
  - Exploration for many new memory access features in OpenGL API extension
    - Using frame buffer object (FBO)

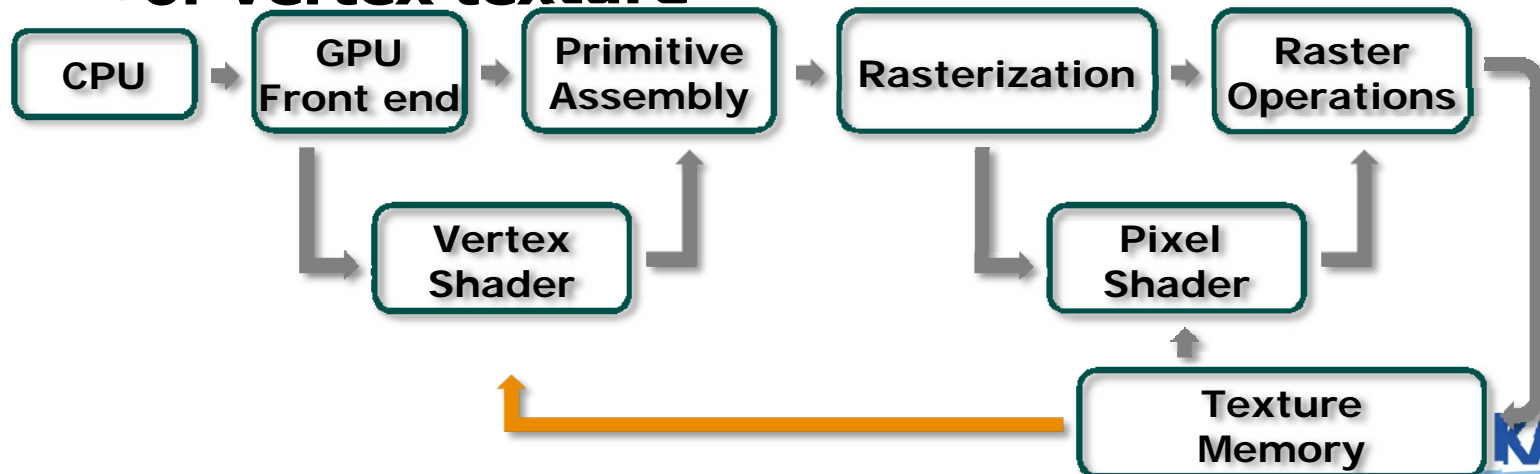


# Previous Works (5) – cont'd

## • Using vertex buffer object (VBO)



## • or vertex texture



# Problems

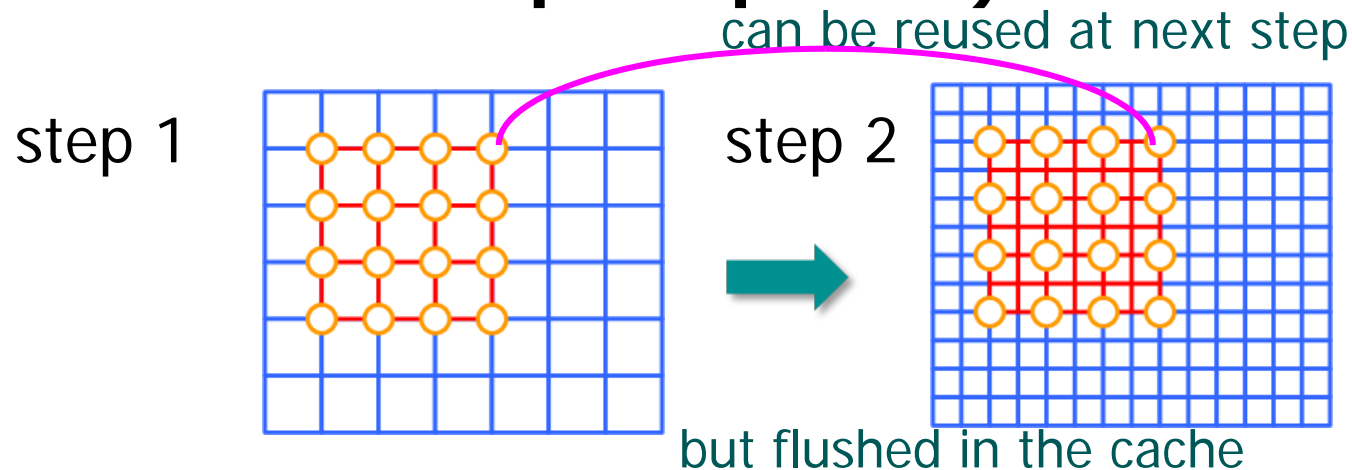
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- **Context switching is large overhead**
  - **FBO destination switching (frame buffer or texture memory)**
  - **Multiple shader program switching**
  - **CPU (host) should handle both context switching**
- **Neighbor mesh information is overlapped**
  - **Redundant information**

# Problems – cont'd

- **Missing temporal locality at each subdivision step**
  - **Flatness test at every subdivision steps**
    - **Crack should be eliminated at final subdivision step**
  - **Breadth first operation (Subdivision step 1 of patch 1 → subdivision step 1 of patch 2 → ... → subdivision step n of patch 1)**



# Question?

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# Thank You!